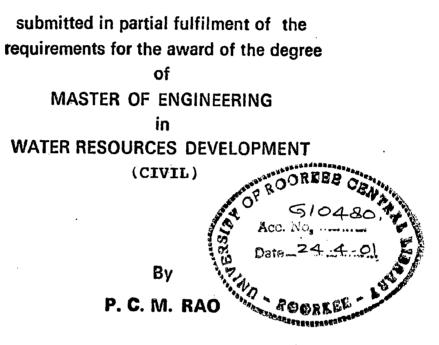
A MULTIPLE – INPUT SINGLE – OUTPUT MODEL FOR FLOW FORECASTING OF WARDHA RIVER

A DISSERTATION





WATER RESOURCES DEVELOPMENT TRAINING CENTRE UNIVERSITY OF ROORKEE ROORKEE-247 667 (INDIA) January, 2001 I hereby certify that the work which is being presented in the thesis entitled "A MULTIPLE-INPUT SINGLE-OUTPUT MODEL FOR FLOW FORECASTING OF WARDHA RIVER", in partial fulfilment of the requirements for the award of the Degree of Master of Engineering in Water Resources Development (Civil), submitted in the Water Resources Development Training Centre, University of Roorkee, Roorkee is an authentic record of my own work carried out during the period from July 16th 2000 to January 2001 under the supervision of Dr. U. C. Chaube, Professor, WRDTC and Dr. U. C. Kothyari, Assistant Professor, Civil Engineering Department, University of Roorkee, Roorkee.

The matter embodied in this thesis has not been submitted by me for the award of any other degree.

Date : January 14, 2001 Place : Roorkee

3. Ching Mon &

(P. C. M. RAO) Trainee Officer

This is to certify that the above statement made by the candidate is correct to the

best of our knowledge.

(**Dr. U. C. KOTHYARI**) Asstt. Professor Deptt. Of Civil Engineering University of Roorkee Roorkee –247667

M.C

(Dr. U. C. CHAUBE) Professor WRDTC University of Roorkee Roorkee -247667

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P. Char Month (PCM RAO)

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D	= Duration of rainfall
DRH	= Direct Runoff Hydrograph
e	= Difference between computed and observed discharge i.e. model residual
e _{OLS}	= Error in ordinary least squares estimate
E ²	= Efficiency of response function estimation i.e. model efficiency in percentage
F_d	= Initial variance of observed discharge
F_1	= Residual variance of observed discharge
G & D	= Gauge and discharge
Η	= Loss of rainfall
I	= Identity matrix
J	= Total number of sub-catchments
K	= Parameter to be chosen by user in smoothed least squares estimate.
ĥ.	= Ratio of Bayesian estimates
ln	= Natural logarithm
1	= Linear portion of memory length of catchment
mm	= Sum of response function ordinates in the model
m	= Total memory length of catchment
MSE	= Mean squares error
NLP	= Non-linear programming
n	= Non-linear portion of memory length of catchment
Р	= Rainfall
\mathbf{P}^{T}	= Transpose of matrix by rainfall values.
Q	= Observed runoff
$\hat{\mathcal{Q}}^{*}$	= Computed runoff.
\overline{Q}	= Mean of observed discharge
Q _{d;r}	= Observed discharge on date 'd' in year 'r'.
R	= Total rainfall for a period.

RGS = Rain gauge stations

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10	5 Italii gauge stations
RFO	D = Response function ordinate
S	= System
\mathbf{S}_{err}	= Standard error in response function ordinate
S^2	= Mean residual variance of observed discharge i.e. mean square error of
	computed and observed discharge.
t	= Time at which the runoff measured
U	= Response function ordinate
$\hat{\mathrm{U}}$	= Estimated response function ordinate
U_{m}	= Last ordinate of the response function
UH	= Unit hydrograph
V	= Resultant matrix from the product of $[P^{T}][P]$
V^{-1}	= Principal diagonal terms of matrix $[P^{T}P]^{-1}$
Х	= Identity matrix or Laplacian matrix in Bayesian method.
Ζ	= Multiplicative biasing matrix
Zo	= Objective function to be used in linear and non-linear programming model.
3	= Error term
ρ	= Prior density of response function ordinate i.e. Bayesian estimate.
ξ	= Positive constant i.e. Baysian estimate
ρ^2	= Noise variance
t-τ	= Time-lag since the input was applied.
δ_t	= Duration of time increment
τ	= Time in which the rainfall occur
Σ	= Summation.

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A large number of methods have been proposed in the past to predict the flood discharges resulting due to a storm event in a catchment. Unit Hydrograph method described by the response functions is the most popular and widely used practical tool, among the various available methods. But, one of the basic assumptions followed in this method is that the effective rainfall is occurring simultaneously over the whole catchment uniformly, which is seldom true, in case of large catchments. The spatial variation generally becomes more and more pronounced as the size of the catchment increases. The unit hydrograph hypothesis is particularly adequate in the range of floods experienced on small catchments (size smaller about 500 km²). For large catchments, it may even happen that some part of the catchment would not have any rain at all during the storm period. Also, these methods are derived on the concept of lumped linear response functions.

In the present thesis, a multiple-input single-output nonlinear model based on systems approach proposed by Muftuoglu (1984 & 1991) has been formulated for forecasting flows during flood events. The total rainfalls have been considered as the inputs and the total runoff as the output as against to the use of effective rainfall and direct runoff as input and output respectively used in conventional unit hydrograph method. The whole catchment area was divided into a number of sub-catchments which receive uniform rainfall, approximately. Rainfall of each sub-catchment was treated as separate lumped inputs to the model to incorporate spatial variations of rainfall as well as catchment heterogeneities. To derive composite response functions of the catchment, various data sets in calibration period were stacked together.

Rainfall and runoff data of the Wardha catchment upto Ghugus gauging site have been used for calibration and verification of the model. Results have been obtained for one, two and three rainfall inputs for the Wardha catchment with its discharge at Ghugus being the output. Both linear and nonlinear approaches have been studied. Multiple-input approach by linear and nonlinear methods was also compared with the rest of the results. Better results have been obtained when number of inputs in the nonlinear model were increased from one to three.

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The search for truth is in one way hard and in another way easy. For it is evident that no one can master it fully nor miss it wholly. But each adds a little to our knowledge of Nature, and from all the facts assembled there arises a certain grandeur.

Aristotle

INTRODUCTION

1.1 GENERAL

A flood is an unusually high stage in a river normally the level at which the river overflows its banks and inundates the adjoining area, causing disruption of day to day activity. At a given location in a stream, peak flood values vary from year to year and their magnitude constitutes a hydrology series. In planning and design of water development projects peak flood values that can be expected are of primary importance as it is required to adequately proportion the structure for controlling the adverse effects of the flood.

The flood magnitude in a catchment depend upon the characteristics of the catchment, rainfall and antecedent condition, each one of these factors in turn depend upon a host of constituent parameters. This makes the prediction of the flood flows a very complex problem. Hence, the problem of flow-forecasting resulting from a known storm in a catchment has received considerable attention. The study in this direction which is essential in analyzing stream characteristics associated with floods forms the vital subject matter of applied hydrology. The computations were performed by experienced hydrometeorologists by using meteorological data in the past. Various methods ranging from highly sophisticated ones to simple empirical methods have been proposed for predicting the flood runoff. Probably the most popular and widely used method for prediction of floods is the unit hydrograph method.

This method was first suggested by Sherman in (1932). Details of background on the unit hydrograph method are discussed below.

1.2 The Unit Hydrograph Theory

A unit hydrograph represents the lumped response of the catchment to a unit rainfall excess occurring uniformly over the basin and at a uniform rate for a specified duration to produce a direct-runoff hydrograph. It relates only the direct runoff to the rainfall excess.

The basic foundation of unit hyrograph theory is supported on the assumptions / principles of (i) the linear response and (ii) the time- invariance.

These are described below (Johnstone and Cross, 1949):

- For a given catchment, the duration of surface runoff is essentially constant for all uniform-intensity storms of the same length, regard less of differences in the total volume of surface runoff.
- 2. For a given catchment, if two uniform intensity storms of same length produce different total volumes of surface runoff, then the rates of surface runoff at corresponding times t, after beginning of two storms are in the same proportion to each other as the total volumes of surface runoff.
- 3. The time distribution of surfaces runoff from a given storm period is independent of concurrent runoff from antecedent storm periods.

1.2.1 Limitations of Unit Hydrograph Theory

Following are the limitations of unit hydrograph theory.

1.2.1.1 Space invariance of effective rainfall

- (i) It is seldom true that the effective rainfall of a specified duration will occur uniformly over the catchment of a reasonable size. Therefore, spatial invariance of the effective rainfall is only an assumption, not a reality. The spatial variation generally becomes more and more pronounced as the size of the catchment increases.
- (ii)

1.

Intense rainfall storms usually do not extend over large areas. A fair semblance of a uniform spatial distribution of rainfall may seldom be obtained on catchment exceeding 500 km^2 an upper limit conventionally observed in the application of the unit hydrograph.

(iii) The non-uniform areal distribution of rainfall can cause variation in hydrograph shape (Dickinson and Ayers, 1965).

1.2.1.2 Time – invariance of effective rainfall

The effective rainfall usually does not occur uniformly even for a short duration. However the effect of temporal variation of rainfall intensity can be accounted for by using smaller period rainfalls.

1.2.1.3 Validity of linearity hypothesis

All catchments in nature are nonlinear; some are more nonlinear and some less. They are linear only by assumption (Singh, 1988).

If the hydrographs from the storms of the same duration are compared, it is commonly found that their ordinates are not in proportion to their volumes and that their time bases are not the same. The peaks of the unit hydrographs for small rainfall events are usually lower than those for larger ones.

Also, the length of the recession depends on the hydrograph peak. Moreover, the catchment linearity requires a linear relationship between storage and discharge and that the velocity of flow at every point must be constant for all discharges. These conditions are too stringent and are almost never valid.

1.3 NEED OF THE STUDY

Runoff is the response of a catchment for a particular rainfall pattern under various hydrometeorological factors and the exact prediction of which is rather difficult but prerequisite for successful planing and design of water resources project for irrigation, water supply, hydropower, flood management/flood forecasting and other water use systems. Of the various characteristics of the flood hydrograph, the most important and widely used parameter is the flood peak the hydrograph of extreme flood and stages corresponding to flood peaks provide valuable data for purposes of hydrologic design. In the design of practically all hydraulic structures the peak flow that can be expected is of primary importance to adequately proportion the structure to accommodate

its effect. T.the design of bridges, culverts, water ways and spillways for dams and estimation of scour at a hydraulic structure are some examples where in flood- peak values are required and play an important role.

It is well appreciated that a runoff series which extends back far enough to include typical long-term variations is essential for proper planning and design of various wateruse systems. Very few rivers, however have runoff records which satisfy this requirement. Although statistical methods enable the designer to generate synthetic data, the success of these methods also depends on the length of the available data from which the statistical model parameters are derived. Also many of the streams in India are ungauged. Therefore, it is required to have reliable methods which can be used for the prediction of flood flow and its peak from precipitation records.

1.4 THE PHENOMENON OF CATCHMENT RUNOFF

Runoff means the draining or flowing off of precipitaion from a catchment area through a surface channel. It thus represents the output from the catchment in a given unit of time. The phenomenon of watershed runoff is complex. The watershed runoff is mainly composed of three components which may, at a given time occur separately or simultaneously with varying magnitudes. These are (i) surface runoff, (ii) subsurface runoff or inter flow and (iii) base flow or ground water runoff.

Surface runoff usually occurs when the rainfall intensity exceeds the initial demand of interception, infiltration, and surface storage. The surface runoff travels over the ground surface and through channels to the watershed outlet. So, the surface runoff may be composed of (i) over land flow and (ii) channel flow. As surface runoff flows towards the watershed outlet, a portion of it is infiltered into the soil or channel bed. The infiltration taking place in a channel is often referred to as transmission loss.

The subsurface runoff represents that portion of infiltrated rainfall that moves laterally through the upper soil horizons until it reaches the stream channel. This moves more slowly than surface runoff and may join the surface runoff during or after the storm.

The proportion of stream flow that occurs as subsurface runoff depends on geological characteristics of the watershed and space-time properties rainfall.

The base flow is that portion of infiltrated water that reaches the water table and then discharges into the stream. This type of flow moves much more slowly and has little effect on flood peaks in small watersheds. Depending upon permeability of soil, the base flow response widely varies from one ground water body to another.

The direct runoff is considered to consist of surface runoff and so-called quick inter flow, whereas base flow consists of delayed inter flow and ground water runoff. Figure 1.1 depicts different routes of runoff.

1.5 A MULTIPLE-INPUT SINGLE-OUTPUT FLOW FORECASTING MODELS- AT A GLANCE

In this approach, the continuity equation of flow is expressed is a spatially lumped form without considering the physical laws operating within the catchment and instead a general but simple relationship is assumed between rainfall amount and the discharges at the outlet of the catchment. The model in its original form with single input is sufficient for small catchments where the rainfall distribution can be assumed to be uniform. In case of larger catchments, the violation of the assumption of uniformity of rainfall is higher. Therefore, the large catchment is divided into a number of hydrologically homogeneous sub-catchments. The rainfall occurring over these subcatchments can be considered as independent inputs. The model consists of both nonlinear and linear components. Because of these reasons the model can take care of spatial variation of rainfall as well as catchment heterogeneities (which are major inabilities in the lumped models, now-a-days in the practice) while transforming daily rainfall into runoff, (Kothyari and Singh, 1999).

Muftuoglu (1984) was the first to suggest the structure of a linear – nonlinear combined model. Liang (1988) checked the validity of multiple- input single-output model in hydrological fore casting. Later, the same linear and non-linear models in the

above aspect have been studied in detail covering various aspects by Liang and Nash (1988), Liang et al. (1992) and Liang et al. (1994). Kothyari and Singh (1999) applied a multiple-input single-output rainfall-runoff model for prediction of daily flows in Narmada catchment. The detailed description about these are mentioned in the Chapter-2.

1.6 PROBLEMS IN THE USE OF METHODS FOR DETERMINATION OF RESPONSE FUNCTION OF A MULTIPLE – INPUT SINGLE - OUTPUT MODEL

The Problem of the numerical instability of a unit hydrograph derived by ordinary least squares from a complex rainfall- runoff event is well known is hydrology. The same problem though perhaps less acute, arises in the identification of the pulse response of the single-input single-output linear, time invariant model applied in the process of flood routing or rainfall-runoff modeling. This problem is not due to the model itself, rather it is due to the estimation method, the sample size and the observed input and output variables, especially the input variables. Bree (1978) pointed out that the estimation of the ordinates of non-parametric unit hydrographs from sample data is very sensitive to the interrelation existing among the observed input series.

The problem has been tackled by Kutchment (1967) and Bruen and Dooge (1994) amongst others using the concept of ridge regression which produces a least squares estimate subject to a constraint expressing the preferred shape of the impulse response.

In the context of a system receiving multiple inputs in parallel, e.g. forecasting the outflow hydrograph in terms of observed inflow hydrographs further up the main stream and on tributaries with or without rainfall on the intervening catchment, the problem obviously becomes more difficult and the possibility of numerical instability is increased, because of the expectation of cross-correlation between various input functions. However, this can be overcome by addition of an uncorrelated white noise component to the inflow series (Liang and Nash, 1988). Amongst the methods available for estimation of response function in the presence of noise in the data, the method of smoothed least squares by Bruen and Dooge (1994) is probably the best suited method.

1.7 AIM OF THE PRESENT STUDY

Inspite of the fact that the unit hydrograph is a practical tool, its inability to represent the full catchment operation which is a non-linear process directed attention to non-linear models some two decades ago. The endeavor resulted in the discovery of the potentialities for catchment analysis of the functional series which was already being used in electronics (Amorocho, 1973). The functional series is a universal mathematical model for non-linear black-box systems, which produced a single output from a serial input.

The unit hydrograph is based on the assumption that the rainfall is occurring simultaneously on the whole catchment with same intensity which is practically not possible. This assumption may be true for a small catchment but the same cannot be true for large ones. Therefore, to derive a response function of a large catchment, it is divided into a number of sub-catchments having the uniform rainfall through out in those subareas. The aim of the present study is to derive the response function for a catchment which is divided into small sub-catchments from consideration of the rainfall inputs. Both the linear and non-linear approaches were applied.

REVIEW OF LITERATURE

2.1 GENERAL

Most hydrologic systems are extremely complex and we can not hope to understand them in all detail. Therefor abstraction is necessary if we are to understand or control some aspects of their behavior. Abstraction consists in replacing the system under consideration with a model of similar but simpler structure. The basic purpose of a model is to simulate and predict the operation of the system that is unduly complex and the effect of changes on this operation.

The hydrologic cycle can be regarded as a hydrologic system. Various components of this system might include precipitation, interception, evaporation, transpiration, infiltration, detention storage or retention storage, surface runoff, inter flow and groundwater flow. Each component is a subsystem, if it satisfies the characteristics of a system set-out in its definition.

There are many illustrations representing the hydrologic cycle. Among them, recognizing the scope of hydrology, more detailed and the simplified system representation for catchment runoff is shown in Fig.2.1.

A catchment can be stated to a hydrologic system. When unit input is applied to the hydrologic system in the form of rainfall, the response function of hydrologic system comes out in the form of rainfall. Several response functions can be obtained for single catchment by applying different rainfalls. Various types of response functions are discussed below.

2.2 **RESPONSE FUNCTIONS OF LINEAR SYSTEM**

2.2.1 The Impulse Response Function

If a system receives an input of unit amount applied instantaneously at time ' τ ' the response of the system at later time't' is described by the unit impulse response function $u(t-\tau)$.

't- τ ' is the time-lag since the input was applied

2.2.2 The Step Response Function

A unit step input is an input that goes from a rate of 0 to 1 at time 'o' and continues definitely at that rate thereafter. The ouput of the system, its step response function is

$$g^{(t)} = \int_{0}^{t} u(t - \tau) d\tau \qquad (2.1)$$

2.2.3 The Pulse Response Function:

A unit pulse is an input of unit amount occurring in duration δt . the rate is $I(\tau)=1/\delta t$, $0 \le \tau \le \delta t$ and zero else where. The response of the system at time t is described by the unit pulse response function U(t).

$$U(t) = \frac{1}{\delta t} [g(t) - g(t - \delta t)]$$
(2.2)

2.2.4 The Standardized Unit Pulse Response

The unit hydrograph as a relationship between "effective rainfall" and "Storm runoff" is necessarily of unit volume as the volumes of the input and output are equal. However, where volume is not conserved, the sum of the ordinates multiplied by the common interval between them represents a "gain factor" which may be greater or less than unity, reflecting the ratio of the volumes of output and input.

$$J^{\text{th}} \text{ gain factor } g(j) = \sum_{j=1}^{m(j)} U_i^{(j)}, j = 1, 2,, j$$
(2.3)

The "standardized unit pulse response" is obtained by dividing every ordinate of the least squares unit pulse response by the corresponding gain factor, thus reducing the area to unity.

2.2.5 The Gamma Function Impulse Response

For a single input-single output, linear system the model is

$$U(t) = (t/k)^{n-1} e^{-t/k} / k\Gamma(n)$$
(2.4)

where,

k = a parameter of dimension time

n = a shape parameter

 $\Gamma(n) = \text{gamma function of } n$

This was suggested by Nash (1957) in the context of rainfall-runoff modeling and by Kalinin and Milyukov (1957) in the context of flood routing.

2.3 RESPONSE FUNCTION FROM MULTIPERIOD STORM

2.3.1 Linear System

It may be more representative to derive a single composite response function for a catchment from several rainfall events considered simultaneously

The relationship of the sampled various flood hydrograph ordinates Q, rainfall P and response function ordinates U can be expressed as,

(2.5)

 $Q_{i,n} = P_{i,n} U_{l} + P_{i,n-1} U_{2} + \dots + P_{i,n-m+1} U_{m}$ $i = 1, 2, \dots I$ $m = 1, 2, \dots M$ $n = 1, 2, \dots N,$

in which

Ι

i = number of flood event

= total number of flood events

- n = ordinate number of each observed hydrograph
- N_1 = total number of ordinates of the observed hydrograph
- m = number of unit hydrograph ordinates
- M = total number of unit hydrograph ordinates.

Matrix representation of general Eq. (2.5) is:

$$[Q] = [P] [U]$$
 (2.6)

when 'I' number of storms occur on a catchment, then the relationship among the hydrographic ordinates 'Q', rainfall 'P' and response function ordinates 'U' are represented in the matrix form as below:

$$\begin{bmatrix} Q_{1,1} \\ Q_{1,2} \\ \vdots \\ Q_{2,1} \\ Q_{2,1} \\ Q_{2,2} \\ \vdots \\ Q_{2,N_2} \\ \vdots \\ Q_{2,N_2} \\ \vdots \\ Q_{1,1} \\ Q_{1,2} \\ \vdots \\ Q_{1,N_1} \end{bmatrix} = \begin{bmatrix} P_{1,1} & 0 & 0 & \vdots & \vdots \\ P_{1,2} & P_{1,1} & 0 & \vdots & \vdots \\ P_{1,N_1} & \vdots & \vdots & P_{1,N_1-m+1} \\ P_{2,1} & 0 & 0 & \vdots & \vdots \\ P_{2,2} & P_{2,1} & 0 & \vdots & \vdots \\ P_{2,2} & P_{2,1} & 0 & \vdots & \vdots \\ P_{2,N_2} & \vdots & \vdots & P_{2,N_2-m+1} \\ \vdots & \vdots & \vdots & \vdots \\ P_{2,N_2} & \vdots & \vdots & P_{2,N_2-m+1} \\ \vdots & \vdots & \vdots & \vdots \\ P_{1,1} & 0 & 0 & \vdots & \vdots \\ P_{1,2} & P_{1,1} & 0 & 0 & \vdots & \vdots \\ P_{1,N_1} & \vdots & \vdots & P_{1,N_1-m+1} \end{bmatrix} \\ * \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ \vdots \\ U_3 \\ \vdots \\ U_m \end{bmatrix}$$

(2.7)

Solution of Eq. (2.6) for 'U' can be obtained from the least squares solution of the above mentioned matrix equations. Details of solution procedure are discussed later. Jain (1993) used this methodology for fore casting of floods in two non-seasonal catchments namely Bird Creck in USA and Ray in UK and obtained satisfactory flood predictions, using eq. (2.5).

2.3.2 Non-Linear System

The catchment can also be considered as a variable non-linear system that operates on the rainfall continuously to transform it into the runoff.

If the catchment was a linear system, the runoff Q_m would be expressed in term of the rainfall P_1 occurring in each unit interval of the memory as.

$$Q_{m} = \sum_{i=0}^{m} U_{m-i} P_{i}$$

$$(2.8)$$

where 'm' is the number of unit intervals in the duration of the memory (counting from 0) and U_{m-1} is a coefficient representing the contribution rate from the (m-i) the internal-Interception, depression, detention and soil storage are partly or fully produced by the rainfall occurring in the antecedent intervals. More over, the sheet and channel flows are non-linear functions of current rain intensities, therefore, the coefficients 'U_{m-1}' are not constant, but vary as function of antecedent and concurrent effective precipitation. Thus we have

$$U_{m-i} = \sum_{j=1}^{m} U_{m-i,m-j} P_j$$
(2.9)
$$i = 0, 1, 2, \dots, m$$

where $U_{m-i,m-j}$ is a new coefficient representing the contribution rate from the ith interval, Substituting the equivalent of U_{m-i} into Eq.(2.8) we have.

$$Q_{m} = \sum_{i=0}^{m} \sum_{j=1}^{m} U_{m-i,m-j} P_{i} P_{j}$$
(2.10)

However, the immediate and moderately delayed responses of the catchment are highly non-linear, where as the delayed response can be assumed to be liner (Amorocho, 1963). Thus the model as given in Eq.(2.9) can be modified for immediate or moderately delayed and delayed responses of catchment simultaneously.

This can be modified as given below:

$$Q_{m} = \sum_{i=1}^{n} \sum_{j=1}^{n} U_{ij} P_{i+1} P_{j+1} + \sum_{i=1}^{l} U_{i} P_{i}$$
(2.11)

Where 'm' is the number of unit intervals in the duration of memory. 'n' and 'l'

the numbers of intervals in the non-linear and linear parts of memory respectively.

i.e. m=n+l n = non-linear part l = liner part

Solution of Eq. (2.11) can be obtained from the least squares solution matrix equations. Details of solution procedure are discussed later on in succeeding chapter.

Kumar (1995) had used the non-linear relationship shown in Eq. (2.11) for flood forecasting in two non-seasonal catchments namely Bird Creek in USA and Ray in UK. It was found that better flood forecasts were made by non-linear model as compared to the forecasts made by a linear model used by Jain (1993).

2.4 MULTIPLE - INPUT, SINGLE - OUTPUT SYSTEMS

2.4.1 Linear System

For a linear system, the relationship of a single input function of time p(t) to a single output function of time Q(t) may be expressed by the convolution integral:

$$Q(t) = \int_{0}^{x} U(\tau)p(t - \tau)d\tau$$
(2.12)

Where U(t) is the impulse response function. A linear system may not however be restricted to a single input and a single output. A system relating a number of independent input functions of time to a single output function is linear, if the relationship of each input to its component in the output is linear and if the Principle of superposition applies to the combination of the several output components. This relationship may be written as.

$$Q(t) = \sum_{j=1}^{J} \int_{0}^{x} U^{(j)}(\tau) p^{(j)}(t - \tau) d\tau$$
(2.13)

Where, J is the total number of input functions, $p^{(j)}$ is the jth input function of time and U^(j) is the unit pulse response function corresponding to the jth input function $p^{(j)}$. When the input function is expressed as a series of pulses (mean values over successive short time intervals T) and the output is similarly expressed, or expressed as a series of ordinates at the same intervals δt the unit pulse response U₁.....U_k.....U_m (also at intervals of δt), may provide more convenient expression of the operation of the system than the inpulse response. The multiple-input, single-output relationship may be expressed in terms of the pulse response as a series of linear algebraic equations:

$$Q(t) = \sum_{j=l}^{J} \sum_{k=1}^{m(j)} U_k^{(j)} P_{(t-k+l)}^{(j)}$$
(2.14)

Where m(j) is the memory length of the system corresponding to the jth input series. Eq. (2.14) implies:

(1) Each input series p(j) is linearly related to its corresponding output component Q(j), j=1,2...,J, by:

$$Q_{t}^{(j)} = \sum_{k=1}^{m(j)} U_{k}^{(j)} P_{(t-k+1)}^{(j)}$$

(2) Output components are linearly additive viz.

$$Q_t = Q_t^{(1)} + Q_t^{(2)} + Q_t^{(j)}$$

Given adequate records of input and output functions over a period generally referred to as "the calibration period", analytical solution of Eq. (2.14) for the several $U^{(j)}$ functions is possible. Even in the presence of errors of observation, nonlinearly, least square solutions may be obtained.

Equation (2.14) becomes;

$$Q_{t} = \sum_{j=1}^{J} \sum_{t=1}^{m(j)} U_{k}^{(j)} P_{(t-k+1)}^{(j)}$$
(2.15)

If each $U^{(j)}$ is treated as an unrestricted series, least squares solutions may be obtained by matrix multiplication as an extension of multiple linear regression. Such solutions are referred to as "non parametric".

Where the U functions are of known form, or can be assumed to be of some specified form with sufficient generality, though varying in their parameter values, solution of Eq. (2.15) requires only the determination of these parameter values. Such "parametric" solutions are less general but also less sensitive to data errors.

Discrete non parametric solution of Eq. (2.15):

Eq. (2s.15), for a series of N values $Q_1, Q_2, ..., Q_n$ can be written in matrix form as: $Q = P^{(1)} U^{(1)} + P^{(2)}U^{(2)} + + P^{(j)} U^{(j)}$ (2.16)

Where Q is an (N,1) columns vector of the output series such that:

$$\mathbf{Q} = \begin{bmatrix} \mathbf{Q}_1 \\ \mathbf{Q}_2 \\ \vdots \\ \vdots \\ \mathbf{Q}_N \end{bmatrix}$$

(2.17)

(2.18)

 $P^{(j)}$ is an [N, m_(j)] matrix of the jth input series:

	$P_{l}^{(j)}$	0	0]
P ^(j) =	$P_2^{(j)}$	$P_{I}^{(j)}$	0
P" =	50	$P_{m(j)-l}^{(j)}$	$P_{I}^{(j)}$
	$\begin{bmatrix} P_{m(j)}^{(j)} \\ P_{N}^{(j)} \end{bmatrix}$	$P_{N-1}^{(j)}$	$P_{N-m(j)+1}^{(j)}$

 $U^{(j)}$ is an [m(j),1] column vector of the pulse response ordinates corresponding to j^{th} input series:

$$\mathbf{U}^{(j)} = \begin{bmatrix} \mathbf{U}_{1}^{(j)} \\ \mathbf{U}_{2}^{(j)} \\ \vdots \\ \mathbf{U}_{m}^{(j)} \end{bmatrix}$$

Eq. (2.16) can be written as:

$$Q = PU$$

(2.19)

Where P is an (N,M) matrix:

$$P = [P^{(1)}P^{(2)}...P^{(j)}]$$

And U is an (M,1) column vector of length $M = \sum_{j=1}^{J} m(j)$ obtained by writing each U^(j)

vector in sequence of j

$$U = \begin{bmatrix} U^{(1)} \\ U^{(2)} \\ \vdots \\ U^{(j)} \end{bmatrix}$$

From Eq. (2.19)
$$Q = P U$$
$$\Rightarrow [P^{T}Q] = [P^{T}P]U$$

 \Rightarrow U = $[P^T P]^{-1} [P^T Q]$

(2.20)

(2.21)

With the given value of observed runoff ordinates and rainfall value form each sub-catchment using Eq. (2.19) & (2.21), the response function ordinates of the large catchments can be derived. Liang and Nash (1988) had used this method for flood forecasting in Hankou catchment from the Changjiang (Yangtze) valley in China for examination. The analysis consists of four input functions. The catchment areas above each of the four input gauging sites are Yichang 1, 005, 501 km², Huangzhuang 142,056 km², Changyang 15,300 km² and Chenlinghj. 223,482 km². The hydrograph at Hankou is the corresponding output functions. The total catchment area of Hankou as shown in Fig. 2.2 is 1,488,036 km². Physically realistic response functions as obtained by his analysis for the above four inputs are shown in Fig. 2.3.

2.4.2 Non-linear System

Response function of a catchment may be non-linear. The multiple-input, singleoutput relationship may be expressed in terms of the pulse response as a series of nonlinear algebraic equations:

$$Q_{t} = \sum_{j=1}^{J} \sum_{i=1}^{n(j)} \sum_{k=1}^{n(j)} U_{i,k}^{(j)} P_{t-i+1}^{(j)} P_{t-k+1}^{(j)} + \sum_{j=1}^{J} \sum_{i=1}^{l} U_{i+n}^{(j)} P_{t-(i+n)+1}^{(j)}$$
(2.22)

Where, $j = 1, 2, \dots, J$ (Number of subcatchment)

n = non-linear part of memory length

1 = linear part of memory length

Eq. (2.22) implies

(1) Each input series $P^{(j)}$ is non-linearly related to its corresponding output component $Q^{(j)}_{t}$, j = 1, 2, ..., J by:

$$Q_{t} = \sum_{t=1}^{m(j)} \sum_{i=1}^{n} \sum_{k=1}^{n} U_{i,k}^{(j)} P_{t-i+1}^{(j)} P_{t-k+1}^{(j)} + \sum_{t=1}^{m(j)} \sum_{i=1}^{l} U_{i+n}^{(j)} P_{t-(i+n)+1}^{(j)}$$

(2) Output components are linearly additive viz.

$$Q_t = Q_t^{(1)} + Q_t^{(2)} + \dots + Q_t^{(j)}$$

Eq. (2.22) can be written in matrix form for a series of N values $Q_1, Q_2 \dots Q_N$ as

$$Q = P^{1} U^{1} + P^{2} U^{2} + \dots + P^{J} U^{J}$$
(2.23)

Where Q is an (N,1) column vector of output series such that:

$$Q = \begin{bmatrix} Q_1 \\ Q_2 \\ \vdots \\ \vdots \\ Q_N \end{bmatrix}$$
(2.24)

 $P^{(J)}$ is an [N, m(j)] matrix of the jth input series:

 $U^{(j)}$ is an [m(j),1] column vector of pulse response ordinates corresponding to jth input series :

$$U^{(j)} = \begin{bmatrix} U_{1}^{(j)} \\ U_{2}^{(j)} \\ \vdots \\ \vdots \\ U_{m}^{(j)} \end{bmatrix}$$
(2.26)

Eq. (2.23) can be written as:

$$Q = P U$$

Where, P is an [N, M] matrix:

 $\mathbf{P} = [\mathbf{P}^{(1)} \mathbf{P}^{(2)} \dots \mathbf{P}^{(j)}]$

(2.28)

(2.27)

And U is an (M,1) column vector of length $M = \sum_{j=1}^{J} m(j)$ obtaining by writing each U^(j)

vector in sequence of j

$$U = \begin{bmatrix} U^{(1)} \\ U^{(2)} \\ \vdots \\ U^{(j)} \end{bmatrix}$$
(2.29)

With the given values of observed runoff ordinates and rainfall value form each subcatchment use Eq. (2.24) and (2.28) the matrix of runoff and rainfall are formed.

$$Q = P U$$

$$\Rightarrow [P^{T}P]U] = [P^{T}Q]$$

$$\Rightarrow U = [P^{T}P]^{-1}[P^{T}Q]$$
(2.30)

Where, 'U' is the response function of the large catchment.

Kothyari and Singh (1999) applied a multiple-input single-output (non-linear) rainfall-runoff model using Eqs. (2.22) and (2.30) as above for prediction of daily flows in Narmada catchment and obtained good results as shown in Fig. 2.4, 2.5 & 2.6.

2.5 METHODS FOR DETERMINATION OF RESPONSE FUNCTION

Various investigators have linked unit hydrograph characteristics of basins (Snyder, 1938; Edson, 1951; Taylor and Schwarz, 1952; Rodrigues-Iturbe and Valdes, 1979; Valdes et al, 1979; Gupta et al, 1980; Rodrigues –Iturbe et al 1982). Some of these efforts are directed towards estimating geomorphologic unit hydrographs. Others are interested in the development of topological unit hydrographs, which are based on the theory of topologically random networks (Gray, 1961, Karlinger and Troutman, 1985; Trontman and Karlinger, 1985).

Different methods have been developed to estimate response functions, Snyder (1955) used the method of least squares. Eagleson et al (1966) obtained an approximate solution of the Wiener-Hopf equations through linear programming and matrix inversion to compute optimum realizable unit hydrographs. Deininger (1969) used linear programming techniques based on minimum absolute deviations and on min-max criteria. Singh (1976) compared the linear programming and least-Squares fitting methods. Mays

and Coles (1980) used linear programming. The objective function does not give special weight to the region around the unit hydrograph peak, which is an important property of unit hydrographs. Mays and Taur (1982) used two non-linear programming techniques, the large-scale generalized reduced gradient technique and the generalized reduced gradient with three different objective functions to compute unit hydrographs. Rao and Delleur (1971) compared the performances of Fourier, Laplace and Z-transform methods in estimating the unit hydrographs. Fourier transform methods were also used by Blank et al. (1971) and Sharma et al (1973). Some methods are discussed to determine the response function in the following paragraphs.

2.5.1 Linear Programming Model

Considering the following Eq. (2.31) relating rainfall-runoff process as given earlier in eq. (2.19).

[Q] = [P] [U]

(2.31)

where 'Q' is observed runoff matrix

'P' is effective precipitation matrix

'U' is unknown response ordinate matrix

The solution of this set by "least squares method" fields the value of unknown response function Ui, $U_{i, j}$. Owing to representation, measurement and process errors involved in the data, some of ordinates may take on negative values. In order to ensure a physically realizable set of response function, the Eq. (2.31) is to be solved under the constraint.

$U_{i}, U_{i,j} > 0$

To satisfy this additional requirement, it is necessary that the regression equations be truncated so as to form under-determined set i.e a set having more unknown than equations. There will then be a multiplicity of solutions from among which the best satisfying the above constraint can be selected. It seems logical to construct the regression equations, for a model having a memory longer than required, i.e. a model having extra response function ordinates and then to leave out the extra equations from the set of regression equations in the solution. We now need a criterion for selection of best solution of Eq. (2.31) as the extra response function ordinates will be used as slack variables in linear programming as their influence is required to be a minimum. Thus, the solution must satisfy the conditions that.

$$\sum_{i=1}^{L_1} U_i$$
 is minimum.

Where, U_I is the number of extra response function ordinates.

The problem can be expressed in general format of linear programming as

$$Minimize \sum_{i=1}^{L_1} U_i$$

subject to a set of linear constraints

[P] [U] = [Q] and [U] > 0

This is simple linear programming problem that can be solved by using simplex algorithm. In order to make extra dummy response function ordinates having least possible effect in actual ordinates, they must be minimum in number (i.e. L_1 . Must be minimum). This minimum can be found by trail and error, starting the trials with small 'L' such as '1' or '2'additional constraints can be introduced to preserve monotonically decrease in the ordinates using.

 $U_{l} < U_{i+1}$ and $U_{i,j} < U_{i,j+1}$

2.5.2 Non- Linear Programming Method:

Mays and Taur (1982) used the non-linear programming approach for derivation of response function. The model based on non-linear programming (NLP) can be used to derive composite response function considering several multiperiod rainfall events simultaneously and does not require rainfall excess to be defined in advance. In this model rainfall losses and consequently rainfall excess is determined. Essentially this new model determines the rainfall losses for each time period of each rainfall event, considered the best composite response function by minimizing the deviation between observed and computed direct surface runoff hydrograph. The NLP codes may be used for solving the problem, which are called LSGRG [Large scale Generalized Reduced Gradient] and GRG-2 [Generalized Reduced Gradient]. In this model, rainfall excess P is defined as difference of total rainfall R for δt hour period and losses H over the same period are expressed as

$$P_{i, n} = R_{i, n} - H_{i, n}$$
 (2.32)
Equation (2.5) can now be expressed as:

$$Q_{i,n} = \left[R_{i,n} - H_{i,n}\right]U_1 + \left[R_{i,n-1} - H_{i,n-1}\right]U_2 + \dots + \left[R_{i,n-m+1} - H_{i,n-m+1}\right]U_m$$
(2.33)

The NLP model can be solved using either of the following two objective functions.

$$\operatorname{Min} Z_{0} = \sum_{i=1}^{l} \sum_{n=1}^{N_{1}} \left[Z_{i,n} + V_{i,n} \right]$$
(2.34)

$$\operatorname{Min} Z_{0} = \sum_{i=1}^{I} \sum_{n=1}^{N_{1}} \left[Z_{i,n^{2}} + V_{i,n^{2}} \right]$$
(2.35)

Subject to the following linear and non-linear constraints;

$$\left[R_{i,n-1} - H_{i,n-1}\right]U_{1} + \left[R_{i,n-2} - H_{i,n-1}\right]U_{2} + \left[R_{i,n-m+1} - H_{i,n-m+1}\right] + Z_{i,n}V_{i,n} = Q_{i,n}$$
(2.36)

$$\sum_{n=1}^{L_{i}} \left[R_{i,n} - H_{i,n} \right] = D_{i}$$
(2.37)

Where $D_l = Direct$ runoff volume to the total rainfall excess for the ith rainfall

$$\delta_t \sum_{n=1}^m U_m = 1$$
 (2.38)

and non-negativity constraints for the following decision variables

$$H_{i,n}, V_{i,n}, Z_{l,n} \text{ and } U_m \ge 0$$
 (2.39)

The direct runoff volume for the rainfall can be expressed as

$$D_{i,=} t \sum_{n=1}^{N_{i}} Q_{i,n}$$
 (2.40)

The total number of decision variables

i=1

$$=2\left[\sum_{i=1}^{I} N_{i}\right] + M + \sum_{i=1}^{I} L_{i}$$

Number of decision variable is non-linear function for objective function
Eq.(2.34)= M + $\sum_{i=1}^{I} L_{i}$

Remaining $2\sum_{i=1}^{1} N_i$, decision variables being linear in the constraints and the objective function. For Eq.(2.34) all the decision variables are non-linear either in objective function (Z,V) or in the constraints (U,H), the total number of constraints for NLP problem is

$$\sum_{i=1}^{I} N_i + I + 1$$

Procedure for NLP solution is given in Fig. 2.7 it is not expected to have the two codes specified earlier.

One con solve the problem using Kuhn Tuker conditions

 $F_{I} = \lambda h_{j} = 0$ $J = 1, 2, \dots, n$ H = 0n > 0 $\lambda \ge 0$

f_l: differential operator

h_i: differential operator

2.5.3 Smoothed Least Squares Method:

Bruen and Dooge (1984) derived this procedure which can also be used for the estimation of composite unit hydrograph.

In cases where the rainfall pattern is such that $p^{T}p$ is ill conditioned then the pulse response will display wild variations in the estimates of adjacent ordinates (even negative estimates) which will be characterized as unrealistic by an experienced hydrologist. Kutchment (1967) has suggested that the prior expectation of smoothness in the derived unit hydrograph can be incorporated into the estimation by solving the following equations in place of the normal equations:

$$(\mathbf{p}^{\mathrm{T}}\mathbf{p} + \mathrm{KI}) \hat{U} = \mathbf{p}^{\mathrm{T}}\mathbf{Q}$$

where K is a parameter chosen by the user.

(2.42)

(2.41)

This approach to regression is described variously in the literature as smoothed least squares or ridge-regression. The properties of this estimator are well known; viz. Hoerl and Kennard (1970). The estimate is biased, thus:

$$\hat{U} = Z \hat{U}_{oLS} \tag{2.43}$$

(2.44)

The multiplicative biasing matrix Z is given by $Z=I+K (p^{T}p)^{-1}$

Thus the degree of bias introduced into the estimate depends on the value of k. A zero value gives no bias while bias increases as k is increased. The operation of the method is best illustrated by considering the mean square error of the estimate of the parameter. This is defined as :

$$MSE(\hat{U}_{s}) = \sum \left\{ \left[\hat{U} - U \right]^{T} \left[U_{s} - U \right] \right\}$$
(2.45)

This can be shown equal to

$$MES = [ZU-U]^{T} - [ZU-U] + trace[Ze_{oLS} e^{T}_{oLS} Z^{T}]$$
(2.46)

Where e_{oLS} is the error in the ordinary least squares estimates of the pulse response ordinates. The first term is the sum of the individual variance of the parameter estimates. The first increases as K increases, while the term can be shown equal to:

trace[Ze_{oLS} e^T_{oLS} Z^T] =
$$\sum_{i=1}^{M} \lambda / (\lambda_i + k)$$
 (2.47)

Which decreases monotonically as K increases (Hoer / and Kenanard, 1970). It can be shown that there is a positive value of K for which the sum of the two terms is minimum. For this value, the mean square error (MSE) of estimation is least and thus offers the best basis for prediction. The coefficient matrix of equations to be solved for the case of smoothed least squares is also symmetric Teoplitz matrix $[P^T P + KI]$.

In fact, it differs from the least squares matrix $p^{T}p$ in only its diagonal, which itself is characterized by a single number, r(1). It remains to be explained why this smoothed least square is preferable to first deriving the least squares estimate and then smoothing it. In the first place, the proposed method is a constrained least squares estimate and thus has some optimal properties, while numerically smoothing an ordinary least-squares estimate destroys its optimality. Secondly, the proposed method can be performed with a lot less computation than deriving an ordinary least-squares estimate and subsequently smoothing it.

2.5.4 Bayesian Method

The Bayesian method also gives instantaneous unit hydrogrpahs like the Ridge regression (smoothed least-squares) method with non-negative ordinates which are not oscillatory. It is the most general method and because it has not been previously used in hydrology.

The Bayesian approach was developed by Bhargava (1986) and Bhargava et al. (1987). The system equation is assumed to be as in Eq. (2.48), where 'e' is normally distributed with mean zero and co-variance matrix ρ^2 I:

$$Q = PU + e \tag{2.48}$$

The conditional probability density of Q given as p and U is given in Eq.(2.49), where ρ^2 is the noise variance:

$$\rho[Q/P, U] = \frac{1}{(2\pi\rho)^{N/2}} \exp\left[-\frac{1}{2\rho} \|Q - PU\|^2\right]$$
(2.49)

The prior density of U is assumed to be as in Eq. (2.50)

$$\rho(\mathbf{U}) = \frac{1}{(2\pi \xi)^{N/2} |\det(\mathbf{x}^{\mathsf{T}} \mathbf{x})|^{1/2}} \exp\left[-\frac{1}{2\xi} \left[\|\mathbf{X}\mathbf{U}\|^{2} \right] \right]$$
(2.50)

Where ξ is a positive constant and X is either the Identity matrix I or the Laplacian matrix C, which is given by Eq. (2.51).

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The Laplacian matrix reduces the effects of large oscillations in the unit hydrograph and hence forces continuity from one-unit hydrograph ordinates. Assuming that the prior densities of ρ and ξ are flat and that these priors satisfy the usual conditions of probability densities, the log likelihood function is written as in Equation (2.52) where k are terms not involving U, ρ and ξ :

$$-\ln f[U, \rho, \xi/\rho, Q] = \frac{\|Q - P U\|^2}{2\rho} + \frac{N}{2}\ln\rho + \frac{\|XU\|^2}{2\xi} + \frac{N}{2}\ln\xi + K$$
(2.52)

On minimizing the log likelihood function with respect to U, ρ , ξ Eq. (2.53)-(2.55) are obtained:

$$\hat{\mathbf{U}} = \left[\frac{\mathbf{P}^{\mathsf{T}}\mathbf{P}}{\rho} + \frac{\mathbf{X}^{\mathsf{T}}\mathbf{X}}{\xi}\right]^{-1} \left[\frac{\mathbf{P}^{\mathsf{T}}\mathbf{Q}}{\rho}\right]$$

$$\hat{\rho} = \frac{1}{N} \left\|\mathbf{Q} - \mathbf{X}\,\hat{\mathbf{U}}\right\|^{2}$$
(2.53)
(2.54)

$$\hat{\xi} \stackrel{\text{a}}{=} \frac{1}{N} \left\| \mathbf{X} \, \hat{\mathbf{U}} \right\|^2 \tag{2.55}$$

These are the Bayesian estimates because of the Gaussian assumptions above. Eqs. (2.53)-(2.55) can be written as Eqs. (2.56) and (2.57)

$$\hat{\mathbf{U}} = \left[\mathbf{P}^{\mathsf{T}} \mathbf{P} + \frac{\hat{\rho}}{\hat{\xi}} \mathbf{X}^{\mathsf{T}} \mathbf{X} \right]^{-1} \mathbf{P}^{\mathsf{T}} \mathbf{Q}$$
(2.56)

$$\frac{\hat{\rho}}{\hat{\xi}} = \frac{\left\| \mathbf{Q} - \mathbf{PU} \right\|^2}{\left\| \mathbf{P} \, \hat{\mathbf{U}} \right\|^2} = \hat{\mathbf{K}}$$

The estimate \hat{K} is the ratio of the sum of squares of residuals to the sum of squares of prior information. As both the numerator and denominator in Eq. (2.57) are positive, the estimate K exists and is unique. If R is large, then the estimated unit hydrograph may not have a direct runoff volume of 1 cm. However, normalizing the unit hydrograph so that it has a unit direct runoff volume is a simple procedure. By letting

 $\hat{\mathbf{K}} = \hat{\rho} / \hat{\xi}$ Eq. (2.58) is obtained form Eqs. (2.56) and (2.57)

$$\hat{K} = \frac{\left\| \mathbf{Q} - \mathbf{P} \left[\mathbf{P}^{\mathsf{T}} \mathbf{P} + \hat{K} \mathbf{X}^{\mathsf{T}} \mathbf{X} \right]^{-1} \mathbf{P}^{\mathsf{T}} \mathbf{Q} \right\|^{2}}{\left\| \mathbf{X} \left[\mathbf{P}^{\mathsf{T}} \mathbf{P} + \hat{K} \mathbf{X}^{\mathsf{T}} \mathbf{X} \right]^{-1} \mathbf{P}^{\mathsf{T}} \mathbf{Q} \right\|^{2}}$$
(2.58)

Equivalently,

$$\hat{K} = \frac{\left\| \mathbf{Q} - \mathbf{P} \left[\mathbf{P}^{\mathsf{T}} \mathbf{P} + \hat{\mathbf{K}} \mathbf{X}^{\mathsf{T}} \mathbf{X} \right]^{-1} \mathbf{P}^{\mathsf{T}} \mathbf{Q} \right\|^{2}}{\left\| \mathbf{X} \left[\mathbf{P}^{\mathsf{T}} \mathbf{P} + \hat{\mathbf{K}} \mathbf{X}^{\mathsf{T}} \mathbf{X} \right]^{-1} \mathbf{P}^{\mathsf{T}} \mathbf{Q} \right\|^{2}} = 0$$
(2.59)

After solving for \hat{K} in Eq. (2.59), it is to be substituted in Eq. (2.56) to obtain the estimated response \hat{U}

2.6 **EFFICIENCY CRITERIA FOR THE MODEL:**

"Initial variance" or variance of the output Q" is the sum of squares of diviations from the mean \overline{Q} , the summation being taken over the period of record under consideration :

var (Q) = $\sum (Q - \overline{Q})^2$

We may also refer to the "residual variance" of a model as the sum of squares of difference between Observed and computed value, also taken over the period of record.

Res. Var (Q) =
$$\sum (\hat{Q} - Q)^2$$

(2.57)

Neglecting the loss of few degrees of freedom, which are negligible in the context of the hundreds, or even thousands of events usually involved, we may define "the efficiency of the model as the proportion of the variance of Q accounted for by the model".

Efficiency of the model depends on the computed and observed values of the storm runoff. If the computed and observed values of storm runoff follow the same pattern, then the efficiency of the model is more. In other words-if the difference of computed and observed values of storm runoff is less, then the model is more efficient while increase in the deviation from computed value of storm runoff to the observed values indicates less efficient model.

Following criteria exists for computation exists for computation of model efficiency.

Initial Var (Q) =
$$F_d = \sum \left[\bar{Q} - Q \right]^2$$
 (2.60)

Where Q = mean of observed discharge in the calibration period.

Q = actual observed discharge

Res var (Q) =
$$F_1 = \sum \left[\hat{Q} - Q \right]^2$$

Where,

 \hat{Q} = Computed runoff hydrograph ordinate

Q =observed runoff hydrograph ordinate

Then the efficiency is given by:

 $E^{2} = \left[\left(F_{d} - F_{1} \right) / F_{d} \right] * 100$ (2.62)

Garrick et. al (1978) proposed that the performance of a conceptual model as a means of forecasting the discharge from a rainfall

$$R_{(t)} \longrightarrow Q_{(t)}$$

(2.61)

(2.63)

should be judged by comparison with a basic forecast which would be the best available forecast without taking into account of rainfall. They suggested that in the absence of rainfall data, this forecast could be obtained only from the observation of previous seasonal behaviour of the discharge and they defined the seasonal forecast for given data 'd' as

$$Q_{d} = n^{-1} \left[Q_{d,1} + Q_{d,2} + \dots + Q_{d,n} \right]$$
(2.64)

where, $Q_{d,r}$ refers to the observed discharge on date 'd' in the year 'r' and 'n' is the number of years of data available for calibration. This Q_d replaces the \overline{Q} in Eq. (2.60) and then F_d becomes:

$$F_{d} = \sum [Q_{d} - Q]^{2}$$
 (2.65)

In the present study, efficiency of the estimated response functions has been computed as above for predicting the flood magnitudes, using Eqs. (2.60), (2.61) and (2.62).

2.7 STANDARD ERROR OF RESPONSE FUNCTION ORDINATES

The standard error i.e. variance of the response function ordinates U_i may be obtained by taking the corresponding terms of the principal diagonal of $[P^TP]^{-1}$ and multiplying by S^2

S.E. =
$$V^{-1} S^2$$
 (2.66)
 $S^2 = (n-m)^{-1} \sum_{i=1}^{n} e_i^2$ (2.67)

Where,

 e_i = difference of computed and observed discharge

n = number of ordinates of observed hydrograph

m = memory length of catchment

 V^{-1} = principal diagonal terms of $[P^{T}P]^{-1}$

The response function ordinate is considered to be significant when its standard error is smaller than its magnitude.

2.8 BRIEF SUMMARY

The system based approach has been exhaustively used for the modeling of rainfall - runoff process. Conventionally, linear relationships have been considered to exist between the rainfall and the runoff and signal-input, single-output kind of rainfall-runoff relationships have mostly been studied. The multiple-input, single-output linear rainfall-runoff relationship had been studied by Liang (1988) and Liang et al. (1994) in the context of flood routing problem. Kothyari and Singh (1999) applied a multiple - input single - output rainfall - runoff non - linear model for prediction of daily flows in the Narmada catchment. Except this, no other study has been considered so far based on nonlinear multiple - input and single - output rainfall - runoff model.

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METHODOLOGY

3.1 GENERAL

The objective of present study is to use multiple - input rainfall for modeling of runoff at the catchment outlet of Wardha river of the Godavari basin having an area of 19975 km². The total rainfalls have been considered as inputs and the total runoff as the output as against to the use of effective rainfall and direct runoff as input and output respectively used in conventional unit hydrograph method. Both the linear as well as the non-linear relationships are constructed by stacking together the data sets of storm events those occurred at different time periods. The whole catchment of Wardha river is divided into three hydrologically homogeneous sub-areas of approximately uniform rainfall distribution. Thereby, the spatial variation of rainfall and the catchment hetrogeneities are incorporated in the model by treating rainfall as separate lumped multiple inputs.

In the present chapter, the particulars of "the multiple-input, single-output model and its description" are presented. The same model can be utilized to the single-input, single-output form by reducing the number of rainfall inputs only one.

3.2 MODEL DESCRIPTION

The output function Q_t of a lumped linear system is related to the single input function P_t as (Nash and Foley, 1981; Singh, 1988).

$$Q_t = \sum_{i=1}^m U_i P_{t-i+1}$$

(3.1)

Where,

U denotes the discrete series of pulse response ordinates

m is the memory length of the system

t is the time expressed as an integer number of sampling intervals.

Equation (3.1) represents the classical unit hydrograph type of model.

Since, the hydraulic equations representing overland and channel flows are nonlinear partial differential equations and therefore become non-linear functions of the rainfall intensities. Hence, the coefficients U_I of eq (3.1) are not constants but vary as functions of antecedent and current rainfalls (Amorocho, 1973; Muftuoglu, 1984; Singh, 1988). Therefore, the immediate and moderately delayed responses of the catchment are known to be highly non-linear, while the delayed (i.e. ground water) response can be realistically assumed to be linear (Amorocho and Orlob, 1961; Brandsteller and Orlob, 1970; Amorocho, 1973; Muftuoglu, 1984 & 1991).

With the above considerations, Eq. (3.1) was modified by Muftuoglu (1984, 1991) to simultaneously account for both the immediate and moderately delayed runoffcomponents and the delayed runoff components, resulting from the single lumped rainfall functions as :

$$Q_{t} = \sum_{i=1}^{n} \sum_{k=i}^{n} U_{i,k} P_{t-i+1} P_{t-k+1} + \sum_{i=1}^{l} U_{i+n} P_{t-(i+n)+1}$$
(3.2)

Where,

n

1

- = number of time intervals of rainfall contributing to the immediate and moderately delayed runoff (i.e. the non-linear part of the total memory of the catchment)
- = number of time intervals of rainfall contributing to the delayed runoff (i.e. linear part of the total memory).

m = n + l = total memory length of the model

- U_{i,k} = ordinates of non-linear part of the response function (also, termed as ordinates of a two-dimensional unit hydrograph)
- U_i = Ordinates of linear part.

The effective number of corresponding unknowns $U_{i,k}$ are equal to n(n+1)/2 where as the number of unknowns U_i are equal to 1. Thus, the total number of unknown elements i.e. ordinates which need to be identified in the calibration process of present model is the sum = mm = [n(n+1)/2+1].

The model in its original form is sufficient for small catchments where the rainfall distribution can be assumed uniform. Therefore, the catchment area of Wardha river has been divided into J (three) sub-catchments and the whole catchment was treated as assemblies of these sub-catchments which can be assumed to be an independent areas of uniformly distributed rainfall.

The memory lengths l and n for the different sub-areas of the catchment were chosen according to a subjective combination of the following criteria (Kothyari et al 1993):

- (i) The memory length values are the minimum values beyond which an increase in l (for the delayed response) and / or n (for the prompt response) does not significantly increase E² (efficiency).
- (ii) The maximum values of n and 1 are such that the last ordinates of the pulse response are still above their respective standard errors;
- (iii) The shapes of the desired pulse response functions are physically realistic.
- 3.3 MULTIPLE INPUT, SINGLE OUTPUT RAINFALL RUNOFF MODEL As explained in the preceding chapter and as above, the multiple - input, single-

(3.3)

output non-linear relationship between rainfall and runoff can be expressed as blow :

$$Q_{t} = \sum_{j=1}^{J} \sum_{i=1}^{n(j)} \sum_{k=i}^{n(j)} U_{i,k}^{(j)} P_{t-i+1}^{(j)} P_{t-k+1}^{(j)} + \sum_{i=1}^{J} \sum_{i=1}^{l(j)} U_{i+n}^{(j)} P_{t-(i+n)+1}^{(j)}$$

Where, j = 1, 2, ..., J (no. of independent sub-catchments) n and 1 as explained in Eq. (3.2) above. For the application of Eq. (3.3), the rainfall in each sub-catchment is lumped and treated as one of the inputs into the model Eq. (3.3) implies that ...

- (1) Each input series $P^{(j)}$ is related by Eq. (3.2) to its corresponding output component $Q_t^{(j)}$, $j = 1,2,, \ldots$ J. In Eq. (3.2) the current and recent rainfall values are multiplied by the non-linear response ordinates $U_{i,k}$, while the antecedent rainfall values are multiplied by the linear response function ordinate U_i . Thus, the prompt flows (i.e. the immediate and moderately delayed flows) and the delayed flows are differently related with the corresponding rainfall values.
- (2) The outflow component $Q_t^{(i)}$ in Eq. (3.3) from different sub-catchments are linearly additive (Liang and Nash, 1988) as :

$$Q_{t} = Q_{t}^{(1)} + Q_{t}^{(2)} + \dots + Q_{t}^{(j)}$$
(3.4)

We may have to calibrate the model on a number of separate data sets of rainfall and corresponding runoff. So, Eq. (3.3) is re-written for calibrating the model by stacking together all the data-sets under consideration as :

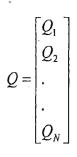
$$Q_{t}^{p} = \sum_{j=1}^{J} \sum_{i=1}^{n(j)} \sum_{k=i}^{n(j)} U_{i,k}^{(j)} P_{t-i+1}^{(j),p} P_{t-k+1}^{(j),p} + \sum_{j=1}^{J} \sum_{i=1}^{l(j)} U_{i+n}^{(j)} P_{t-(i+n)+1}^{(j),p}$$
(3.5)

Where, p = the counter number of the storm – event with $p = 1, 2, \dots$ NN.

The solution of Eq. (3.5) for a calibration series of N discharge values Q_1, Q_2, \dots Q_N can be written in vector / matrix form as

$$O = P^{(1)}U^{(1)} + P^{(2)}U^{(2)} + \dots + P^{(0)}U^{(0)}$$
(3.6)

In the above, N is the total number of observations from the all the storm events used for calibration, placing one immediately after the other to give a long series and Q is an [N, 1] column vector of the runoff calibration series such that .



Thus, for each of the NN data sets, the set of inputs and the outputs are first arranged in the form of Eq. (3.6) and then these storm events are vertically stacked together to form the complete matrix of inputs and the corresponding complete vector of outputs. Hence $P^{(j)}$ is an [N, mm(j)] rainfall matrix of the jth input series, corresponding to the jth sub-catchment area, such that and $U^{(j)}$ is an [mm (j),1] column of the pulse response ordinates corresponding to the jth input series such that :

 $\begin{bmatrix} p_{11}^2 & p_{m}p_{m-1} & \dots & P_{m}p_{m-(n-1)} & p_{11}^2 & P_{m-1}P_{11-2} & \dots & P_{m-1}P_{12-(n-1)} & p_{m-2}^2 & \dots & P_{m-(n-2)}^2 & P_{m-(n-2)}P_{m-(n-1)} & p_{11-(n-1)}^2 & P_{11-(n-1)} & P_{$ $P_{m+1}^{1}P_{m+1}P_{m} \dots P_{m+1}P_{m-n+2} P_{m}^{2} P_{m}P_{m-1} \dots P_{m}P_{m-n+2} P_{m-1}^{2} \dots P_{m-n+3}^{1} P_{m-n+3} P_{m-n+2} P_{m-n+2}^{2} P_{m-n+1} P_{m-n}$ and the second ·• . .. •• .. •• ••• ••• P^(j) ... $\begin{bmatrix} p_{t}^{2} & p_{t}p_{t-1}^{2} & \dots & p_{t}p_{t-(n-1)}^{2} & p_{t-1}^{2} & p_{t-1}p_{t-2}^{2} & \dots & p_{t-1}p_{t-(n-1)}^{2} & p_{t-2}^{2} & \dots & p_{t-(n-2)}^{2} & p_{t-(n-2)}^{2} & p_{t-(n-2)}^{2} & p_{t-(n-1)}^{2} & p_{t-(n-1)}^$ P. ... $P_{1-(i+1)+1}$.. [.] ••••• $P_{N}P_{N+1} = \dots = P_{N}P_{N+(n-1)} = P_{N+1}^{2} = P_{N+1}P_{N+2} = \dots = P_{N+1}P_{N+(n-1)} = P_{N+(n-1)}^{2} = P_{N+(n-1)}P_{N+(n-1)} = P_{N+(n-1)}^{2} = P_{N+(n-1)}P_{N+(n-1)} = P_{N+(n-1)}P_{$ P_{N-B-L} $P_{N-(l+n)+1}$ P_{N}^{2} Linear input [1 - Columns] Non - linear input [n(n+1)/2 Columns] [For the delayed (For the immediate and moderately delayed response) (ground water) response]

(3.8)

and

$$U^{(j)} = \left[U^{(j)}_{1,1}, U^{(j)}_{1,2}, \dots, U^{(j)}_{1,n}, U^{(j)}_{2,2}, \dots, \dots, U^{(j)}_{n-1,n}, U^{(j)}_{n,n}, U^{(j)}_{n+1}, U^{(j)}_{n+2}, \dots, U^{(j)}_{n+1} \right]^{T}$$
(3.9)

where T denotes the vector transpose.

This vector consists of n(n+1)/2 non-linear and 1 linear response function ordinates. So, U is an (M,1) column vector of

Length
$$M = \sum_{j=1}^{J} mm(j)$$

Equation (3.5) can also be written as

$$Q = PU$$

 $P = [P^{(1)}, P^{(2)}, \dots, P^{(J)}]$ Where, P is an (N, M) matrix such that :

and

Thus, $\{P^T P\}$ called "auto and cross covariances matrix" of the inputs is a [M x M] matrix

$$M = \sum_{j=1}^{J} mm(j)$$
 (3.12)

which plays very important role and U is an (M; 1) column vector obtained by writing each $U^{(j)}$ vector in the sequence of j, as :

$$U = \begin{bmatrix} U^{(1)} \\ U^{(2)} \\ \vdots \\ \vdots \\ U^{(j)} \end{bmatrix}$$
 where, N >> M (3.13)

From Eq. (3.10) we can get the vector U as :

Q = P U

$$\Rightarrow [P^{T}.P]U = P^{T}Q$$
$$\Rightarrow U = [P^{T}P]^{-1}[P^{T}Q]$$

Where, U = the response function of the large catchment.

(3.14)

(3.10)

(3.11)

The solution in Eq. (3.14) above can be obtained from the ordinary least-squares solution, expressed in terms of auto and cross covariances of the input P and the output Q (Nash and Barsi, 1983).

If any of the ordinate values of the above derived response functions contain significant negative ordinates, the slightly more complex method of smoothed least squares also called ridge – regression (Bruen and Dooge, 1984) can be used for derivation of the response functions as positive ordinates.

In the method of smoothed least- squares, the estimate of U of Eq. (3.14) is taken as the solution U of the system of normal least – squares equations given below :

$$\left[\mathbf{P}^{\mathrm{T}} \mathbf{P} + \mathbf{K}\mathbf{I}\right] \mathbf{\hat{U}} = \mathbf{P}^{\mathrm{T}}Q \tag{3.15}$$

Where, K is a positive scalar.

I is an (M x M) unit identity matrix.

In Eq. (3.15), \hat{U} is the biased estimate for U of Eq. (3.14) and the bias is proportional to K. For K equals to zero, this bias is zero and the solution obtained is the same as that of the method of ordinary least squares. This solution also yields estimates of the standard errors of the estimate of \hat{U} (Nash and Barsi, 1983; Bruen and Dooge, 1984).

Standard error of estimates of the response function ordinates can be computed using Eq. (2.66).

The results obtained by different models are compared using the Nash – Sutcliffe efficiency (E^2) using Eq. (2.62) for model evaluation.

AREA OF STUDY

4.1 WARDHA SUB-BASIN

The catchment area of the river Wardha has been considered for the model study.

4.1.1 General

The Wardha is one of the right tributaries of Pranhita river. The Wardha subbasin lies between latitudes 19° 18 N and 21° 58 N and longitudes 77° 20 E and 79° 45 E.

The Wardha river rises at an altitude of about 777 M in the southern slopes of the Dahawadhana peak in Multai Taluk of Betul district of Madhya Pradesh and traverses a total length of 528 km and joins the river Wainganga. From the source, it traverses 42 km in Madhya Pradesh, 16 km along the common boundary between Madhya Pradesh and Maharashtra, 428 km in Maharashtra and 42 km. along the common boundary of Maharashtra and Andhra Pradesh. The important left bank tributaries are the Kar, the Jam, the Wena and the Erai and the right bank tributaries are the Madu, the Bembla and the Penganga. It joins the river Pranhita near Asifabad Taluk of Adilabad district in Andhra Pradesh.

The Penganga being a major tributary of Wardha has been considered as an independent sub-basin. Thus, the Wardha sub-basin comprises of the catchment area of Wardha from its source to its confluence with Wainganga including its tributaries but excluding the catchment area of Penganga. The catchment area of Wardha sub-basin is 24087 km which is 7.7% of the area of Godavari basin. The sub-basin lies in the states of Madhya Pradesh, Maharashtra and Andhra Pradesh.

4.1.2 Topography, Physiography, Geology and Hydrogeology

The Wardha sub-basin is triangular in shape with an average width of about 90 km. The terrain is mountaneous consisting of ridges and valleys covered with forests and the country opens out lower down.

The geological formation in the sub-basin presents various types of rock formations including the older precambrian, Vindhyans, Gondwanas and sediments. Various types of rocks found in the sub-basins are classified under the Gondwanas, the Deccan trap and the Archaean.

Hydro-geological studies have been carried out by the State Ground Water Departments and the Central Ground Water Board in the sub-basin. The studies reveal that in the Vindhyans, Gondwanas, Deccan traps, laterites and alluvium groups, ground water occurrence is noticed. Ground water occurs in the soil cover, weathered mantle and in the highly jointed and fractured zones of the hard rock. In the alluvium, the ground water is found in the basal portion containing gravel and course sand under the water table. The depth of water table varies from 4.5 m to 16.0 m. The existing ground water development in the sub-basin is mainly from open wells and dug-cum-bore wells.

4.1.3 Climate

There are three seasons prevailing in the sub-basin i.e. summer from March to May, monsoon from June to October and winter from November to February. There are IMD observatories at Betul, Amaravati, Chanda, Nagpur and Yeotmal located in and adjacent to the sub-basin. There are 16 rain gauge stations in and adjacent to the sub-basin catchment. The average annual rainfall for the entire sub-basin catchment is 1000 mm (approx.).

4.1.3.1 Rainfall

The Wardha sub-basin experiences only the south-west monsoon and it is from early June to end of October. The rainfall during the non-monsoon months, i.e. November to May is not significant.

4.1.3.2 Temperature

The sub-basin is located entirely in tropical zone. The daily and seasonal variations are high. The climate in general remains dry except in the monsoon months. The sub-basin experiences uniformly high maximum temperature of 40° C and above during summer and low minimum temperature of about 10° C during December.

4.1.3.3 Humidity

Humidity in the sub-basin is more during the monsoon and comparatively less during the non-monsoon period. The minimum humidity is generally recorded during April and the maximum during August. The climate remains dry for about 7 months in the year from November to May.

4.1.3.4 Wind Speed

Winds are generally light to moderate with increasing speeds in the later part of summer and during monsoon. The sub-basin is influenced by winds from the south-east during summer and south-west during the monsoon.

4.1.3.5 Cloud Amount

Generally the sky appears clear or lightly clouded in the non-monsoon period. The intensity of cloud amounts is more during the south-west monsoon season.

4.1.4 Soils and Land Use

4.1.4.1 Soils

The soils of the Wardha sub-basin are broadly divided into three groups as shown in Table 4.1.

Table 4.1

Soils in the Wardha Sub-basin

Area under each type of soil (km ²)	
16700	
289	
7098	
24087	

4.1.4.2 Land Use

The cultivable area was maximum in the year 1991-92 at 1592964 ha. The land use figures for the year 1991-92 are given in Table 4.2.

Table 4.2

Land Use Figures for the Year 1991-92 of the Wardha Sub-Basin

Land use	Area (ha)	Percentage to sub-basin area
(i) Geographical area	2408700	100.00
(ii) Forest	507133	21.05
(iii) Barren land	76872	3.19
(iv) Land under non-agrl.use	116817	4.85
(v) Culturable waste	92641	3.85
(vi) Permanent pastures	114914	4.77
(vii) Land under misc.crops &	15045	0.63
trees		
(viii)Current fallows	61292	2.54
(ix) Other follows	91356	3.79
(x) Net area sown	1332630	55.33
(xi) Area sown more than	69847	2.90
once		
(xii) Gross sown area	1402477	58.23
(xiii)Cultivable area	1592964	66.14

HYDROLOGICAL DATA

5.1 GENERAL

The drainage area of the Wardha river of the Godavari basin has been selected for flow forecasting during monsoon periods by the present model study.

There is a G & D site located at Ghugus in Maharashtra, India being maintained by the Central Water Commission (C.W.C.), Government of India. The catchment area of the Wardha river upto Ghugus site which forms the head water catchment of the river is 19975 km² which covers nearly 83% of the total catchment area of the sub-basin (24087 km²). Figure 5.1 shows the drainage pattern in the catchment.

There are 14 raingauge stations considered in and around the catchment upto Ghugus site. They are Atner, Multai, Barud (Warud) Chandur Railway, Morsi, Katol, Nagpur, Yeotmal, Arvi, Hinganghat, Kharanjha, Wardha, Chandrapur and Warora as shown in Fig. 5.1. The catchment is gauged by taking hydrological observations i.e. gauge and discharge observations on the river Wardha at Ghugus site by the Upper Godavari Division of the Central Water Commission (Southern Zone) under Godavari Circle, situated in Hyderabad, A.P. Daily rainfall and daily discharges are used in the present study. Rainfall in the catchment is observed using both the automatic recording as well as the non-recording raingauges. The rainfall data under study has been collected from the India Meteorological Department, Government of India, Additional Director General of Meteorology (Research) situated in Pune, M.S.

5.2 HYDROLOGICAL DATA

Data used in the present model study consist of daily river discharge and corresponding rainfall in the catchment which contributed flow to Ghugus G& D site. The recorded daily rainfall data for 14 RGS and the observed daily discharge data of Wardha river at Ghugus G & D site are collected from the respective organizations for the period from 1985-1996.

Since the present study is for flow forecasting during monsoon flood events, the observed rainfall, runoff data are analysed in the light of above study. Initially, nineteen flood storm events which occurred during monsoon season from 1985-1996 were identified based on observed hydrographs. Out of them, only twelve flood storm events were selected for this study for which both rainfall as well as runoff data are available concurrently. These storms occurred during the period from 1985 to 1996. The first eight of these events were used for calibration of the model and the data of the remaining four events were used for model verification. The dates of the storm events are given in Table 5.1.

The catchment representation was done in three ways. Firstly, the whole catchment was considered as a single unit of model input and the average rainfall was computed by the Thiessen Polygon method. Secondly, the catchment was divided into two and then into three sub-areas as shown in Figs. 5.2 and 5.3 respectively and taken as two inputs and three inputs scenarios of the model. For each sub-area, the Thiessen average rainfall was determined to form the input functions to the model. The sub-area demarcation as exhibited in Figs. 5.2 and 5.3 was based upon the hydro-physio-graphical homogeneity indicated by vegetation, slope, soil type and the long-term rainfall isohyetal maps for the catchment.

The rainfall-runoff data used in the present study are listed in the Appendix-1.

Table 5.1

Dates of the Selected Storm Events

Catchment	Storm No.	Period of Storm	Duration (Days)
Wardha upto		Calibration Period	
Ghugus (19975 km ²)	1.	19.06.85 to 03.07.85	15
· ·	2.	01.08.85 to 20.08.85	20
	.3.	02.08.86 to 27.08.86	26
	4.	01.07.88 to 11.08.88	42
• •	5.	15.08.88 to 28.09.88	45
	6.	11.08.89 to 14.09.89	35
	7.	08.06.90 to 30.06.90	23
	8.	12.07.90 to 31.07.90	20
			Total 226
		Verification Period	
i .	1.	04.08.90 to 21.09.90	49
	2.	20.07.93 to 17.08.93	28
	3.	13.07.95 to 31.07.95	19
	4.	24.08.95 to 14.09.95	22
			Fotal 118

Note:	Alternative Study	Scenario	Area of sub- Catchment(Km ²)	Area of Total Catchment (Km ²)
;	Alternative - I	One input	19975	19975
?	Alternative - II	Two inputs	6910 13065	19975
-	Alternative - III	Three inputs	6910 7534 5531	19975

RESULTS AND DISCUSSIONS

6.1 GENERAL

The daily rainfall and runoff data of the Wardha catchment are used in the present study. The total rainfalls have been considered as the inputs and the total runoff as the output as against to the use of effective rainfall and direct runoff as input and output respectively used in conventional unit hydrograph method. The catchment area upto Ghugus gauging site located on the Wardha river was considered. This catchment area falls in the Maharashtra state of India and the gauging site has been maintaining by the Central Water Commission, Government of India.

Among the identified storm events, twelve storms are selected for use in the model study of flow forecasting of Wardha river. These storms occurred in the monsoon period during 1985 to 1996. Out of these twelve storms, first eight are selected for calibration purpose and the remaining four are used for the purpose of forecasting (verification). A computer program for deriving the response functions for any number of inputs and single output based on ordinary and smoothed least squares technique has been developed and used in the present study. The Nash-Sutcliffe efficiency for the models both in calibration as well as verification period has been computed.

The study has been done by considering one, two and three rainfall inputs to the model, although any number of rainfall inputs may be used.

The study has been carried out using the following approaches viz.

- (i) Linear approach : for single input and multiple inputs
- (ii) Non-linear approach : for single and multiple inputs.Results obtained are presented herein.

6.2 DISCUSSION ON RESULTS OBTAINED BY LINEAR APPROACH

The linear approach for single and multiple rainfall inputs has been studied for different memory lengths (m) varying from m = 4 to m = 10. With an increase in value of m the efficiency was increased from about 64% to 73% in linear – single input case and it increased from about 66% to 77% in case of linear – three inputs case. It indicates that when m = 10 the increase in the efficiency of linear approach from single input to three – inputs was only marginal from 73% to 77% i.e. 4%. The ordinates of the response function and the other results are presented in the Table 6.1 and 6.2 respectively. It is observed that three inputs (linear) case has given better results than lumped linear single input case for every value of m selected as above. However some of the ordinate values are negative and the same could not be smoothed by the method ridge regression.

6.3 NON - LINEAR APPROACH

6.3.1 Calibration Period

6.3.1.1 Single Rainfall Input

Average rainfall occurring on the whole catchment of the Wardha upto Ghugus is used as the model input. First eight of the selected storms have been used for calibration purpose. The Thiessen weighted averages of observed rainfall values at fourteen rain gauge stations as depicted in Fig. 5.1 are taken as one input. For different memory lengths of the catchment 'm' and for different values of Linear (l) and non-linear (n) memories, the Response Function Ordinates (R.F.O.) are derived. For these derived ordinates, the corresponding standard error (S_{err}) are also calculated. Nash-Sutchliffe efficiency (E^2) was also computed. The results obtained for single input case are presented in the Table 6.3. From the Table 6.3, it is considered that when m = 10 and n = 3, 1 = 7, the efficiency (E^2) is maximum. However some of the ordinate values are still negative.

From the Table 6.3, by comparing efficiency, standard error for different memory lengths of catchment, it is considered that m = 10 and n = 3, l = 7 holds good for the present catchment. Although the efficiency is still higher in case m = 10 and n = 1, l = 9, it is not considered as the appropriate response function as it contains more number of

negative ordinates. The estimated discharges are computed based on these derived response functions and compared graphically with the corresponding observed discharges as shown in Figs. 6.1 to 6.12. A discussion on the graphical comparison is presented later in subsequent paragraphs.

6.3.1.2 Two rainfall inputs

In this case, the whole catchment is divided into two sub-catchments as shown in Fig. 5.2. The weighted averages of rainfall values of each sub-catchment are calculated by the Thiessen polygon method and used in the model alongwith the observed discharge at Ghugus gauging site for finding out the response functions combined for the two sub-catchments. For different values of m and for different values of n and 1, R.F.O.s and S_{err} are calculated and present in Table 6.4.

As shown in Table 6.4, comparing efficiency for different memory lengths 'm' and n and l, a set of m = 10, n = 3, l = 7 was considered as the appropriate one for deriving R.F.O.s and further used for verification period. These response functions are convoluted with the rainfall values for calibration period in two sub-catchments to compute the discharges. The above computed discharges are graphically compared with the corresponding observed values as shown in Figs. 6.13 to 6.24. A discussion on the graphical comparison is presented later in subsequent paragraphs.

6.3.1.3 Three rainfall inputs

In this case, the catchment is divided into three sub-catchments as shown in Fig. 5.3. The weighted average of rainfall values over each sub-catchment are computed by the Thiessen polygen method and used individually as the inputs from their respective sub-catchments. The response functions for the three sub-catchments are computed for different 'm' values and different 'n' and 'l' values. The R.F.O. alongwith the associated efficiency are presented in the Table 6.5.Comparing the R.F.Os. and the efficiencies among various memory lengths, the values m = 10 and n = 3, l = 7 was adopted and later used for verification purpose.

Also, it was investigated that whether different value of m could be chosen for different sub-catchments, as it is expected that sub-catchment which is nearer to the catchment outlet may not contribute the flow to it for long time. These trials revealed that efficiency (E^2) is maximum when m = 10 for all the sub-catchments. It is therefore thought that the sub-catchments those are near to the river gauging site are comparatively flatter in slope, and hence it will contribute to the river flow for a longer period than as expected above.

The finally selected R.F.Os are convoluted with the corresponding rainfall values for the calibration period in the three sub-catchments and the discharges at Ghugus are estimated. The graphical comparison between the observed and computed discharges is shown in Figs. 6.25 to 6.36 and a discussion on this comparison is presented below.

6.4 DISCUSSION ON RESULTS OBTAINED FOR CALIBRATION PERIOD

The finally adopted R.F.O. values in all the three cases discussed above have the memory length m = 10 with n = 3, and l = 7, although some of the ordinates are negative. Even by using the "smoothed least squares technique", these negative ordinates could not be changed into positive values as discussed already. Comparison of E^2 values for the finally adopted R.F.Os. indicate that efficiency E^2 increases from about 76% to about 84% as the number of rainfall inputs increased from one to three with non-linear approach. However, the increase in E^2 was higher about 5% when rainfall inputs were increased from one to two. But comparatively further increase in number of inputs i.e. for three inputs, the increase in efficiency was only about 2.5%. However, the number of raingauge stations over the catchment especially over 2^{nd} and 3^{rd} sub-catchment areas were not considered to be sufficient and uniformly distributed for making a detailed study of this aspect.

The graphical comparison of observed and computed runoff values and that of variation of rainfall with time are shown in Fig. 6.1 to 6.36 for all the above three scenarios. From these comparative graphs, it is revealed that as the number of inputs are increased, the predictability of model with respect to the higher flows in particular is improved. Nevertheless, some of the segments of flow hydrographs are not very-well

predicted by the present method. However, use of effective rainfall (i.e. total rainfall – evapotranspiration) instead of the total rainfall would result in better simulation of such data.

6.5 DISCUSSION ON COMPARATIVE STUDY OF LINEAR AND NON-LINEAR APPROACHES

The efficiency (E^2) of both linear and Nonlinear approaches as obtained above for different memory lengths (m) varying from 4 to 10 are presented in Table 6.6. From this table, it is noticed that for every value of m, linear multiple- input approach has given better results than that of lumped linear single input case. When m=10, the efficiency was increased to about 77% in linear multiple- input approach when compared with lumped linear single input case ($E^2 = 73\%$).

The efficiency of about 76% was obtained in nonlinear single input case (When m=10) which is almost equal to the efficiency as obtained in linear multiple input case.

In the case of nonlinear multiple- input case, when m=10, an efficiency (E^2) of about 84% was obtained i.e. a further improvement of about 7% in the estimation of flows from linear multiple-input to nonlinear- multiple approach. On an overall scenario, the efficiency was increased from about 73% to about 84% in case of nonlinear multiple-input approach when compared with lumped linear single rainfall input system.

Hence from the above all studies, it can be concluded that nonlinear approach of multiple-input system gives good results of estimated flows particularly in predicting peak flows.

6.6 DISCUSSION ABOUT THE NEGATIVE ORDINATES OF THE RESPONSE FUNCTIONS AND USE OF CONCEPT OF RIDGE REGRESSION (SMOOTHED LEAST SQUARES ESTIMATE)

In the present study, the memory length of catchment, m was determined by trial and error, by varying value m = 4 to m = 10 both by linear and non-linear approaches

with single and multiple inputs. It is noticed from Table 6.1 to Table 6.5 that the negative ordinates were obtained almost in all data sets used in the above approaches. The range of negative ordinates varied from 12% to 40% of total number of ordinates. So, it is felt that the estimation of the ordinates of non-parametric unit-hydrographs from the sample data is very sensitive to the interrelationships existing among the observed input series. The least squares estimate is a good one if P^TP is nearly a unit matrix. If P^TP is not nearly a unit matrix, the least squares estimates are sensitive to errors which was occurred in the present study.

To tackle the above problem, the concept of ridge regression which also produces least squares estimate with some bias was used in the present case. Only in some cases, the negative ordinates could be eliminated. It was particularly possible when the number of negative ordinates are upto about 20% of the total number of ordinates or less. So, from the above, it is observed that the concept of ridge regression was helpful in eliminating the negative ordinates of the response function only for limited cases.

6.7 VERIFICATION (FORECASTING) PERIOD

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Data for four storm events which were not used previously are used for flow forecasting (verification) of the present method with non-linear approach and one input, two inputs and three inputs. For each input case, the weighted average rainfall values were computed for Wardha catchment upto Ghugus.

6.7.1 Discussion on Results Obtained for Verification Period

The response function ordinates in case of one input which have m = 10, n = 3, l = 7 are convoluted with the corresponding rainfall values to compute the estimated flows. The efficiency (E²) of 70% and 85% was obtained in the two storm events (i.e. storm No. 1 & 4 of verification period). However the efficiency in the other two storm events was smaller due to inaccurate and unreliable data sets. Graphical comparison of these results are shown in Figs.6.37 to 6.40.

6.8 SUMMARY

The problem of floods and their computation is one of the main and most complex problems facing by the hydrologists. The optimal development of Water Resources depends to a considerable extent on flood estimation and flood flow control.

A large number of methods have been proposed to predict magnitude of flood resulting due to a storm over a catchment based on response functions method such as unit hydrograph. But, uniformity of effective rainfall over the entire catchment is one of the assumptions followed in the derivation of response functions by unit-hydrograph theory. We know that the occurrence of uniform rainfall as expected is seldom true in case of large catchments. To account for the non-uniformity of rainfall and the catchment heterogenieties to a maximum extent, the whole catchment is divided into three sub-areas to treat the rainfall of each sub-catchment as separate lumped inputs. In the present study, the total rainfalls have been considered as the inputs and the total runoff as the output as against to the use of effective rainfall and direct runoff as input and output respectively used in conventional unit hydrograph method. A multiple-input single-output non-linear model was formulated and used in this study. This method was tested for the data from Wardha catchment upto Ghugus.

The response functions were derived for one, two and three rainfall inputs from the data used in calibration period. Then, these response functions were convoled with rainfall for forecasting the flows during storm events, which were not selected for calibration.

The results obtained herein indicated that as the number of inputs are increased, the results are improved very satisfactorily. At the same time, it is to state that accurate and reliable data for flood estimation by hydrologic analysis is very essential. It is expected that the method proposed herein would be more useful particularly when nonuniformity in spatial distribution of rainfall is significant.

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Table 6.1 Results	Obtained from	Single Input	(Linear Approach))
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Memory	R.F. value	E ² %
length of the		
catchment (m)		
1	2	3
4	25.4505	64.01
	44.2063	
	21.4628	
	14.6001	
	- -	
5	24.6978	64.55
	44.0204	
	22.2629	
	10.3235	
	6.7803	
	•	
6	24.7514	65.48
	42.6993	
	22.4098	
	10.9174	
	2.9756	
	6.4520	·
7	25.3372	65.48
	42.7918	
	22.1058	
	10.8845	
	2.9890	
	5.1551	
	2.1126	
-	· · · · · · · · · · · · · · · · · · ·	

Contd-/ Table 6.1

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Contd-/ Table 6.1

Memory	R.F. value	E ² %
Memory length of the	R.r. value	L 70
catchment (m)		
	2	
		3
ð	26.4670	66.55
	43.4147	
	22.4331	
ĺ	10.2347	
	2.5784	
	5.1603	
	-0.0707	
	3.5783	
9	30.9876	69.90
	45.3484	
	21.7319	
	10.2430	
·	1.2872	
	5.1518	
	-0.4083	
	3.3384	
	-0.4597	
10	31.5628	73.29
	48.6979	
	23.3082	
	9.2222	
	0.9325	
	3.2491	
	-0.1329	
	3.4201	
	-2.5098	}
	3.0302	

Memory length of	R.F.O	E ² %
the catchment (m)		
1	2	3
4	13.7542	66.29
	11.9422	
	-7.2568	
	-1.7310	
	11.1355	
	8.6874	
	5.6441	
	5.6559	
	0.8094	
	22.0769	
	17.2362	
	8.9521	
7	10.7223	69.45
	9.2388	
	-7.8182	
	0.3146	
	3.9792	
	4.5125	
	2.5538	
	2.3330	
	16.3319	
	9.9966	
	-0.2591	
	1.7109	
	-14.5930	· .
	-4.5843	
	1.8753	
	-3.6105	
	22.5271	
	20.9791	
	9.2960	
	14.9337	
· ·	6.6743	
	-2.5835	

 Table 6.2 Results Obtained from Three - Inputs (Linear Approach)

Contd./ table 6.2

Contd./ table 6.2

Memory length of	R.F.O	E ² %
the catchment (m)		
1	2	3
8	7.3513	70.99
	9.7227	
	-8.8117	
	3.3661	
· · · ·	5.4894	
	5.8408	
· .	0.5461	
	9.9980	
		•
	23.7465	
	11.9407	
	3.7358	
	1.0932	
	-17.8711	
	-5.2239	
	2.5651	
	-1.1031	· · · ·
	-8.5267	
	21.4409	
	16.9374	
	8.0526	, i
	16.6427	
	7.4265	
	-3.8177	
	-2.0475	

Contd./ Table 6.2

Contd./ Table 6.2

Memory length of	R.F.O	$E^2\%$
the catchment (m)	-	
1	2	3
9	11.8347	73.76
	6.0875	
	-12.5071	
	3.5809	
	6.8388	
	.4.4121	
	2.0314	
	11.8239	
	11.4596	
	20.1225	
	21.1310	
	7.2287	
	4.8425	
	-16.9641	
	-8.0649	
	0.7790	
	-0.5694	
	-110750	
	-5.0580	
	14.8934	
	15.9637	
	2.8946	
	14.9578	
	11.1535	
	-3.3051	
	-1.8217	
	1.6423	•

Contd./Table 6.2

Contd./Table 6.2

Memory length of	R.F.O	E ² %
the catchment (m)		
1	2	3
10	7.7341	77.02
	11.2430	,,
	-20.0537	
	1.9171	
	4.7488	
	4.9778	
	3.1951	
	14.0443	
	11.1076	
	13.4289	
	23.4944	
	20.3149	
	18.2787	
	9.2252	
	-12.4428	
	-8.3089	
	-3.3410	
	-1.3473	
	-11.3863	
	-2.4667	
	-4.8650	
	15.4263	
	8.8970	
	-0.0595	
	9.5258	
	11.1218	
	-0.5980	
	-0.5335	
	1.6339	
	-4.9290	

Note ----- Demarcation line for the response function ordinates of different sub-catchments.

Memory length of	Non-linear part	Linear	R.F.O.	Efficiency
the catchment		part		E ² %
(m)	(n)	(1)		
1	2	3	4	5
•			0.4189	
4	1	3	47.8086	67.18
			20.1671	
			17.6580	
4	2	2	0.6035	
			-0.2702	
			0.6720	64.57
			31.2628	
			17.7385	
			0.4155	
			45.7900	
			20.1253	
. 7	1	6	14.3283	68.90
			1.6910	
			7.6017	
			2.2961	
			0.5788	
	· _		-0.2613	
			0.6451	
. 7	2	5	30.1028	68.06
	· · · · · · · · · · · · · · · · · · ·		9.7260	· .
			7.7408	
		~	.6.7604	
			5.9773	
			0.3418	
			-0.1174	
			0.8554	
			0.4953	
7	3	4	0.1964	68.99
			0.2914	
			16.4161	1
			5.9528	
			10.2522	
			6.6218	

Table 6.3 : Results Obtained from Single Input (Non-Linear Approach)

Contd/---Table 6.3

Contd/-:Table 6.3

		· · ·	·	,
Memory length of	Non-linear part	Linear	R.F.O.	Efficiency
the catchment		part		$E^2\%$
(m)	<u>(n)</u>	(l)		
1	2	3	4	5
	-		0.4423	.[
			53.7335	
		ſ	19.8818	
			13.7491	
10	1	9	-0.5781	75.80
			5.9427	
			-0.5546	
			3.2287	· ·
1			-2.2170	
			5.1725	
· · · ·			0.5524	
			0.5534	
		-	-0.0920	
			0.6327	
10	2	0	32.4088	
10	2	8	7.7520	73.09
			6.9764	
			4.7014	
			3.6042	
			2.5299	
			-2.0839	
			7.4499	
			0.3291	
			0.2296	
			0.5030	
		ſ	0.3254	} 1
			0.5524	
10	3	7	0.2063	73.59
			16.9234	
			3.2803	
			10.4213	
	-		1.4214	
		•	5.6665	
			-3.1757	
		ĺ	8.6150	

Memory length of	Non-linear part	Linear	R.F.O.	Efficiency
the catchment		part		E ² %
(m)	(n)	(1)		
1	2	3	4	5
	•		0.3517	
			15.5108	
			-3.7870	
			2.1465	
4	1	3		68.30
			0.1907	
			29.2466	
			20.5684	
			14.6145	[
			0.4465	· · · ·
			-0.3362	
			0.6462	
			8.9681	
			9.6019	
4	2	2		66.58
· · ·		-	0.2986	
			-0.0925	
			0.2815	
			16.9607	
			10.4475	
			0.3897	
			16.0507	
			-2.7069	
			-1.0761	
			3.1957	
			7.1874	
7	1	6	8.8774	70.51
		Ū	0.0771	/ 010 1
			0.1821	
			25.6707	
			20.1550	
			12.9177	
			1.4672	
			1.5462	
			-3.5900	
	· · · · · · · · · · · · · · · · · · ·		-3.3900	

Table 6.4 : Results Obtained from Two Inputs (Non-Linear Approach)

Contd/--Table 6.4

Contd/--Table 6.4

Memory length of	Non-linear part	Linear	R.F.O.	Efficiency
the catchment		part		E ² %
(m)	(n)	<u>(l)</u>		
1	2	3	4	5
			0.2716	
•			-0.1943	
			0.6445	
			9.6677	
			4.9644	
<i>,</i>			9.3949	
			14.7326	
			19.5830	
7.	· 2	5		71.60
			0.3624	
			-0.2312	· ·
·			0.3060	
			13.3117	· ·
			9.0472	
			-0.5192	· ·
			-1.2662	
			-9.6457	
	. 2		0.1757	
			-0.3190	
			1.4931	
			0.4605	
			0.2208	
			0.1653	
		,	9.1820	
			12.9697	
			14.3048	
7	3	['] 4	23.4328	73.31
-			0.2793	
			-0.2602	
			0.3512	
			0.4214	
			-0.2469	
			0.1813	
			6.4655	
			-2.6156	
			-0.8284	
			-10.4600	

Contd/--Table 6.4

Contd/--Table 6.4

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Memory length of	Non-linear part	Linear	R.F.O.	Efficiency $E^2\%$
the catchment		part		E %
(m)	(n)	<u>(l)</u>		
1	2	3	4	5
			0.3723	
			18.5801	
			-3.1521	
			0.3088	
			4.2268	
			7.1327	
			6.8178	
			7.5862	
8	1	7	0.1771	71.20
			25.4412	
			20.0258	
			11.7138	
			0.4574	
			1.9113	
			-3.8631	
			-2.1295	
			0.2489	
			-0.1517	
			0.7998	
			9.8278	
			6.5938	
			11.2756	
			15.3223	
			18.6075	
8	2	6	10.6640	72.81
			0.4137	
			-0.3789	
			0.3116	
			11.1392	
			8.2214	
			-2.3322	
			-0.7993	
			-10.2812	
			-4.6829	

Contd/-- Table 6.4

Memory length of the catchment	Non-linear part	Lincor part		
/ 、 I	-	Linear part	R.F.O. '	Efficiency E ² %
(m)	(n)	(1)		
1	2	(l) 3	4	5
8	3	5	$\begin{array}{r} 4\\ 0.1893\\ -0.4201\\ 1.4153\\ 0.6484\\ 0.1052\\ 0.1932\\ 10.1183\\ 14.8752\\ 15.2925\\ 21.7977\\ 14.8270\\ \hline \\ 0.3436\\ -0.3909\\ 0.2607\\ 0.4691\\ -0.3040\\ 0.1837\\ 5.0949\\ -4.1817\\ \end{array}$	74.22
. 10	I	9	-4.1817 -0.7633 -10.5344 -7.3065 0.4884 21.7495 -5.9322 2.0862 4.1427 7.9546 8.6575 6.8922 6.2148 19.1010 0.1786 26.9284 19.1479 10.7268 -2.0716 -0.1101 -4.5447 -0.1362 -6.2562 -8.5667	78.59

Contd/-- Table 6.4

Contd/--Table 6.4

Memory length of the catchment (m)	Non-linear part (n)	Linear part	R.F.O.	Efficiency E ² %
1	2	(1)	4	5
1	4		1.4356	
			-2.5897	
			1.2244	
			8.3096	
			7.1445	
			10.4084	
			18.5809	
			11.4993	
			11.3132	
	•		7.0434	
			14.5450	
10	2	8	-0.1439	80.66
			0.8381	
			0.1796	
			10.3119	
			9.2064	
			-5.7256	
		1	-2.4992	
			-8.6364	
			-1.6602	
			-8.1539	
			-3.8606	
			1.3969	
			-2.5976	
	•		1.0241	
			1.3607	
			-0.4365	
		1	0.2952	
			12.2028	
			12.8773	
			19.2431	
			14.8072	
			12.7625	
10	3	7	7.6906	81.23
			15.8261	
			-0.2535	
		ł l	0.8999	
			0.2237	
			0.0215	
		{	0.3153	
			0.0280	
			6.1560	
			-6.5000	
			-2.7896	
			-9.4257	
			-2.6958	
			-8.6585	
	n line for the respo		-4.3467	

Note : ---- Demarcation line for the response function ordinates of different sub-catchments.

Memory length of the catchment (m)	Non-linear part (n)	Linear part (l`)	R.F.O.	Efficiency E ² %
1	2	(1')	4	5
			0.4001	
			18.8690	
			-3.6121	
			2.2719	
	-			
4	1	3 ·	.0.1791	69.24
			4.3417	
			10.4434	
			6.3415	
			0.0104	
			23.0695	
			9.3007	
			7.6703	
	·		0.5292	
			-0.2919	
		ĺ	0.7304	
			11.8417	
			8.9089	
		.*		
			0.2559	(0.00
4	2		-0.5295	68.32
4	2	2	0.1701	
			0.7579	
			5.1884	
			-0.0343	
			0.4566	
			0.0753	
			13.3266	
			4.5595	
			0.3996	
			14.9747	
			-3.4845	
			5.2241	
			7.3784	
			9.7150	
			5.1405	
			0.2087	
			5.3946	
			4.8721	
7	1	6	2.4169	73.06
			-19.3473	
	,		-5.3907	
			-0.0641	- •
			0.0207	
			-0.0397 22.9929	
			11.8861	
			8.1980	-
			16.5333	
			5.6739	
		1 1	-2.8380	

Table 6.5 : Results Obtained from Three Inputs (Non-Linear Approach)

Contd/-Table 6.5

Contd/-Table 6.5

Memory length of the	Non-linear part	Linear part	R.F.O.	Efficiency E ² %
catchment (m)	(n)	(1)	4	5
l	2	3	0.2499	
			-0.1047	
			-0.5907	
			9.3109	
			7.2340	
			16.5036	
			18.3574	
			13.4057	
			0.3279	
			-0.4118	
7	2	5	0.2003	74.48
			-1.5209	
			3.2932	
			-17.4266	
1			-13.0971	
			-3.9469	
			-0.0852	
			0.3683	
			0.0867	
			14.0625	
			2.5532	
			13.8934 8.2446	
		<u> </u>	-2.8807	
			0.4996	
			-0.9245	
			2.1694	
			0.8355	
			-0.5297	
			0.2338	
			15.1031	
			17.3487	
			22.2005	
			17.5439	
			0.2246	
			-0.4567	
-	2	4	-0.9378	77.44
7	3	4	0.3808	11,-17
			-0.8334	
			0.3408	
			1.5032	
			-14.4985	
			-14.4985	
			-10.9343	
			-0.0772	
		-	-0.1110	
			0.4349	
		1	0.3923	
			0.0384	
			0.5702	
			-0.1324	
		1	2.2352	
			7.6792	
			6.0647	
			-1.2666	
	1	1	1.2000	L

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Contd/-Table 6.5

Memory length of the	Non-linear part	Linear part	R.F.O.	Efficiency
catchment (m)	(n)	(1)		E ² %
1	2	3	4	5
			0.3272	
			16.3181	
		t.	-4.3229	
			8.1530	
			8.5152	
			11.1776	
			3.6223 7.3389	
			7.5569	
			0.2917	
			8.7411	
			8.7590	
8	1	7	2.5434	74.63
O	L	'	-22.3984	
			-5.6352	
			0.6052	
			-0.7496	
		· ·	-0.1047	
			21.3907	
			7.3581	
,			6.8239	
:			17.9321	
			5.9295	
			-4.1014	
			-1.4672	• .
			0.0049	
			0.2328	ſ
1			0.6866	
			9.0999	
			9.6487	
	•	· .	19.3854	
		ļ	20.1377	
			14.0934	
			10.1438	
			0.4883	
	2		-0.6413	76.50
8	2	6	0.2712 1.7036	76.59
			4.3045	
	· · · · · ·		-19.9887	
			-14.4071	
	• •		-3.8652	
			-2.8170	
			2.0170	
		· ·	-0.1200	
			0.3470	
			0.0496	
			9.1269	
{			0.1035	
			14.6483	
			9.0293	
			-3.8357	
I				

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Contd/-Table 6.5

Contd/--Table 6.5

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Contd/-Table 6.5

Memory length of the catchment (m)	Non-linear part (n)	Linear part	R.F.O.	Efficiency E ² %
1	2		4	5
1	1	9	$\begin{array}{r} 4\\ 0.4577\\ 17.1653\\ -14.4601\\ 6.8443\\ 7.9403\\ 9.7185\\ 5.8838\\ 11.6817\\ 9.1436\\ 14.4674\\ \hline \\ \hline \\ 0.2382\\ 16.4776\\ 23.0428\\ 11.5998\\ -16.6169\\ -9.3363\\ -4.0137\\ -2.7651\\ -9.2029\\ -5.0380\\ \hline \\ \hline \\ -0.0528\\ 16.2277\\ -1.0224\\ -2.4293\\ 11.3833\\ 9.3292\\ -1.1594\\ 0.7191\\ 1.0777\\ -2.0489\\ \end{array}$	80.60

Contd/-Table 6.5

Contd/-Table 6.5

Memory length of the	Non-linear part	Linear part	R.F.O.	Efficiency
catchment (m)	(n)	(1)		<u> </u>
1	2	3	4	5
			0.8811	
			-1.8472	
			1.1335	
			-1.1769	
			6.7878	
			16.8260	
			24.0513	
			6.6420	
			16.8618	
			14.4578	
			12.3493	
			0.2367	
			-0.1214	
			0.2574	
			17.7219	
			12.8209	
10	2	8	-11.0722	83.21
10	2	0	-15.6014	02121
			-10.1263	
			-2.3129	
		2	-14.7614	
			-6.5740	
			-0.2473	
			0.6981	
			-0.0141	
			-1.1634	
		1	-5.2133	
			2.3252	
			11.7334	
			1.6723	
		}	-2.0802	
			2.5595	
			1.8690	

Contd-/ Table 6.5

Contd/-Table 6.5

Memory length of the catchment (m)	Non-linear part (n)	Linear part (1)	R.F.O.	Efficiency E ² %
1		3	4	
1	3	(1) 3	$\begin{array}{c} 4\\ 0.9729\\ -2.1570\\ 1.3523\\ 1.2246\\ -0.5890\\ 0.1648\\ 11.1535\\ 17.8657\\ 24.7830\\ 12.2206\\ 18.3807\\ 13.4903\\ 15.0091\\ \hline \\ \hline \\ 0.1434\\ 0.0595\\ -0.0859\\ 0.1833\\ 0.1850\\ 0.2037\\ 12.4787\\ -10.4188\\ -13.9470\\ -11.2531\\ -4.1367\\ -13.0731\\ -7.5259\\ \hline \\ \hline \\ -0.2618\\ 0.6185\\ 0.1805\\ -0.0033\\ -0.0048\\ -0.0871\\ -5.9450\\ 0.6555\\ 9.4082\\ 1.4131\\ -1.9194\\ 1.3201\\ \hline \end{array}$	5

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Note : ----- Demarcation line for the response function ordinates of different sub-catchments.

Efficiency (%)				
Linear Approach		Non-Linear Approach		
1 Input.	3 Inputs	1 Input	2 Inputs	3 Inputs
Table 6.1	Table 6.2	Table 6.3	Table 6.4	Table 6.5
		· · · · · · · · · · · · · · · · · · ·		
2		3		
(1.01	((0)	(7.10	69.20	69.24
64.01	66.29	67.18	08.30	09.24
65.48	69.45	68.99	73.31	77.44
66.55	70.99	-	74.22	78.66
			74.04	00.22
69.90	73.76	-	74.96	80.22
72 20*	77 07	75.80	81.23	83.50**
15.29	11.02	15.00	01.20	05.50
	1 Input Table 6.1 64.01 65.48	1 Input. 3 Inputs Table 6.1 Table 6.2 2 64.01 66.29 65.48 69.45 66.55 70.99 69.90 73.76	Linear Approach Nor 1 Input 3 Inputs 1 Input Table 6.1 Table 6.2 Table 6.3 2 - - 64.01 66.29 67.18 65.48 69.45 68.99 66.55 70.99 - 69.90 73.76 -	Linear Approach Non-Linear Appr 1 Input. 3 Inputs 1 Input 2 Inputs Table 6.1 Table 6.2 Table 6.3 Table 6.4 2 3 3 3 64.01 66.29 67.18 68.30 65.48 69.45 68.99 73.31 66.55 70.99 - 74.22 69.90 73.76 - 74.96

 Table 6.6 Comparative Study of Linear and Non - Linear Approaches

* Efficiency of Lumped Linear Approach

** Efficiency of Nonlinear Three – inputs Approach

Note: Efficiency, E^2 (%) = $\left(\frac{F_d - F_1}{F_d}\right) x 100$

 F_d = sum of squares of difference between Q_{av} and Q_{obs} . F_1 = sum of squares of difference between Q_{cst} and Q_{obs} .

CONCLUSIONS AND SUGGESTIONS

7.1 CONCLUSIONS

- (1) The response function ordinates were derived by trial and error for different memory lengths of the catchment for various conditions viz. One, two and three inputs. Some of the ordinates are negative in sign.
- (2) Ridge regression (smoothed least squares estimate) concept was helpful only to some extent in the process of smoothing the disappear negative values of the response functions.
- (3) From comparative study among alternative approaches used the following conclusions are drawn.
 - (a) Increase in efficiency with linear approach being used and rainfall varied from single input to three inputs is only marginal i.e. from 73% to 77%.
 - (b) Efficiency obtained from non-linear approach by changing the rainfall from single input to three inputs is high i.e. from 76% to 84%.
 - (c) Efficiency obtained through linear approach multiple input when compared with non - linear approach single input is almost same. (i.e. $E^2 =$ 77% and 76% respectively).
 - (d) Efficiency of multiple input by non-linear approach is appreciably higher than that obtained through multiple input linear approach ($E^2 = 77\%$ and 84% respectively).
- (4) Non-linear form of the model produced better efficiency among all the methods studied.
- (5) The efficiency of the model increased with an increase in number of rainfall inputs.
- (6) Graphical comparison of the results indicated that capability of the model to predict the peak flows is increased when number of inputs are increased.

- (7) As some of the storm events selected for present study could not be predicted satisfactorily by using any number of inputs. It is stipulated that --
 - (a) Accurate and reliable data for flood estimation by hydrologic analysis is very essential.
 - (b) Use of effective rainfall (total rainfall evapotranspiration) instead of total rainfall, as input would result in better predictability.
- (8) Value of 'm' for different sub-catchments ----

It is expected in general that the sub-catchment, which is nearer to the catchment outlet, may not contribute the flow for long time. But, trials revealed that it will contribute to the river-flow for a longer period than expected as above.

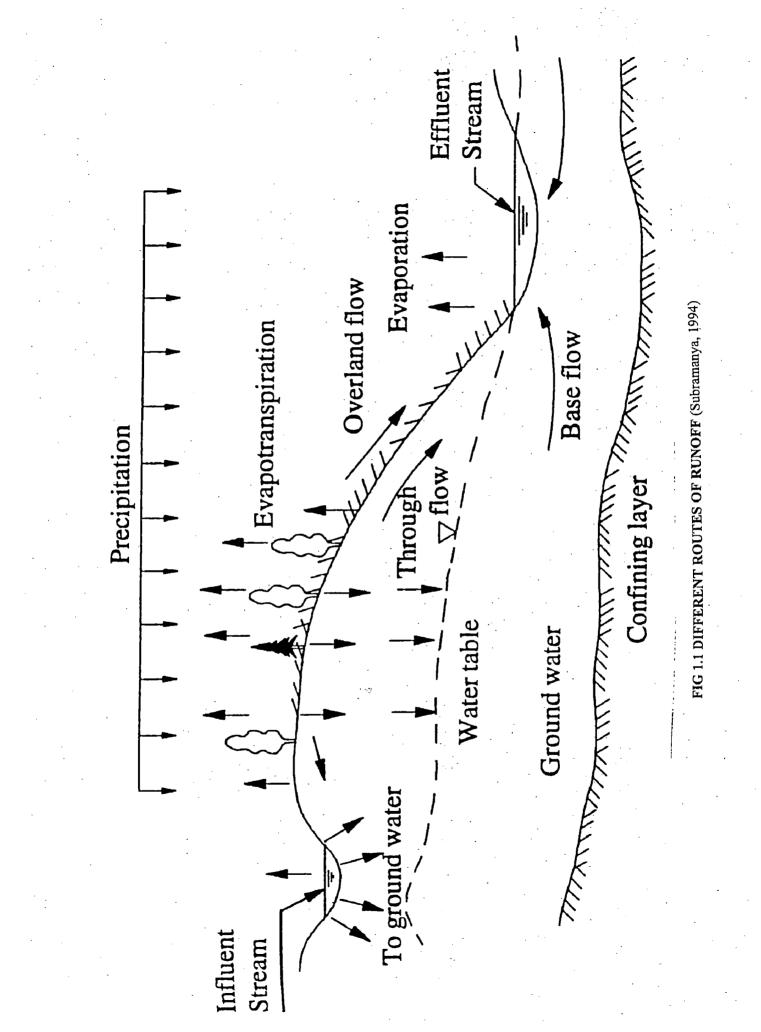
(9) The estimation of response function ordinates of non-parametric type from the sample data is very sensitive to the interrelationships existing among the observed input series.

7.2 SUGGESTIONS

- Use of Bayesian method of unit hydrograph estimation developed by Bhargava (1986) which gives non-oscillatory unit hydrographs with non-negative ordinates, can be studied instead of ridge regression method.
- (2) Determination of Memory : To determine 'm', 'n' and 'l' values by trial and error, it necessiates complete calibration of the model for various values used. So, use of cross-correlation between rainfall and runoff can provide a short cut to this problem.

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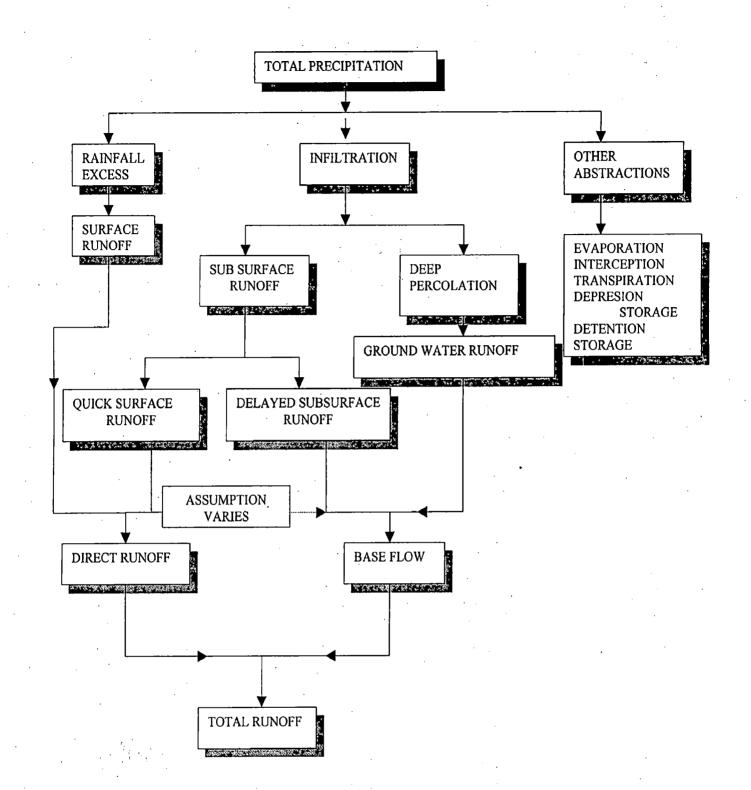
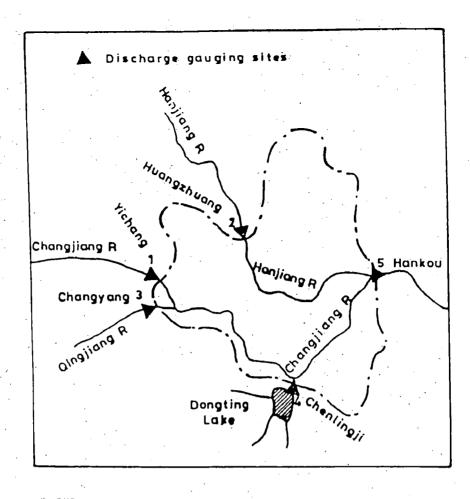


FIG. 2.1 SYSTEMS REPRESENTATION OF CATCHMENT RUNOFF (Chow, 1964).





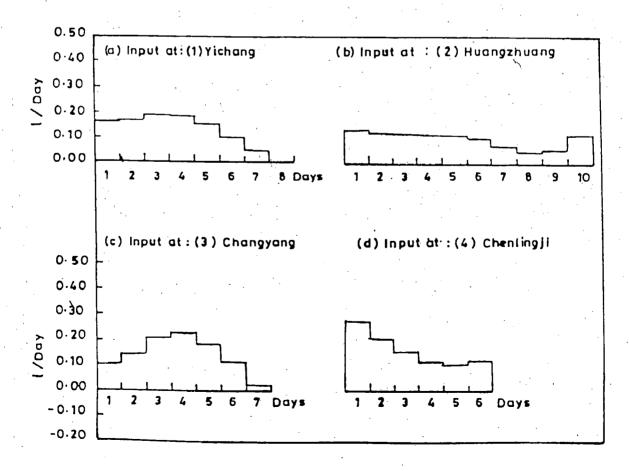


FIG. 2.3 NONPARAMETRIC RESPONSE FUNCTIONS AS OBTAINED BY LIANG (1988) FOR A LINEAR MULTIPLE – INPUT SINGLE – OUTPUT RAINFALL – RUNOFF MODEL

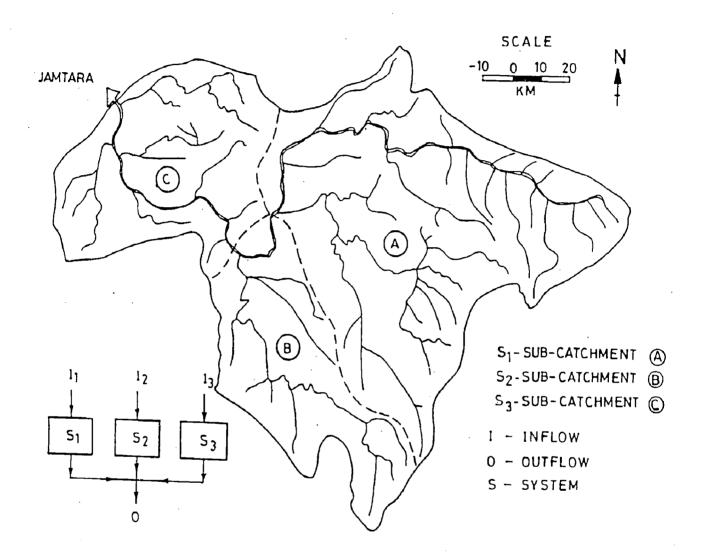


FIG. 2.4 SKETCH OF THE NARMADA CATCHMENT

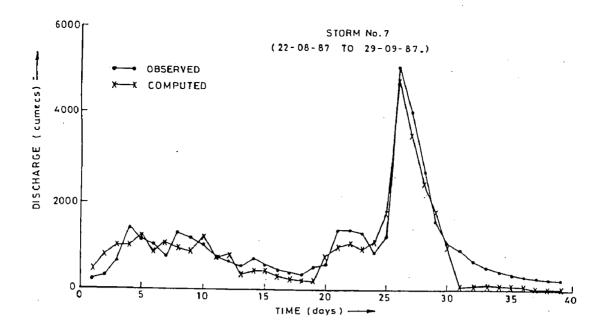


FIG. 2.5 COMPARISON OF COMPUTED AND OBSERVED RUNOFF USING THREE INPUTS AS OBTAINED BY KOTHYARI AND SINGH (1999) FOR A NON – LINEAR MULTIPLE – INPUT SINGLE – OUTPUT RAINFALL – RUNOFF MODEL

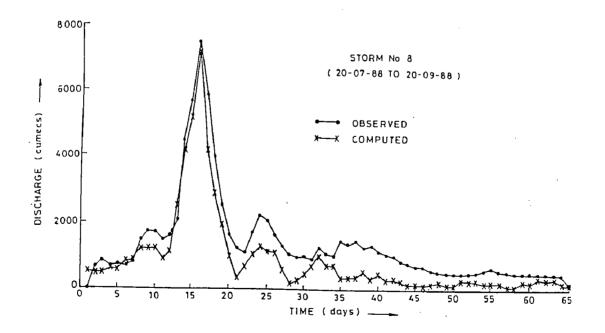


FIG. 2.6 COMPARISON OF COMPUTED AND OBSERVED RUNOFF USING THREE INPUTS AS OBTAINED BY KOTHYARI AND SINGH (1999) FOR A NON – LINEAR MULTIPLE – INPUT SINGLE – OUTPUT RAINFALL – RUNOFF MODEL

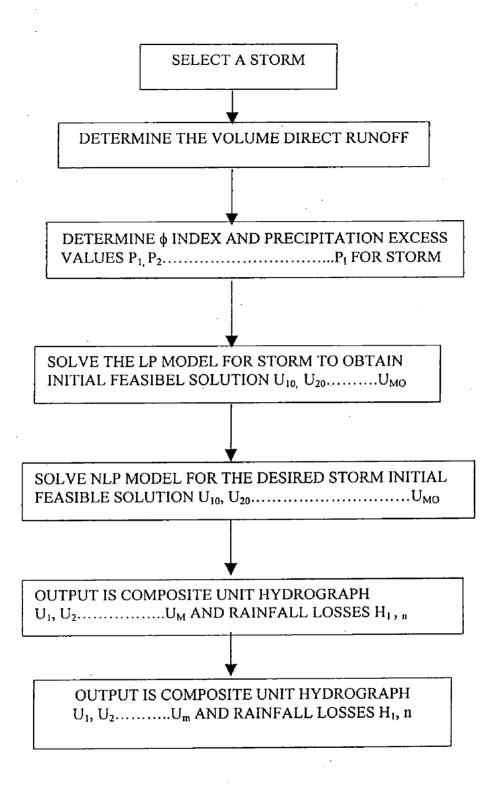
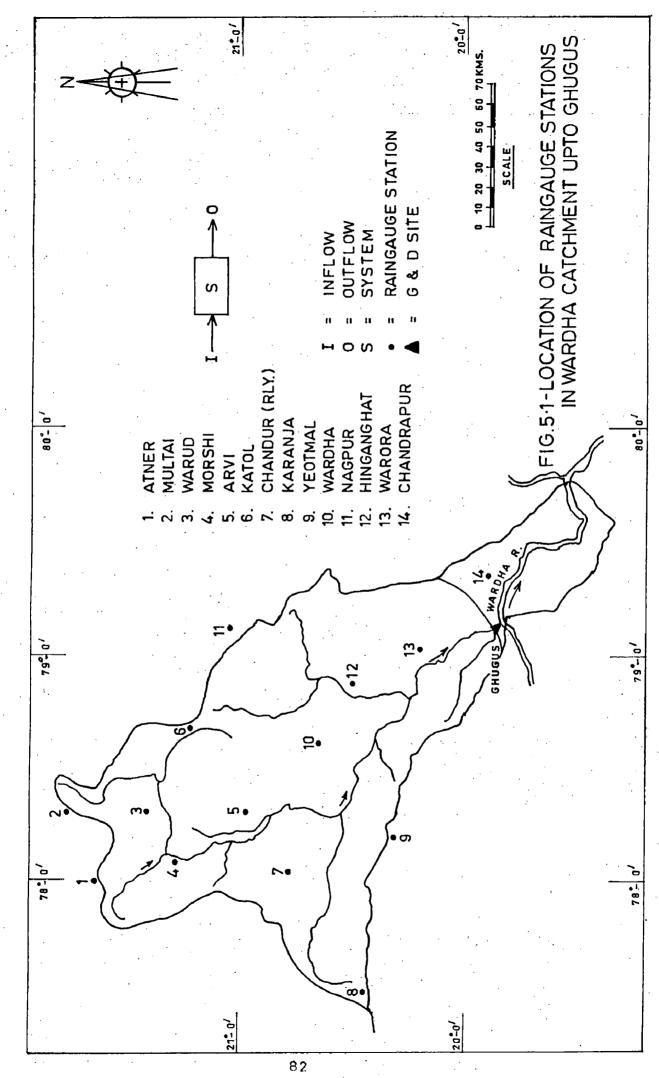
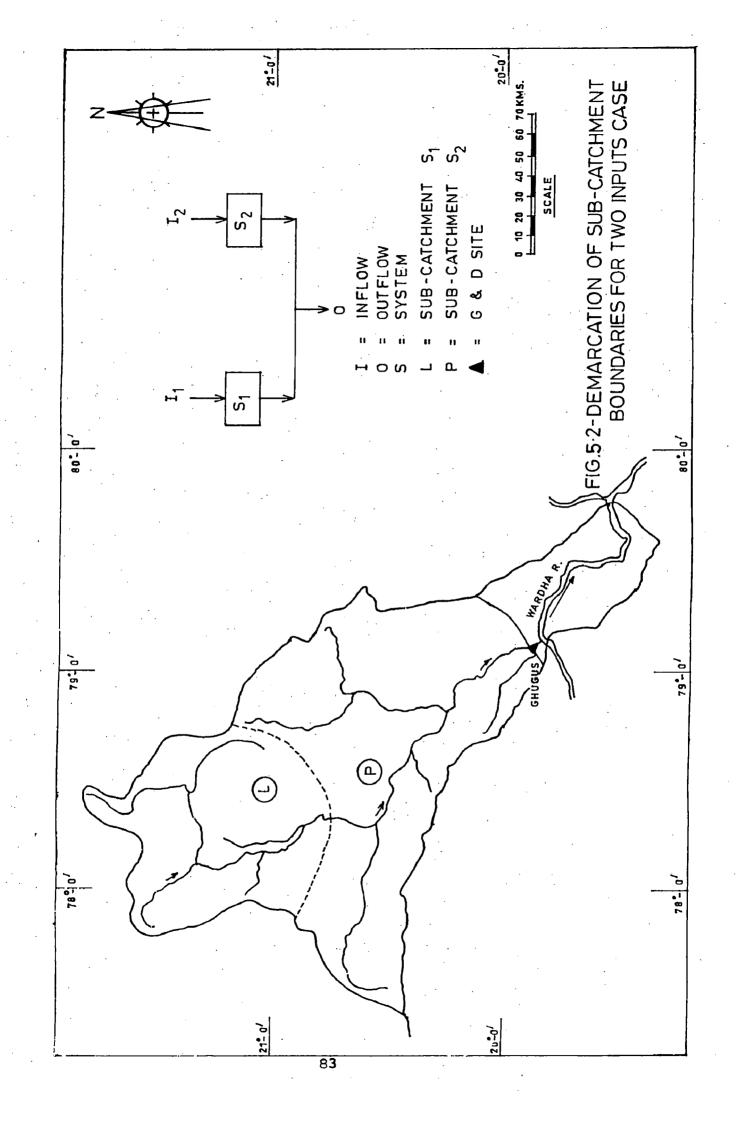
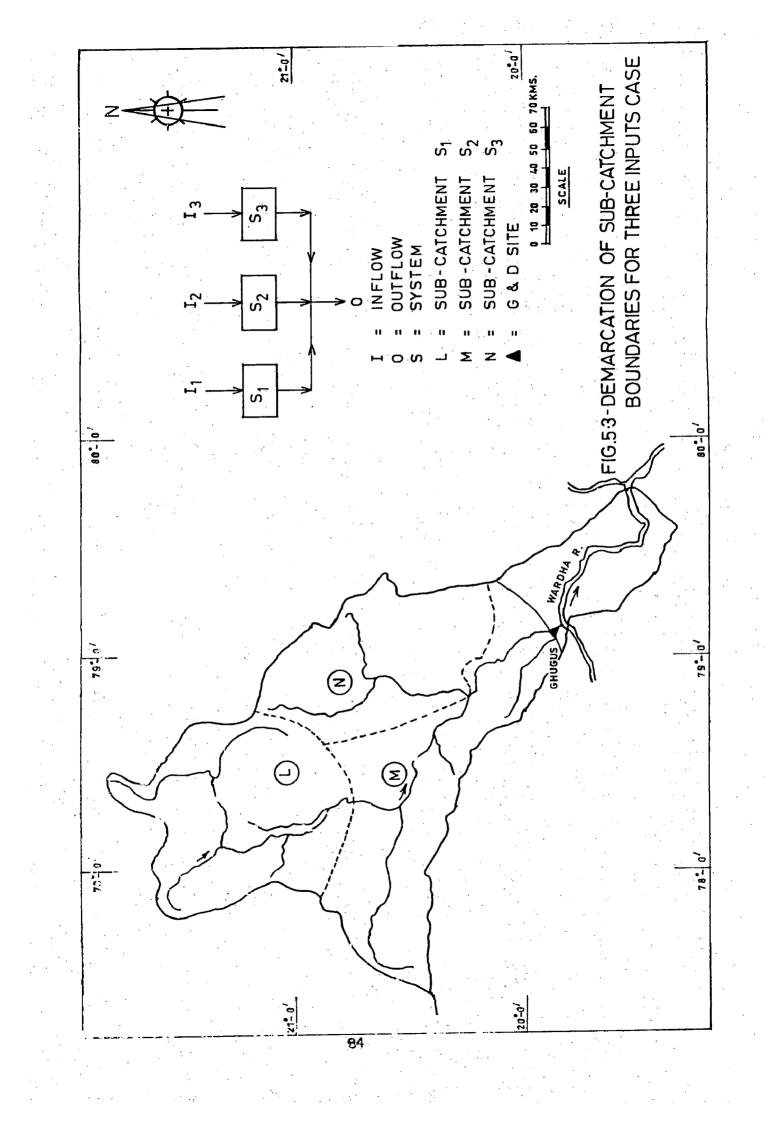


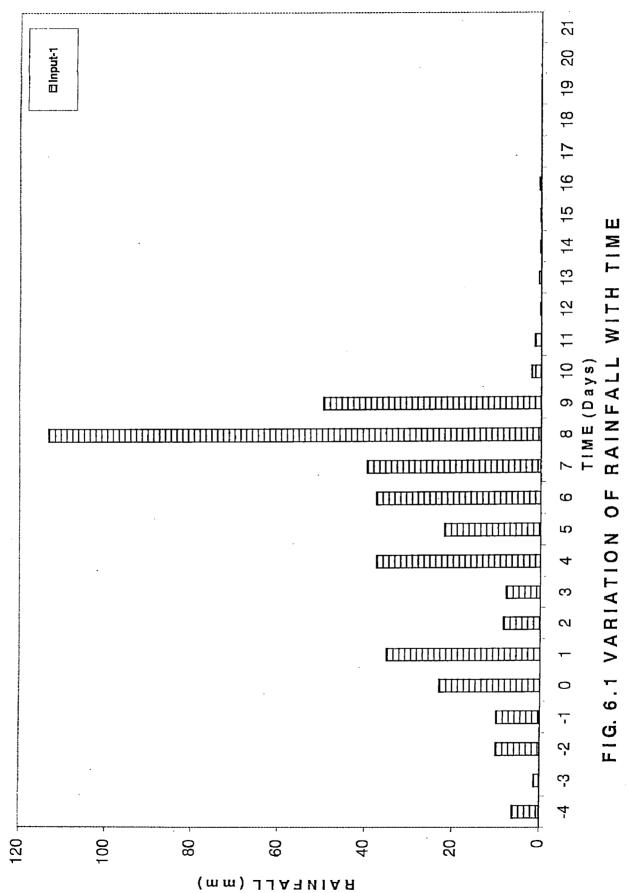
Fig. 2.7 APPLICATION STRATEGY FOR NLP

(Mays and Taur, 1982)

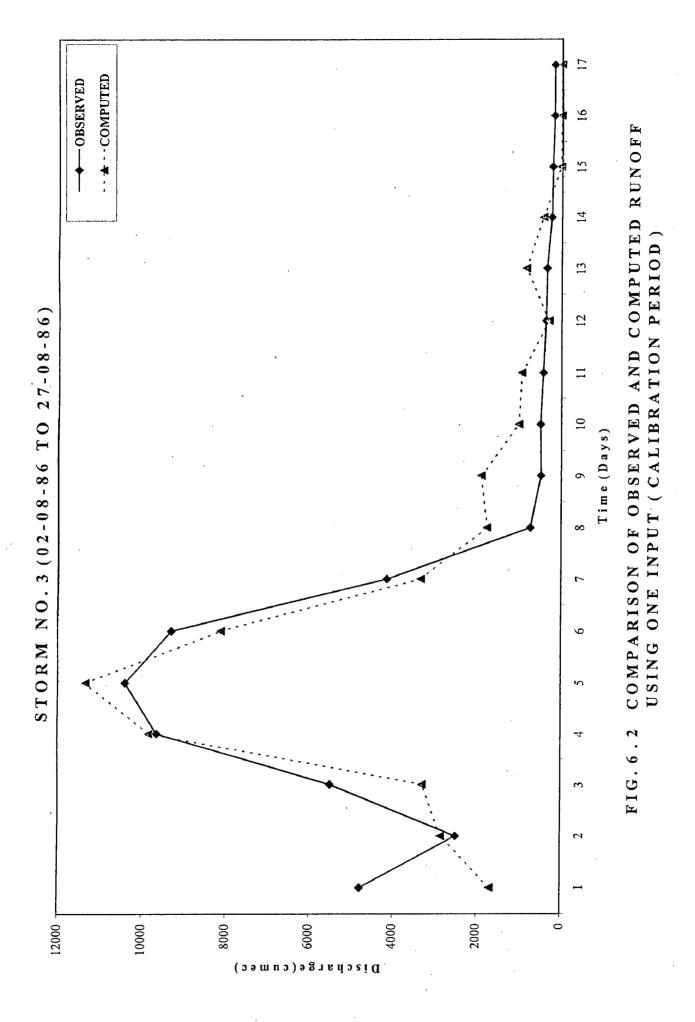


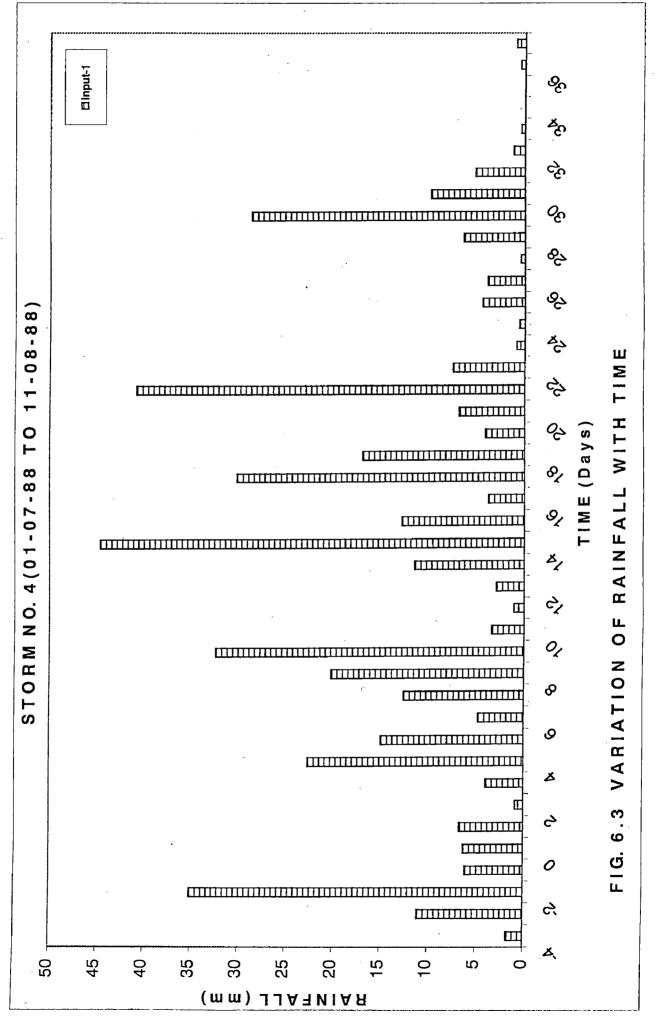


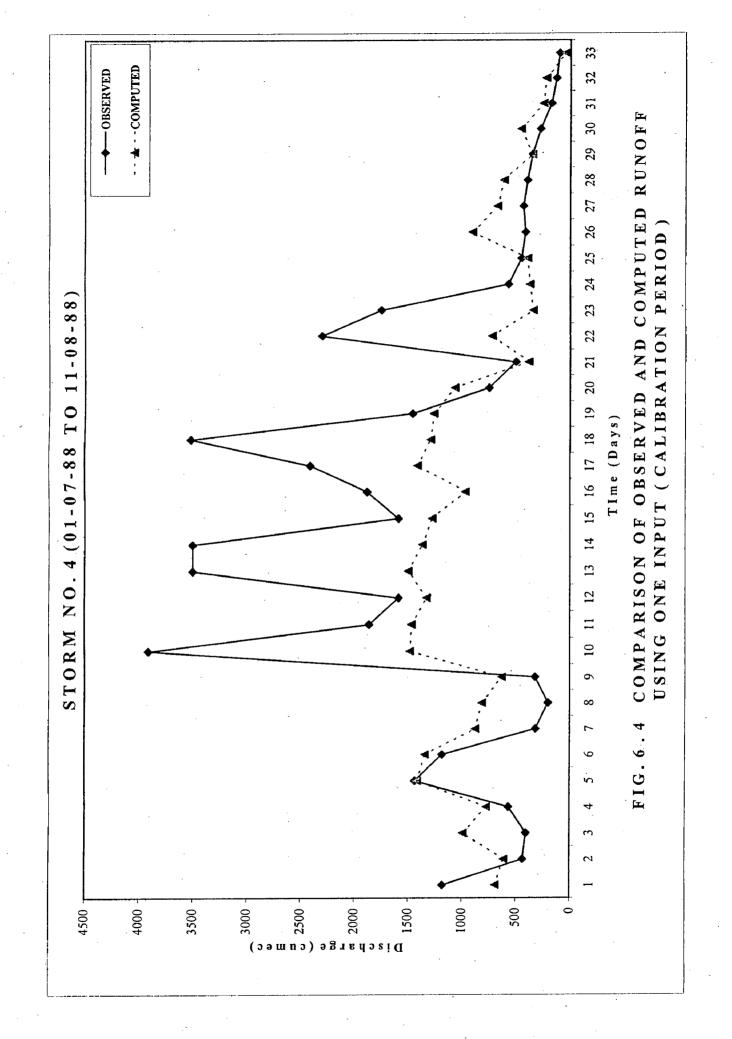


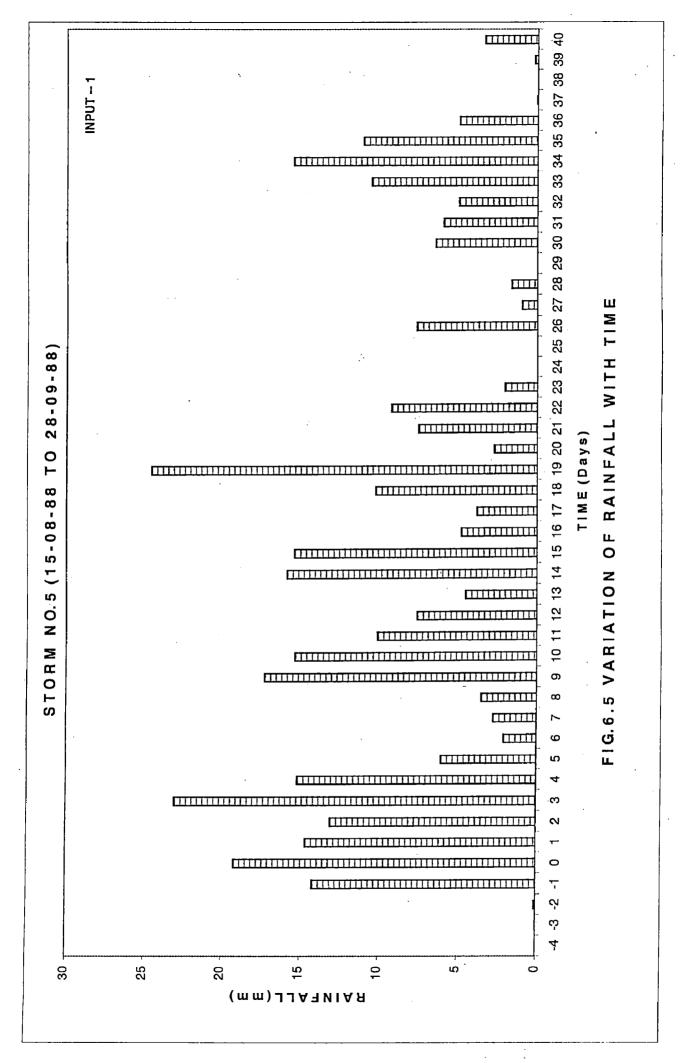


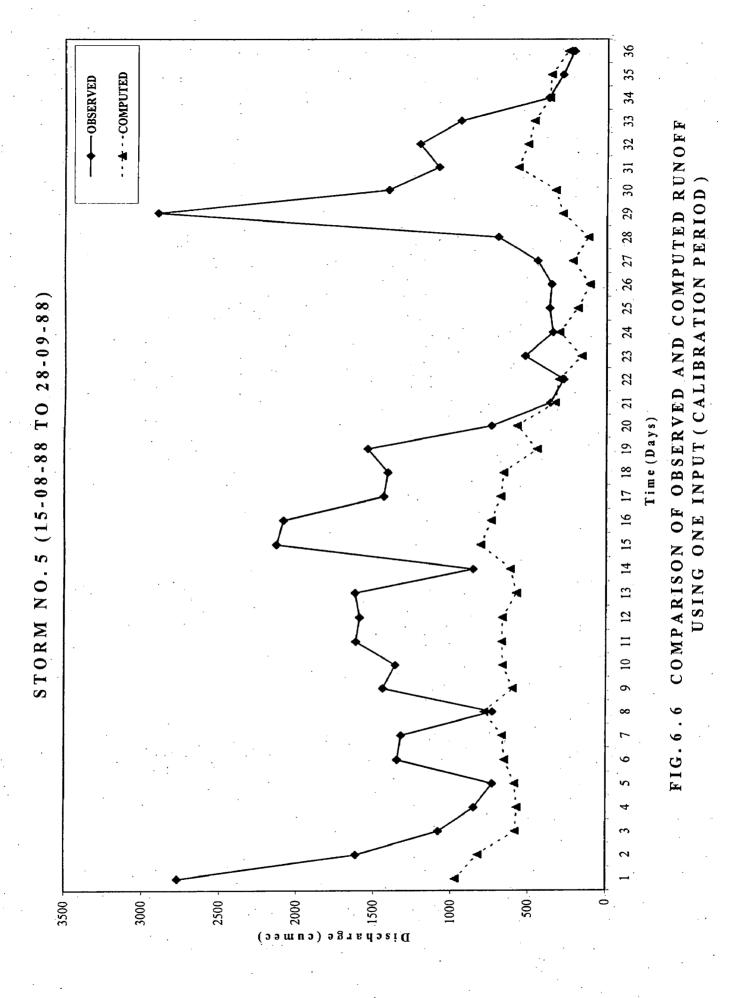
STORM NO.3 (02-08-86 TO 27-08-86)

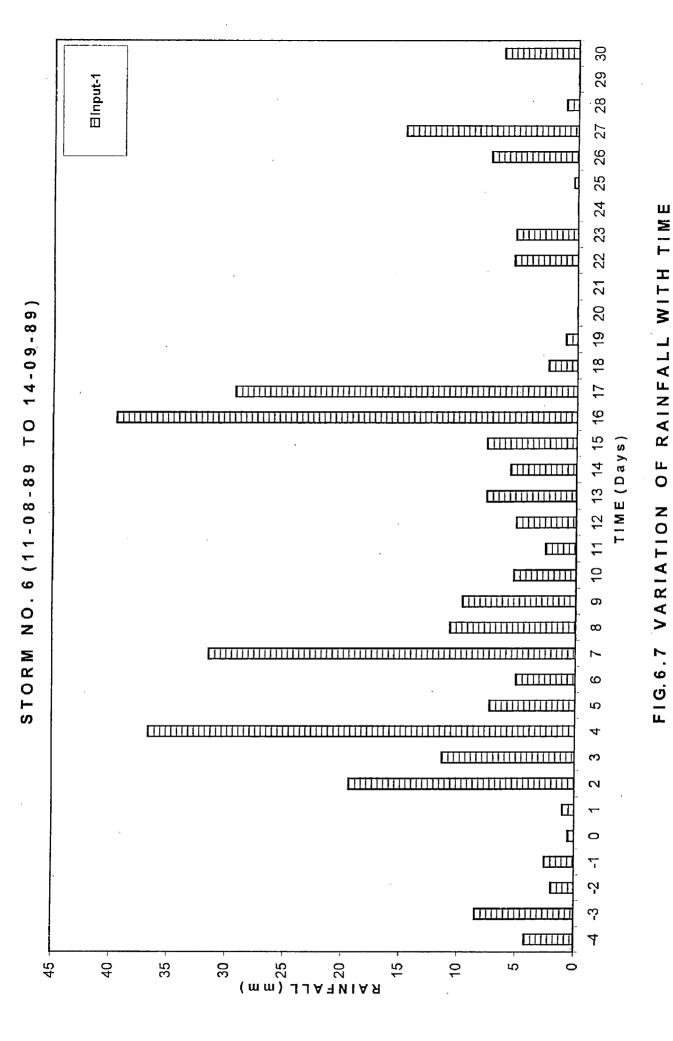


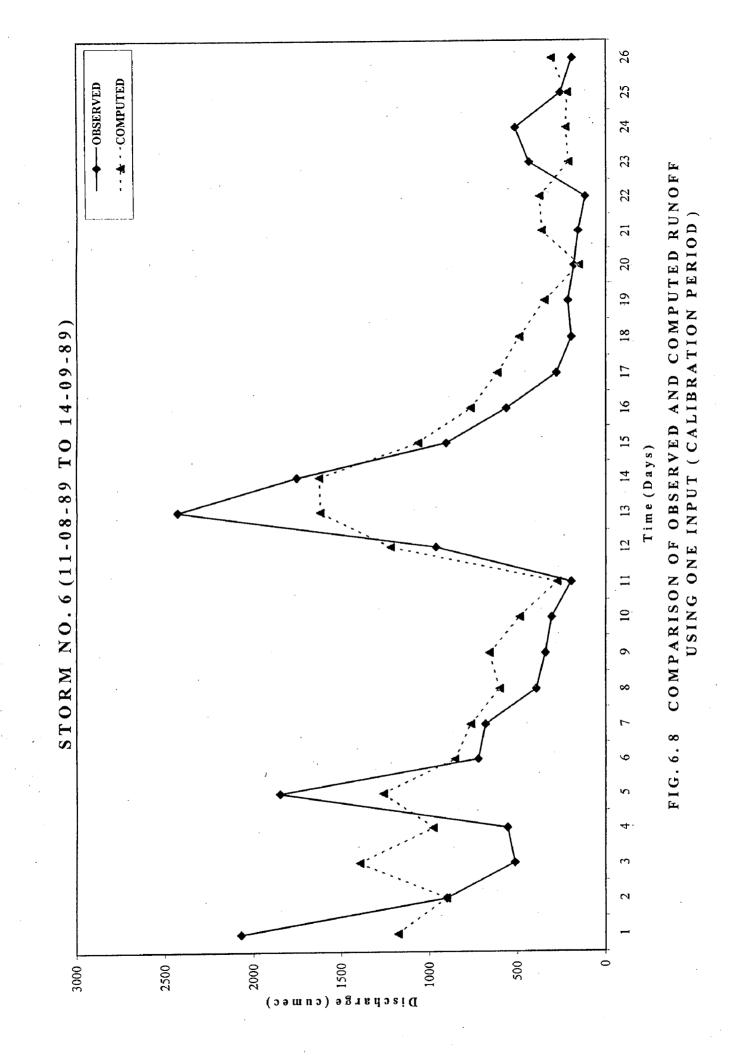


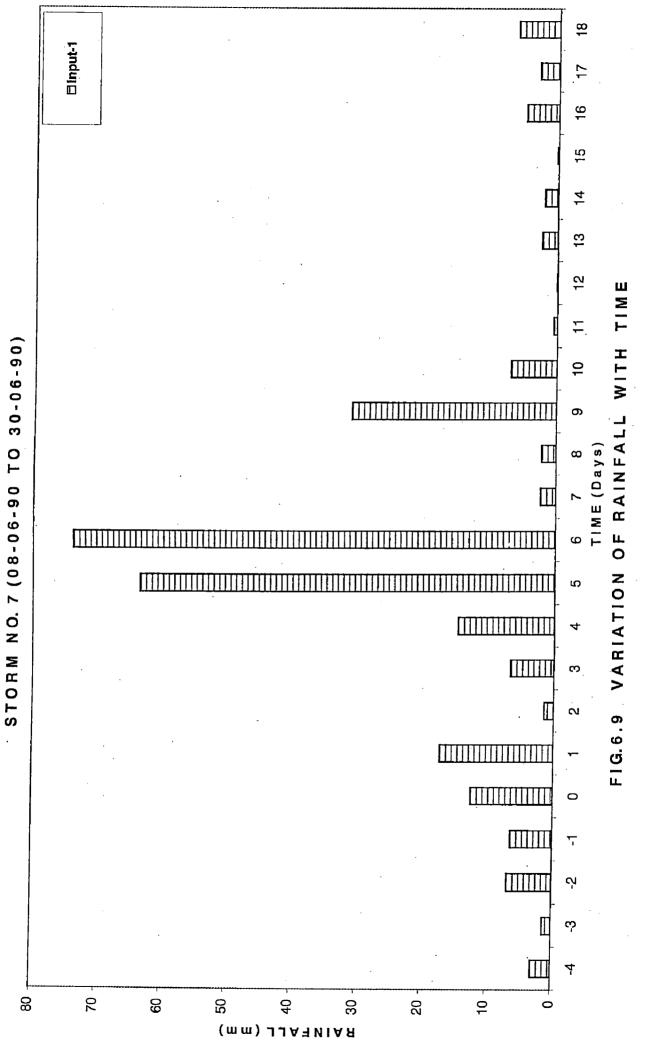




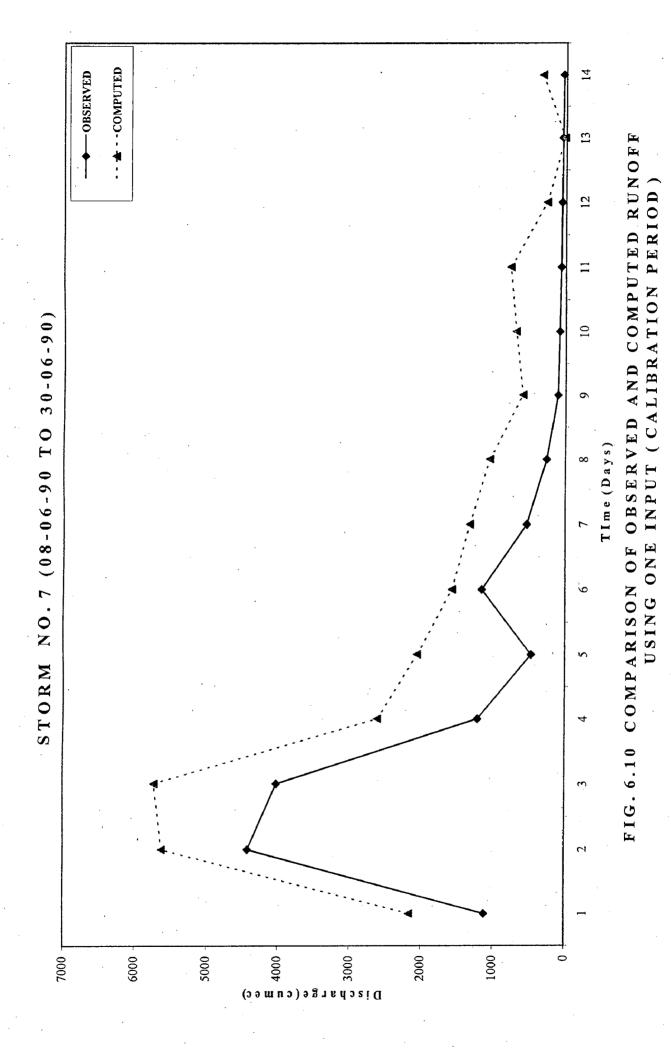


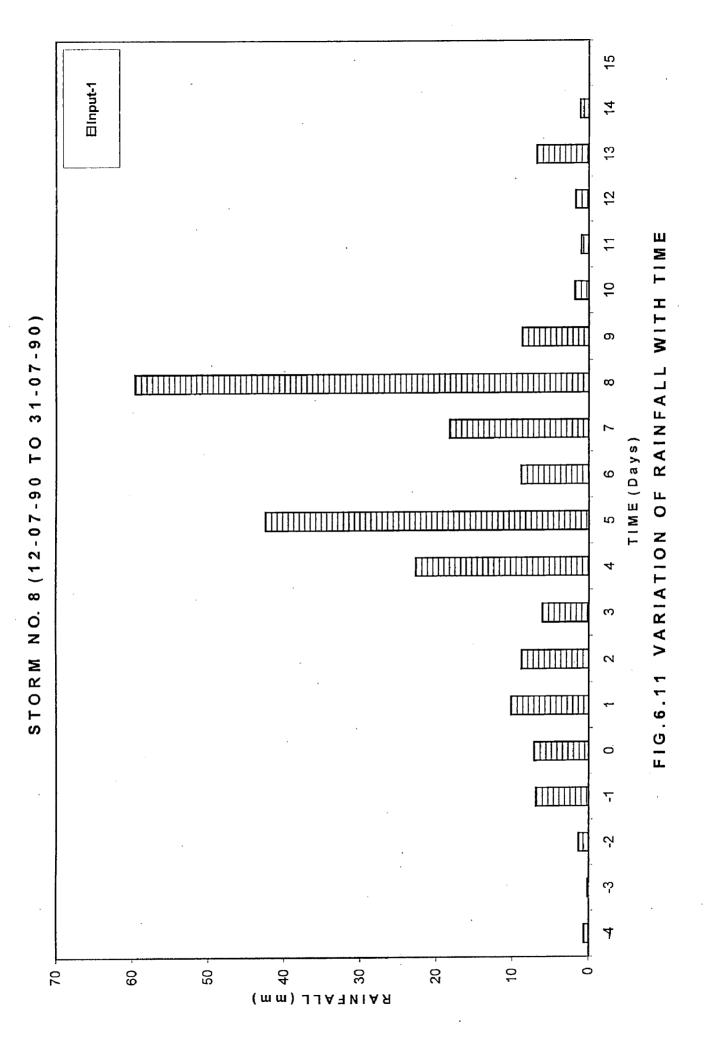


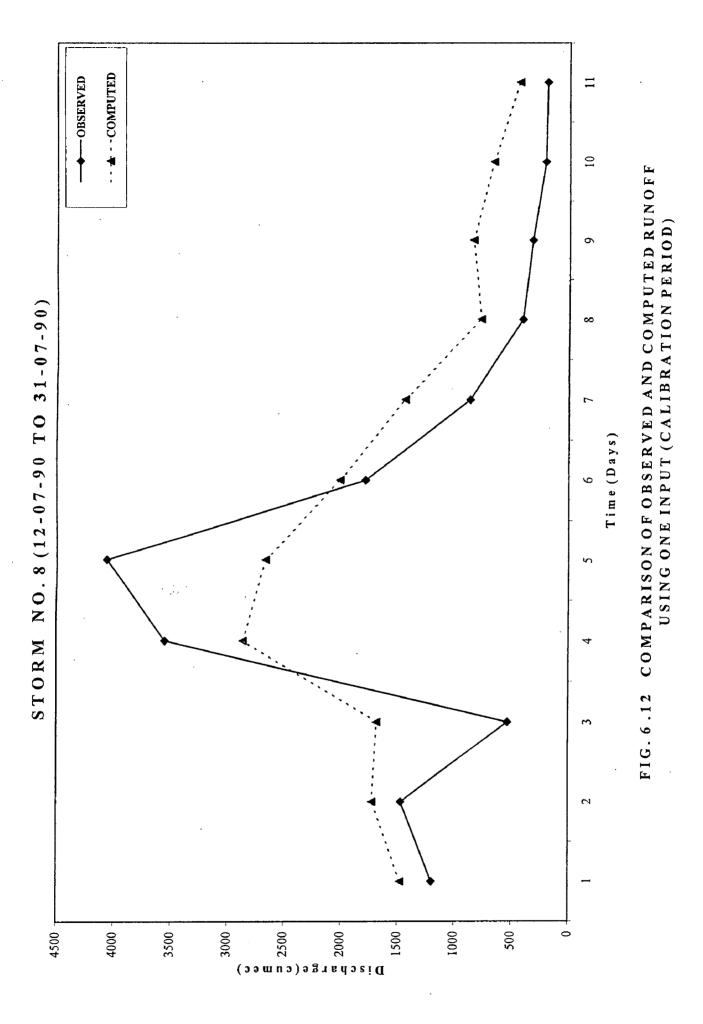


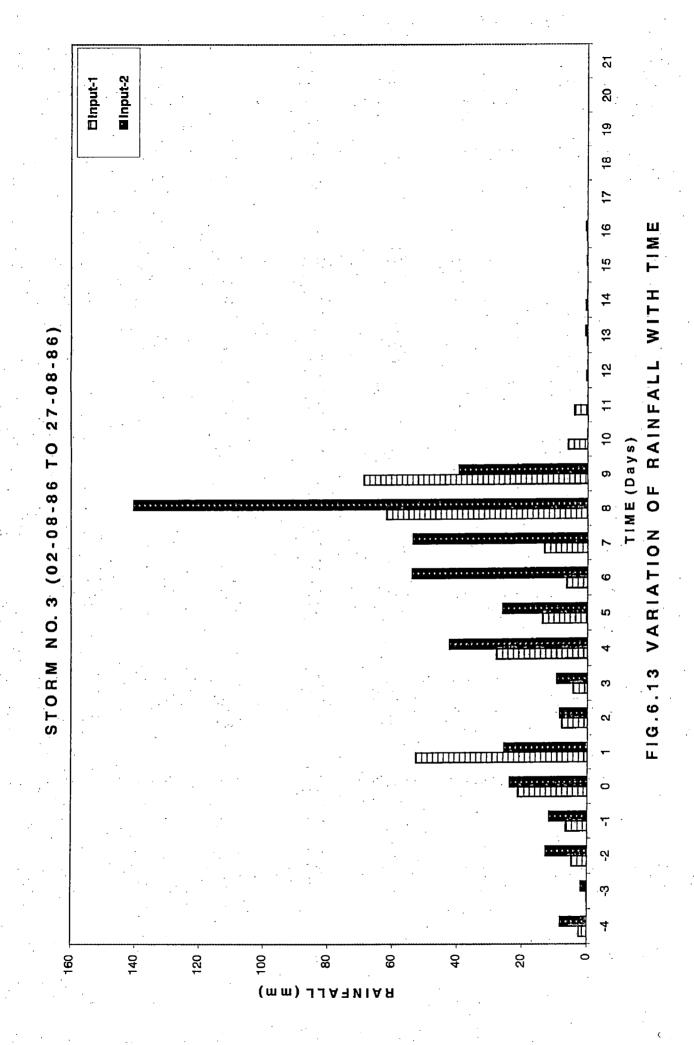


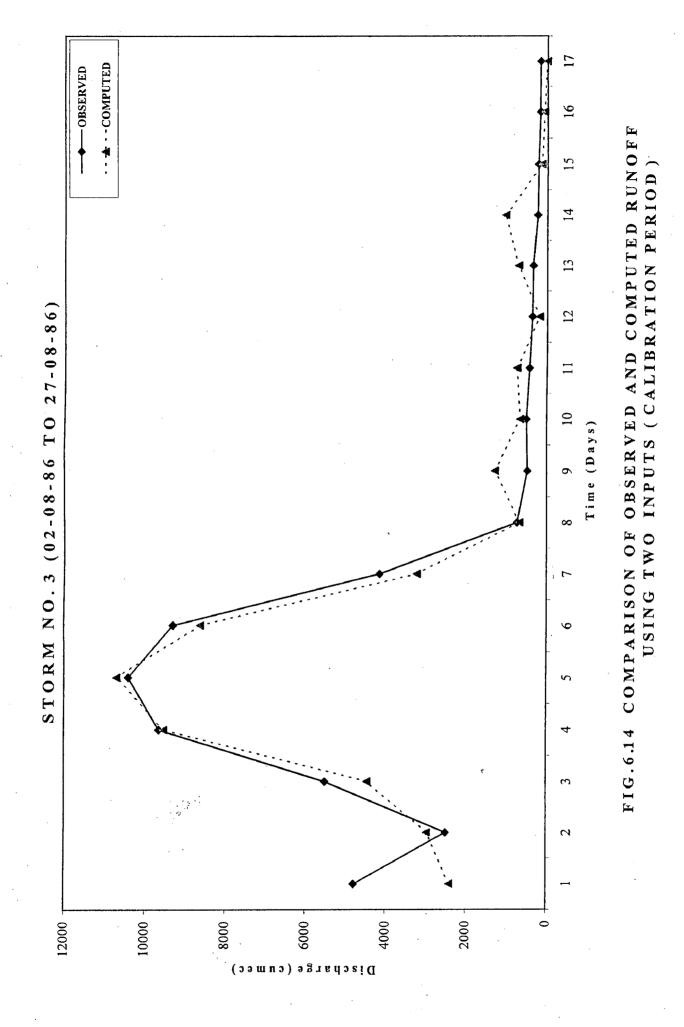
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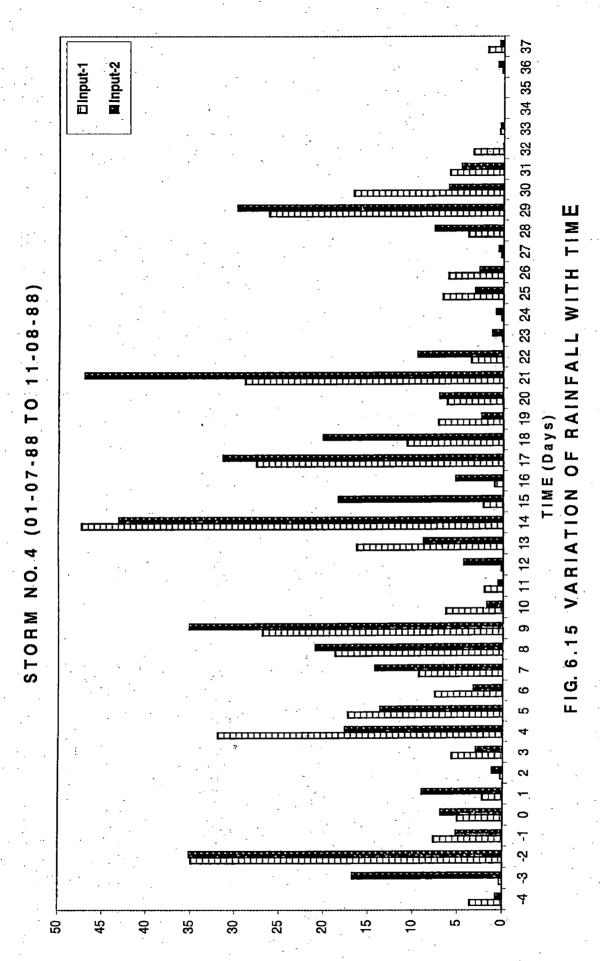




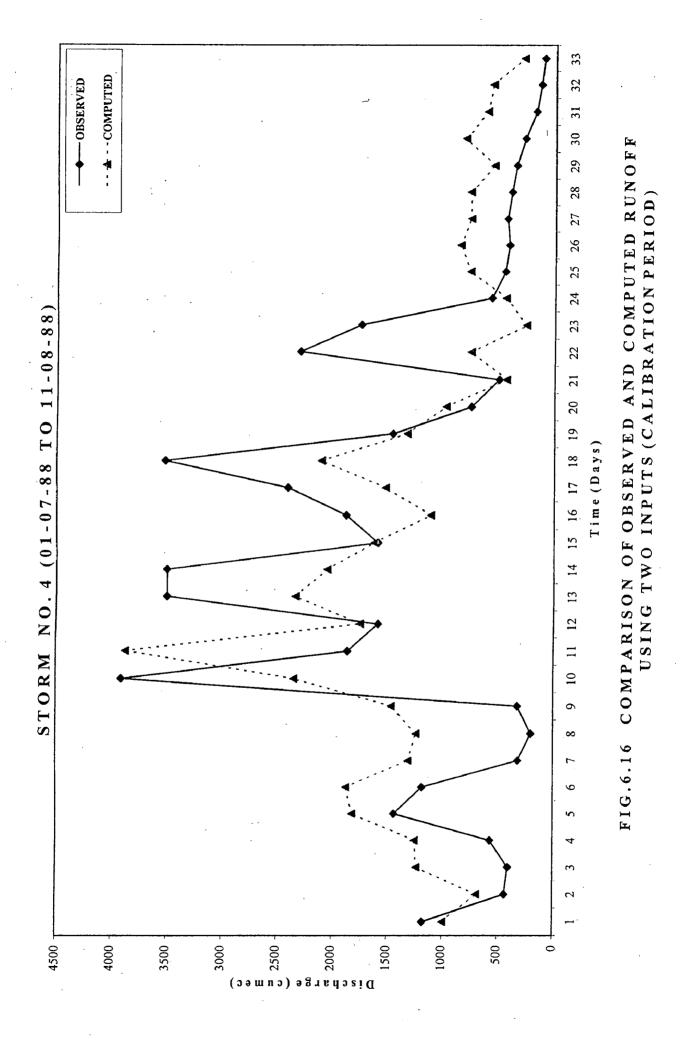


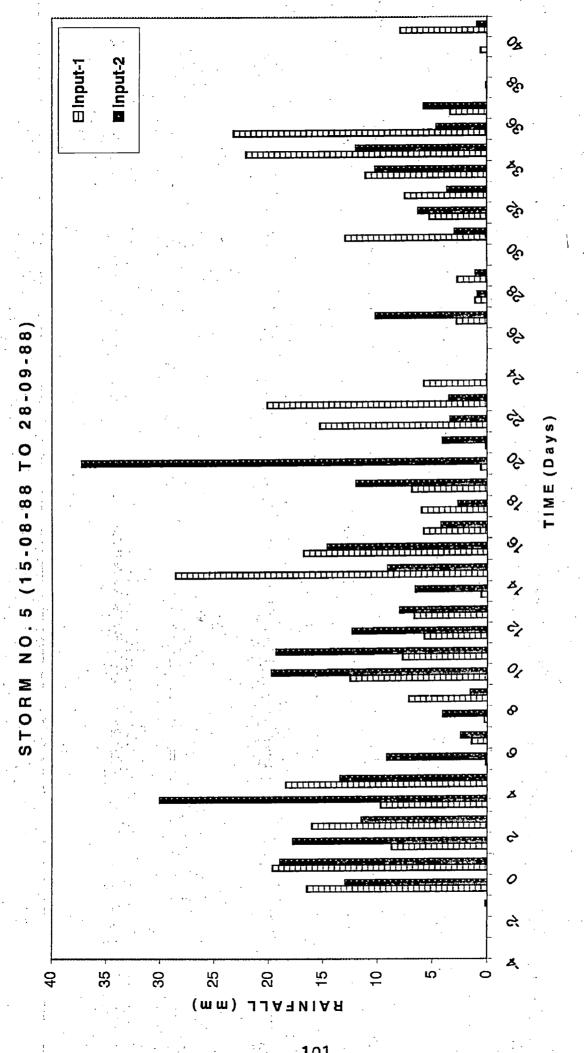






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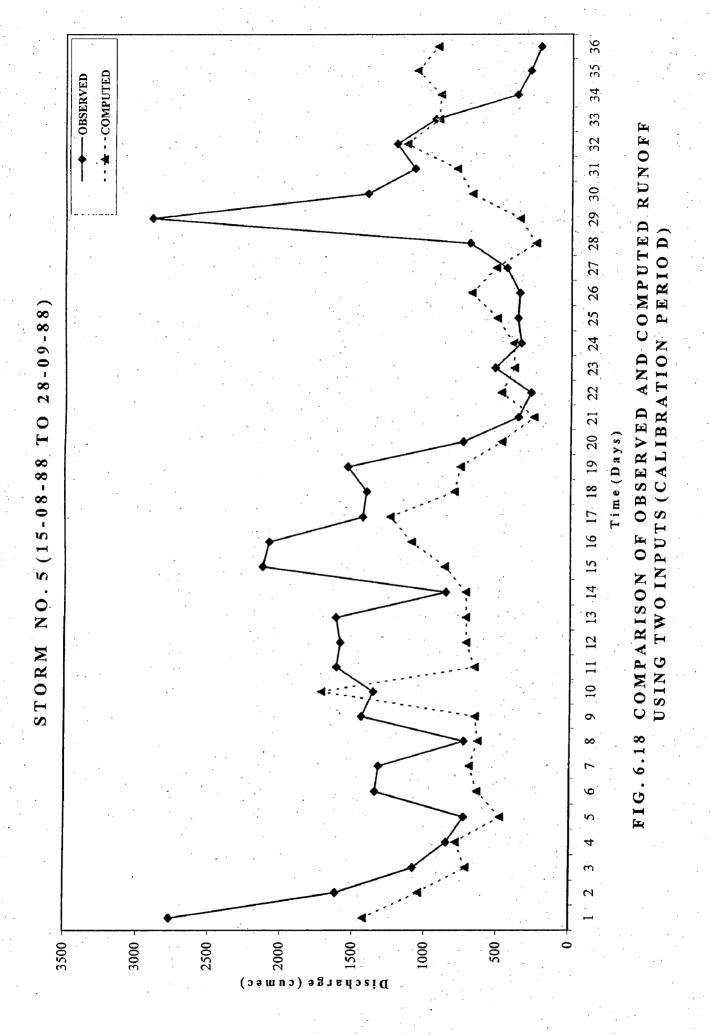
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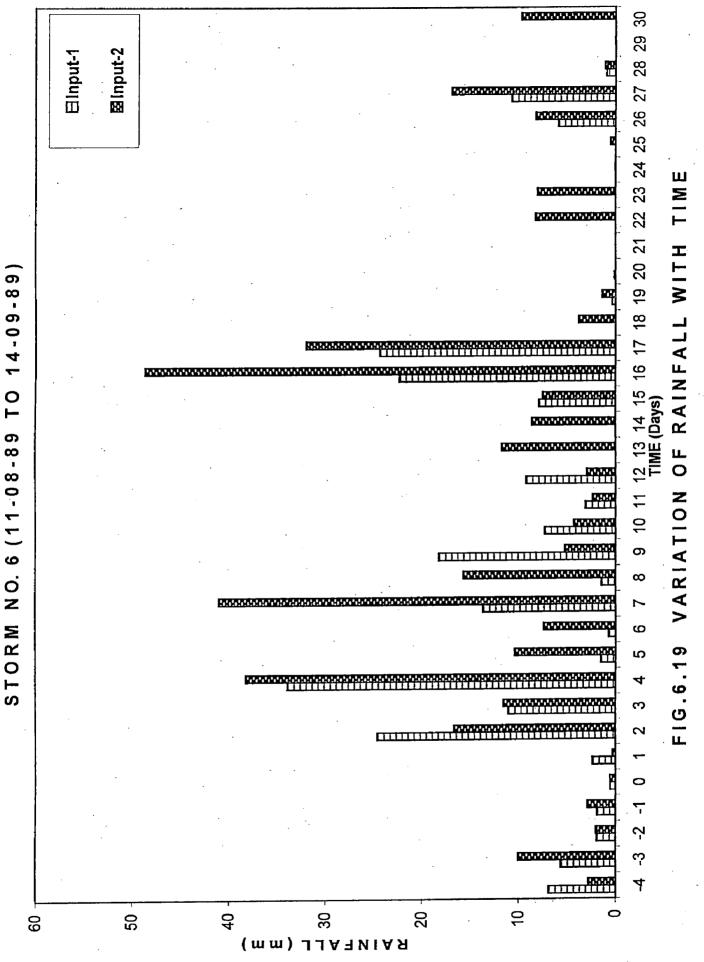
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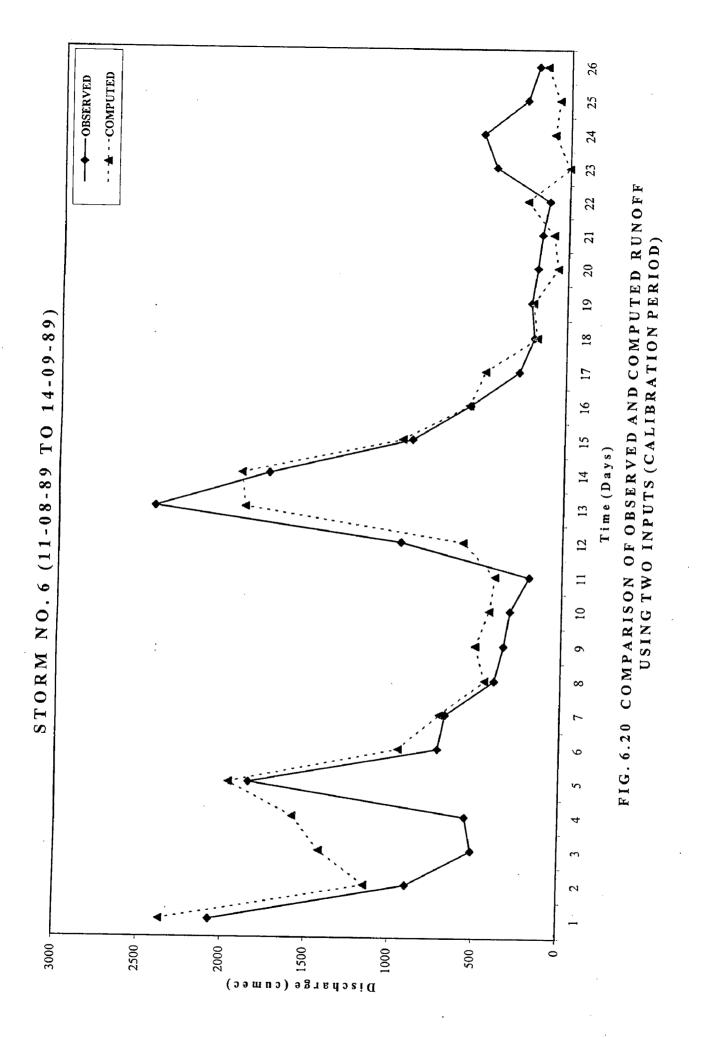
FIG.6.17

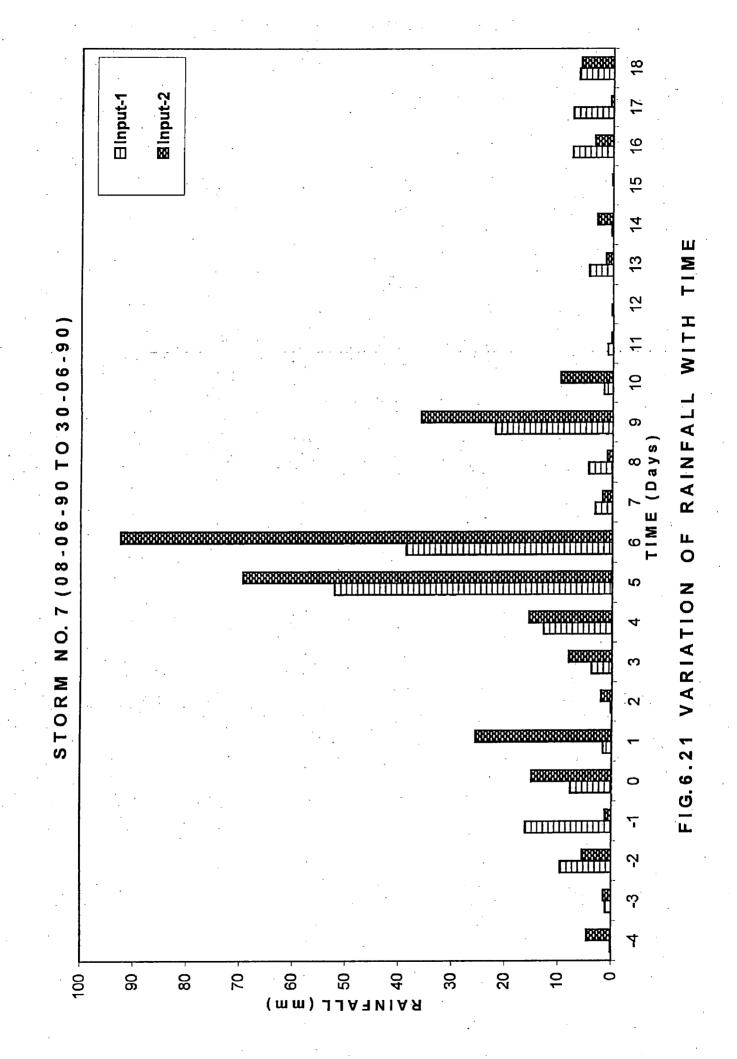


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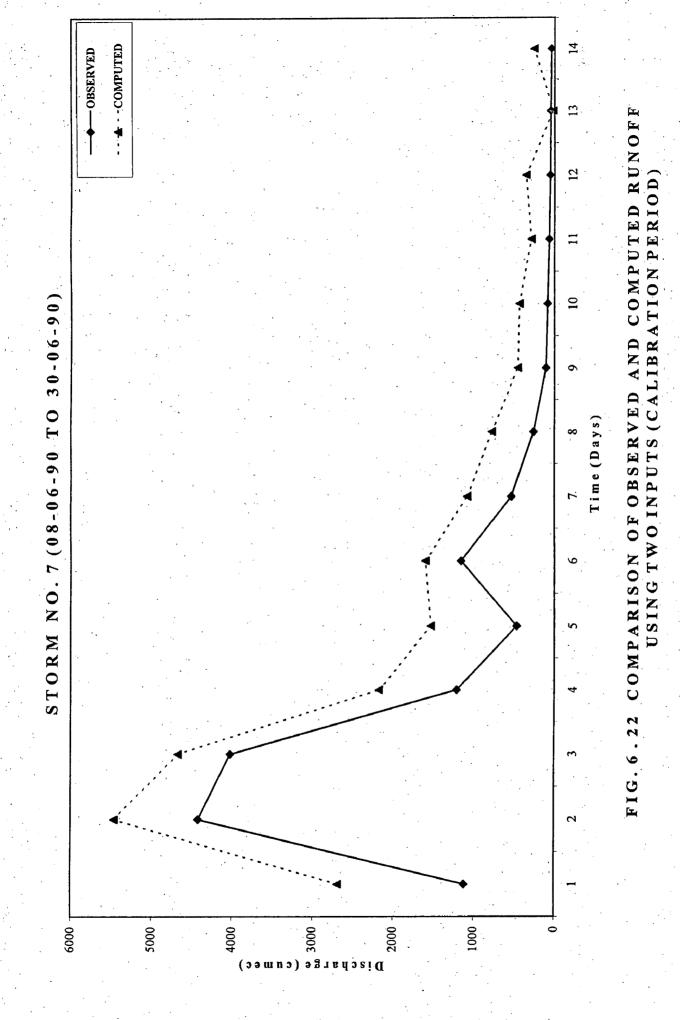


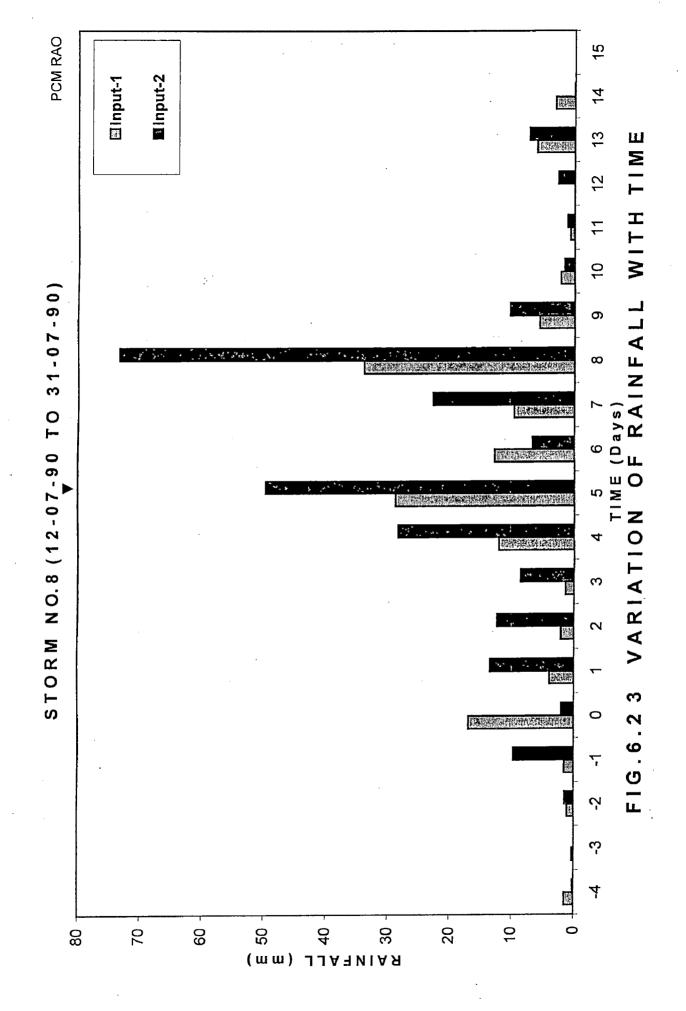
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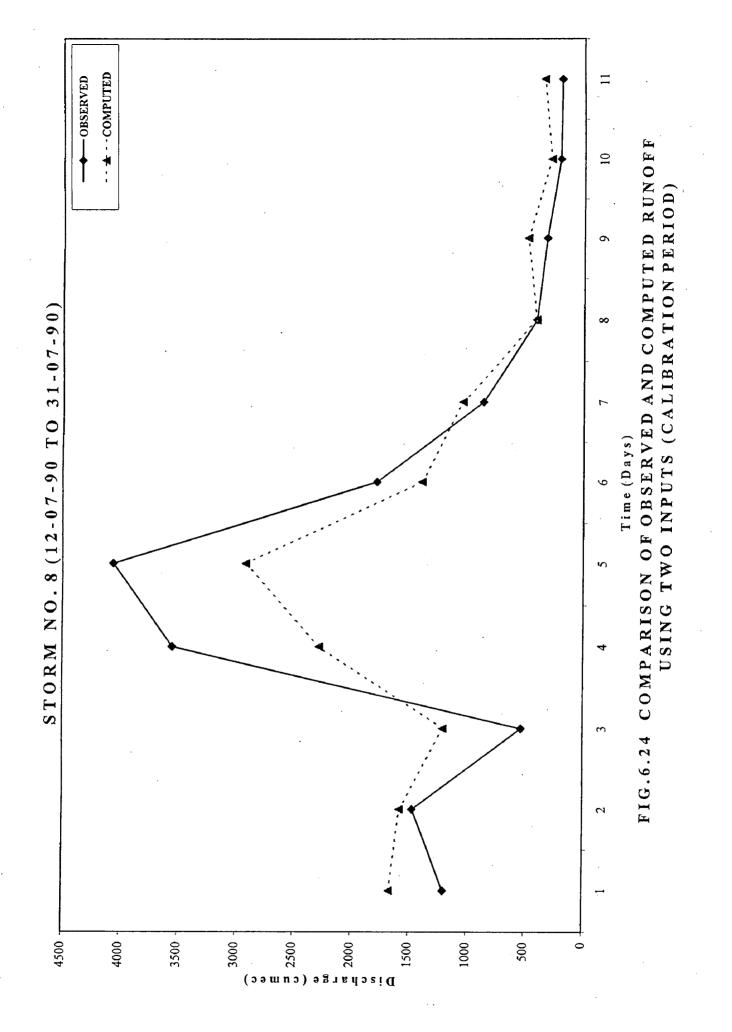


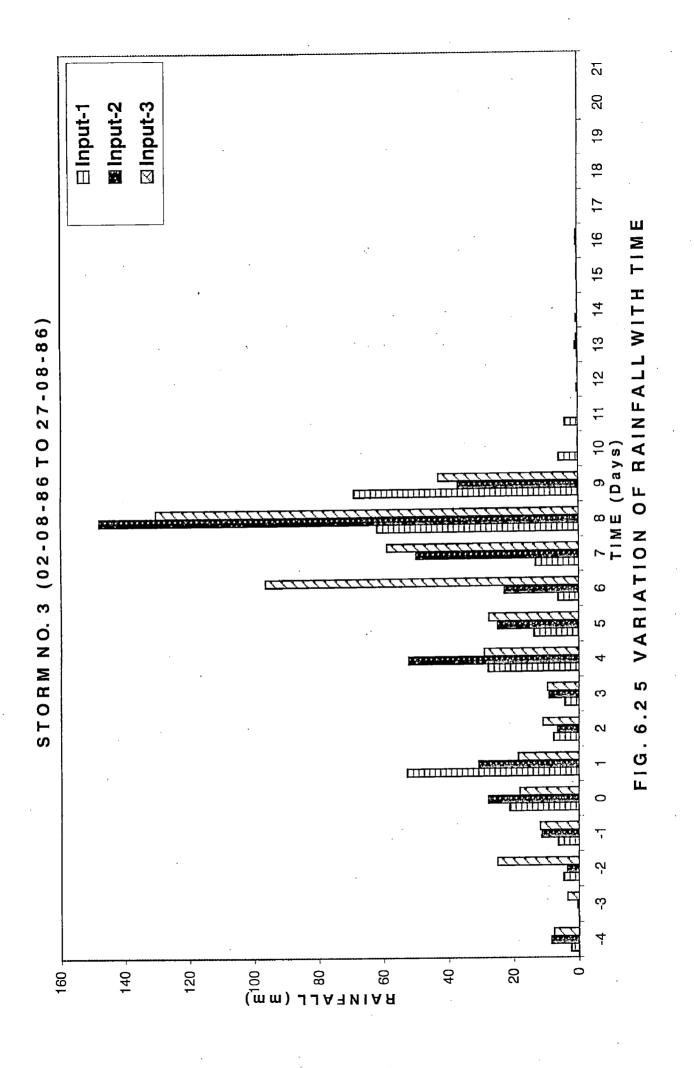


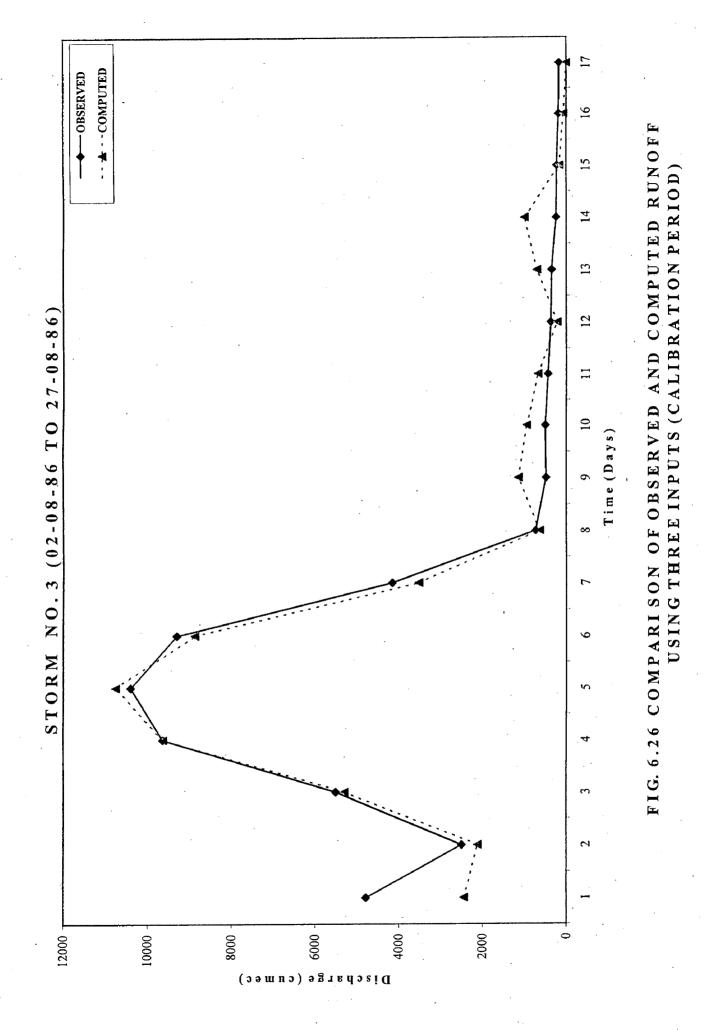
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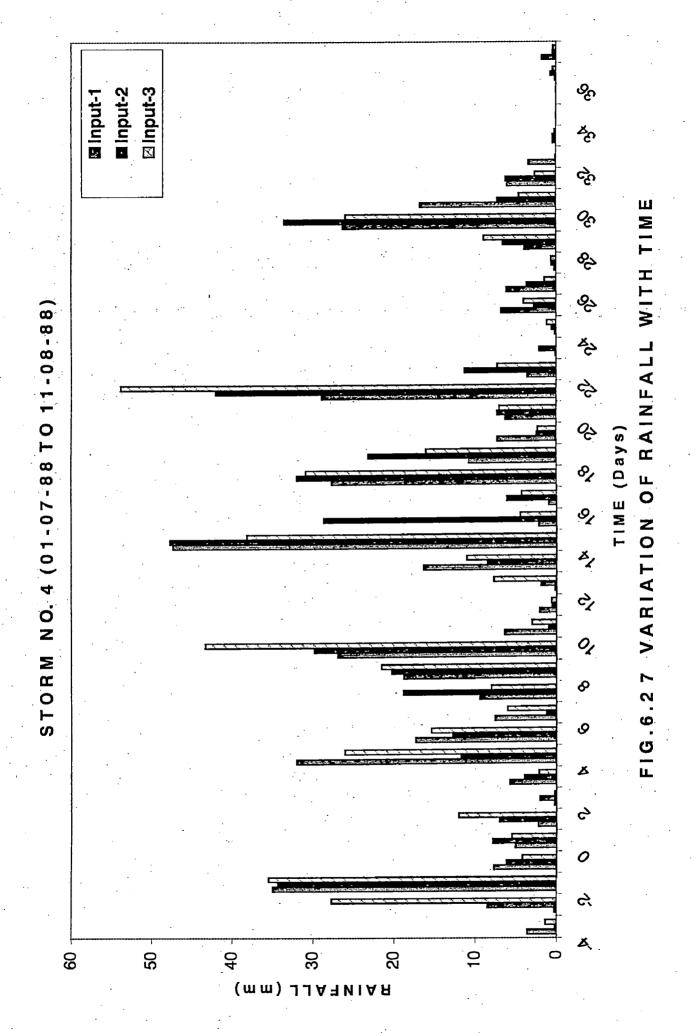




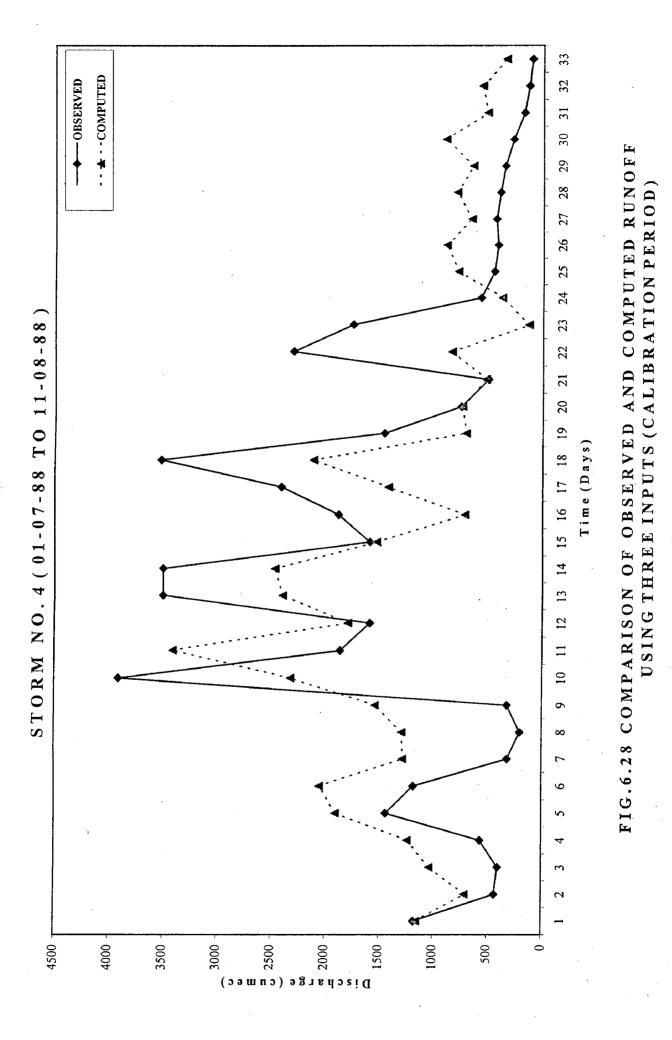


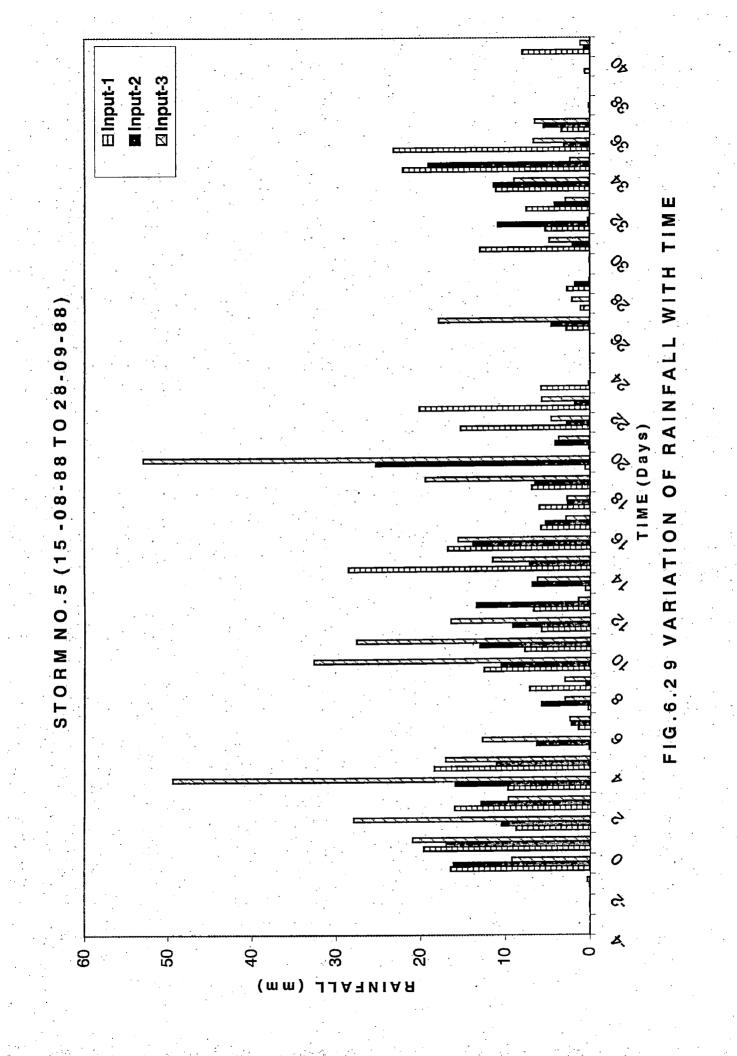


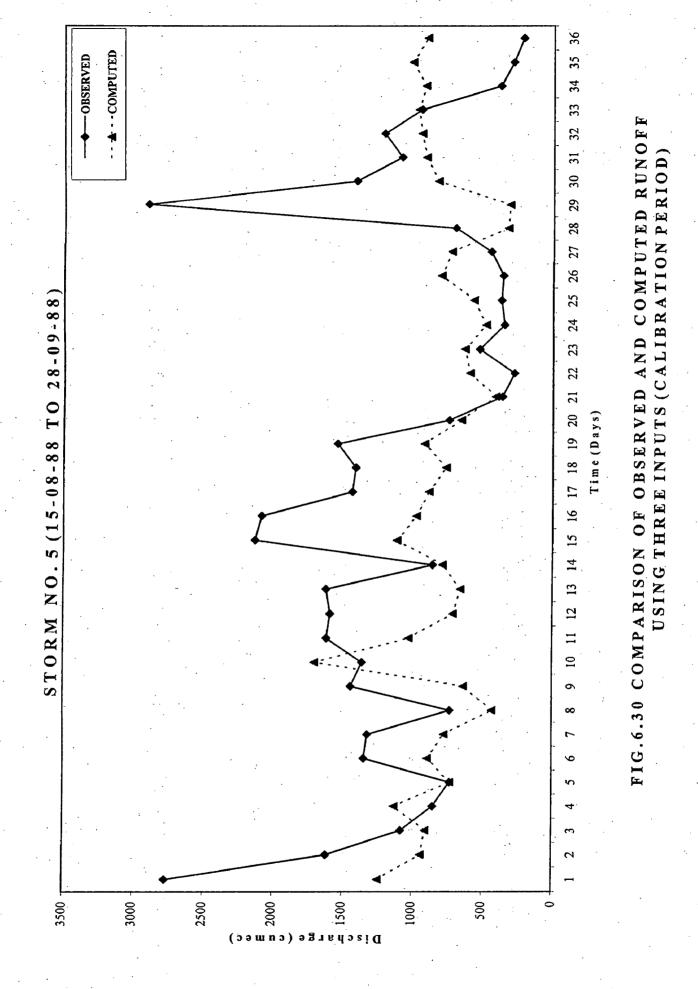


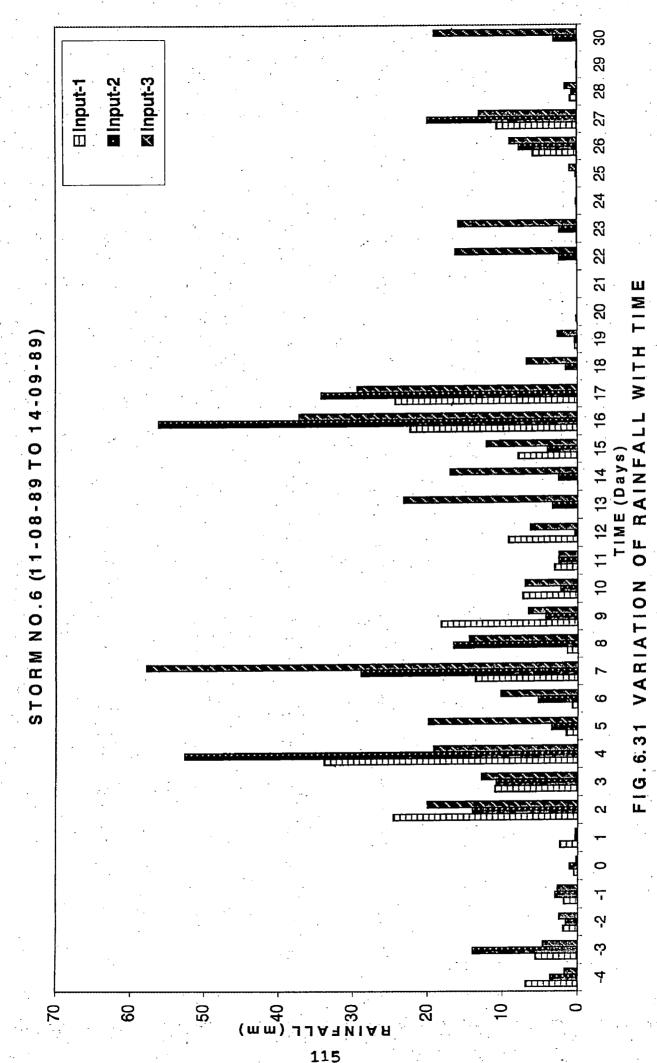


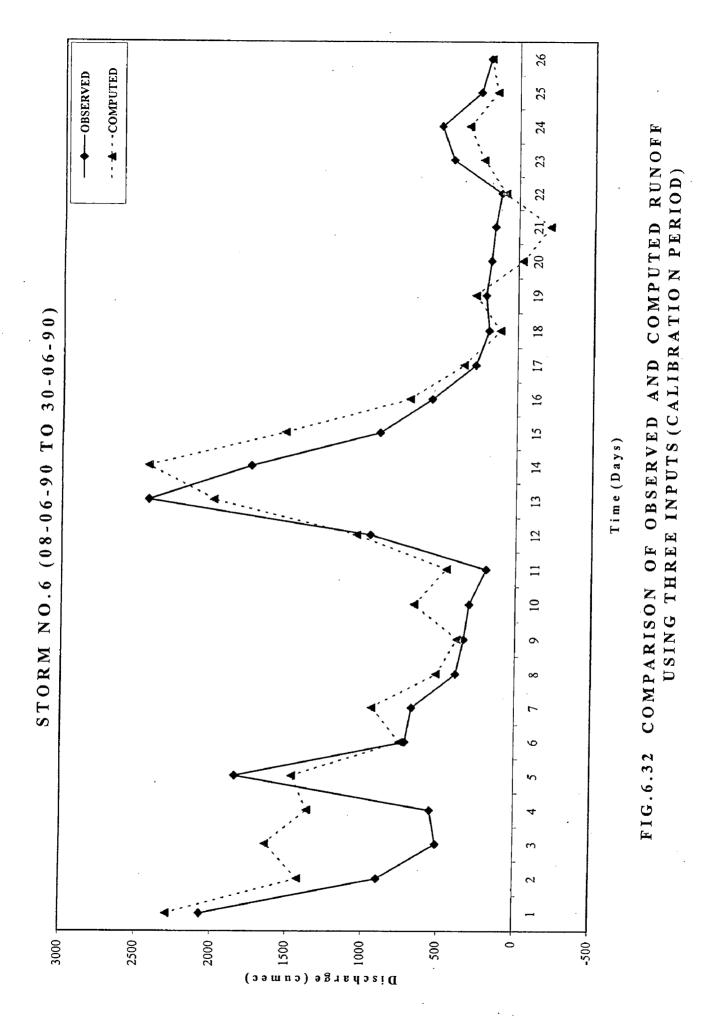
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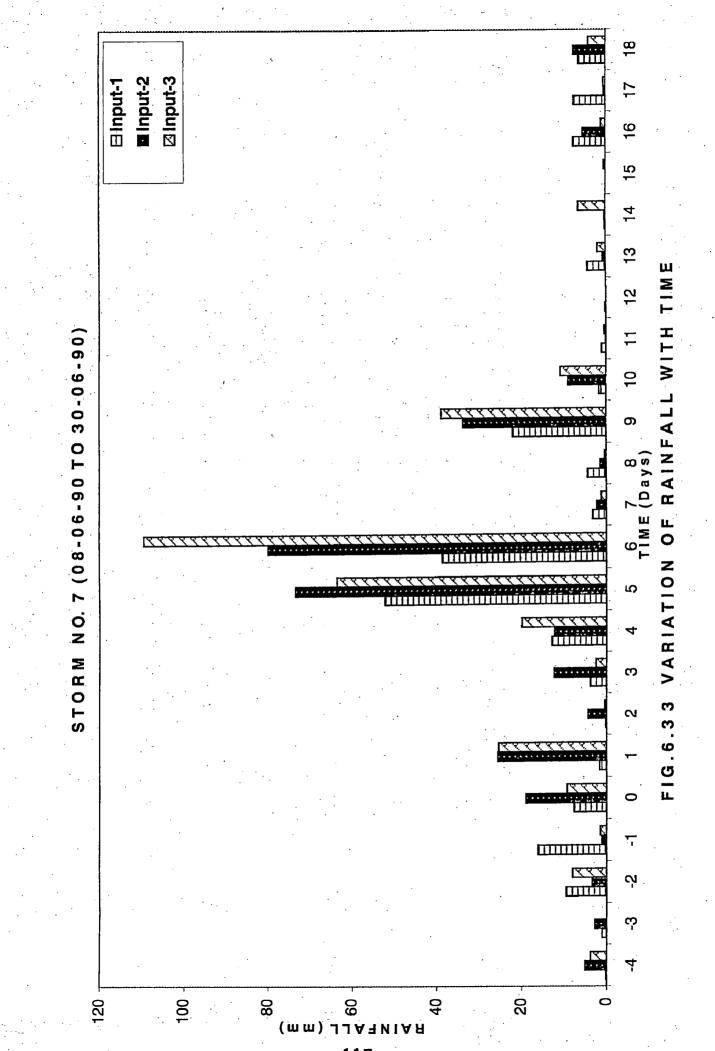


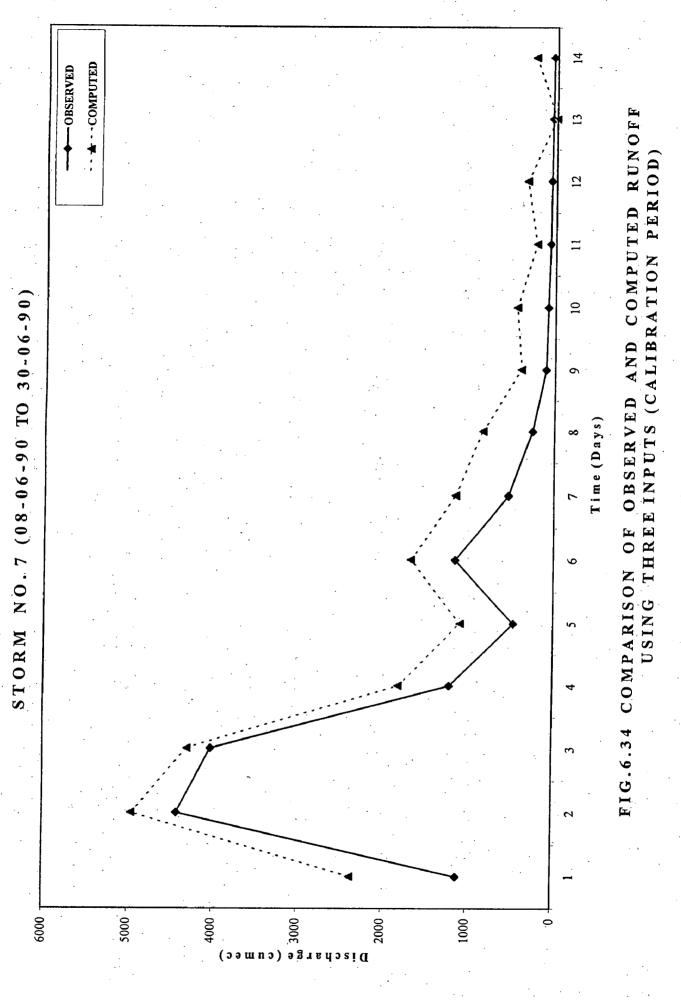




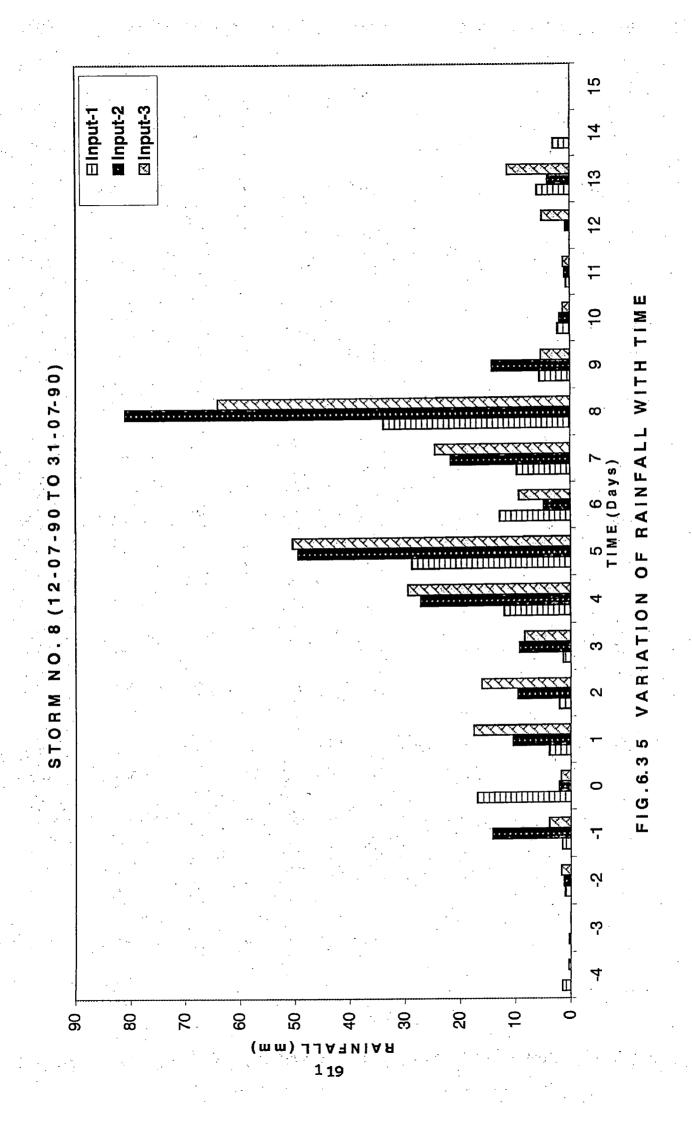


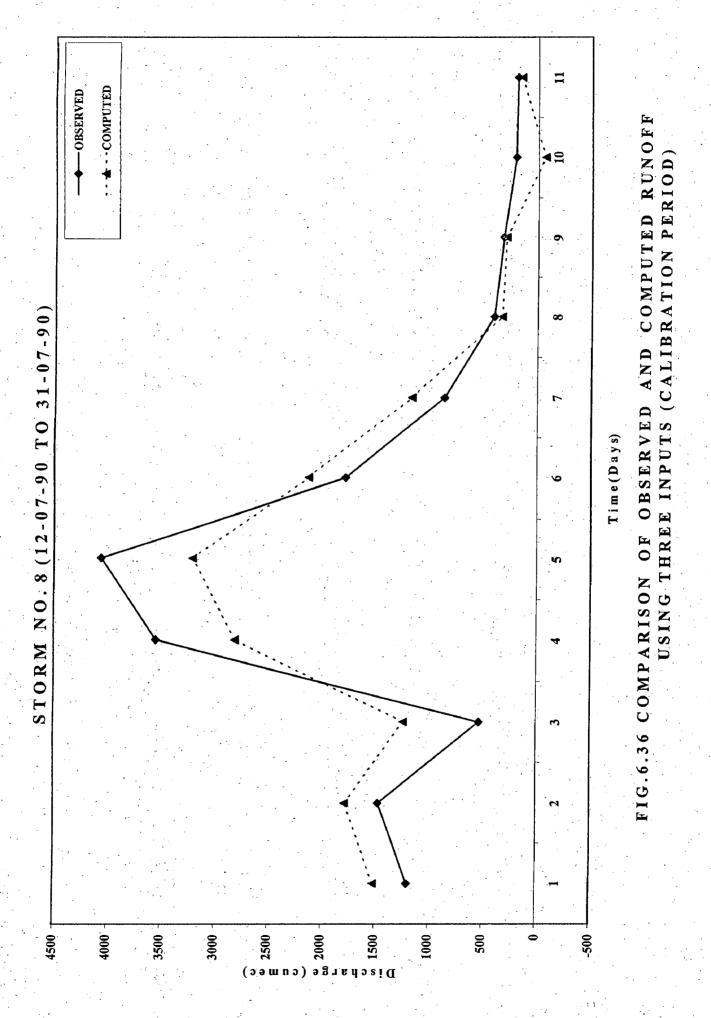




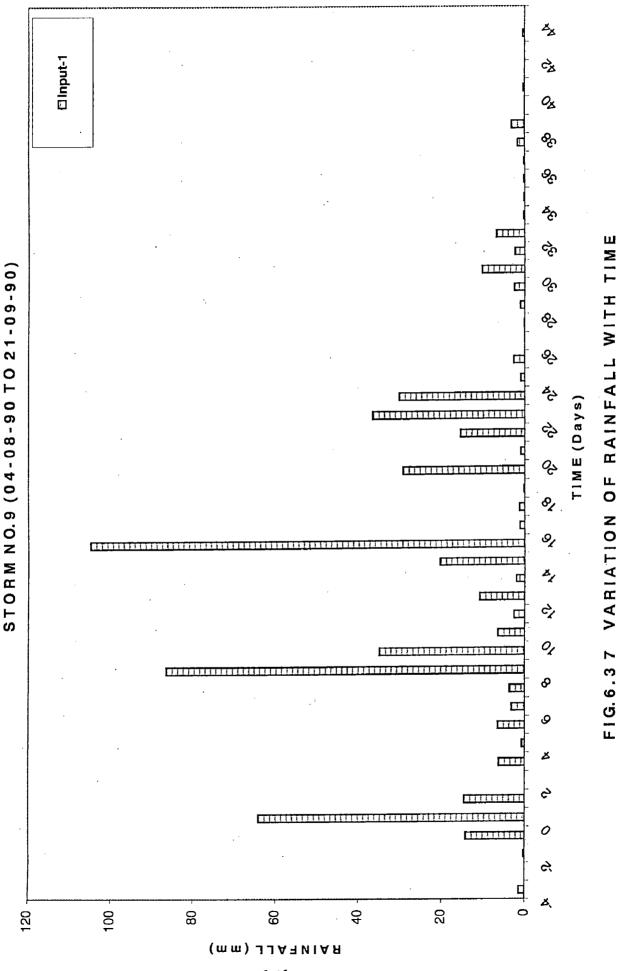


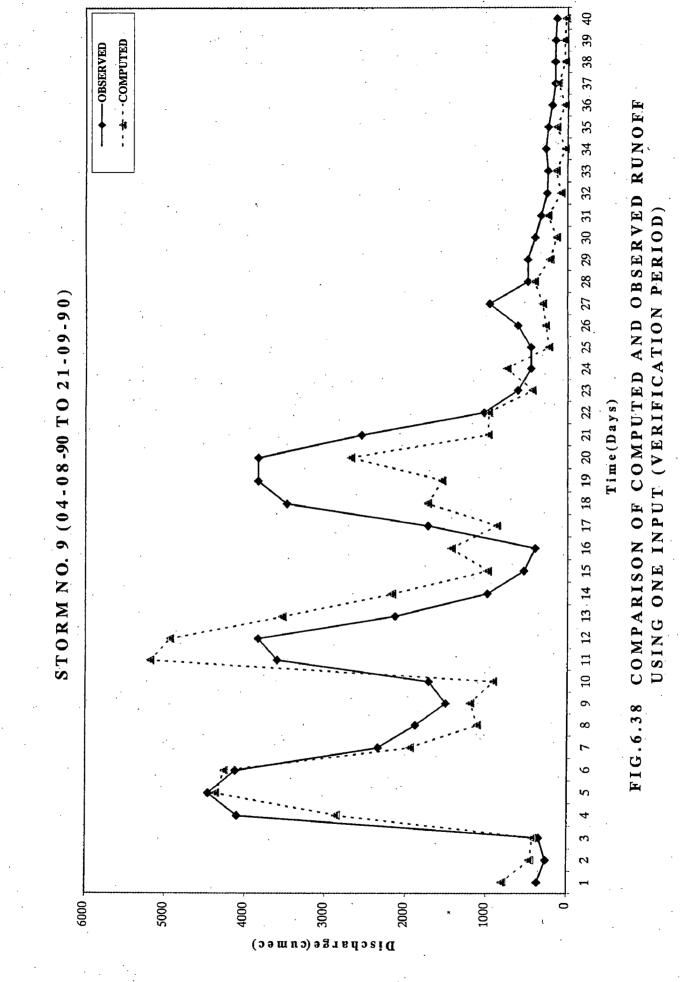
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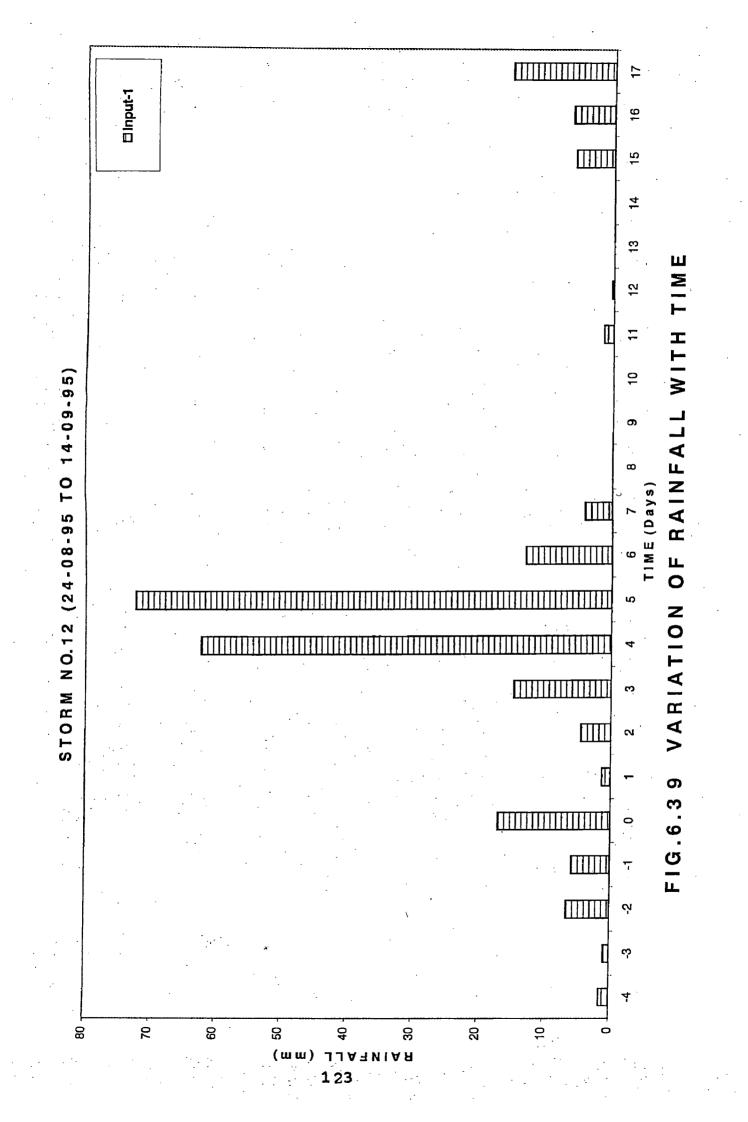


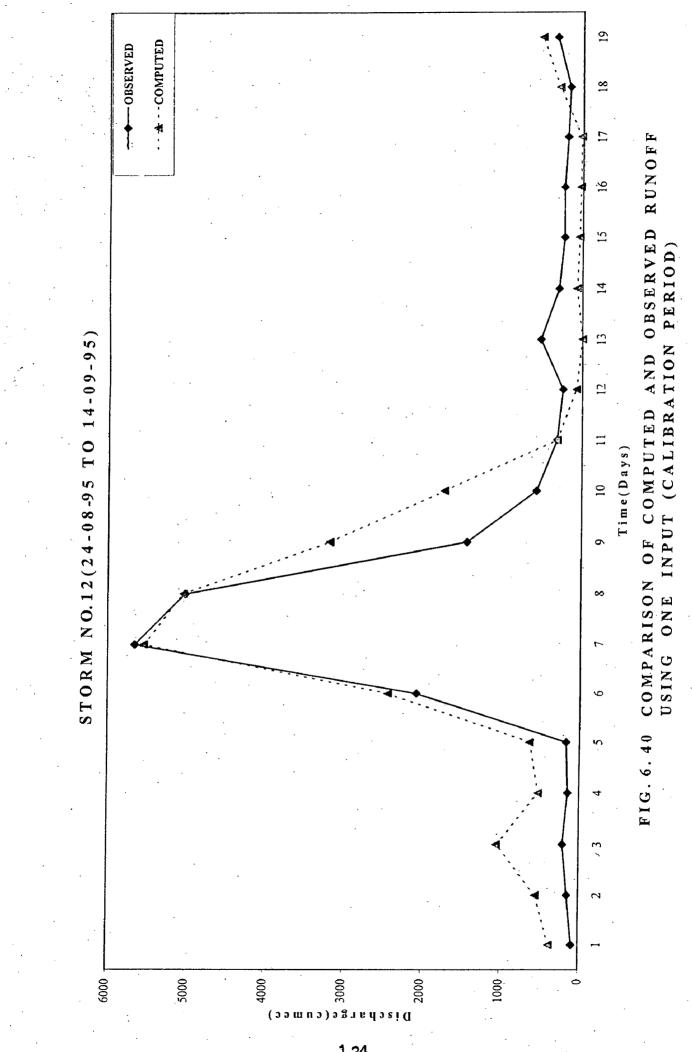


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APPENDIX --- 1

RAINFALL -- RUNOFF DATA FOR WARDHA UPTO GHUGUS

CALIBRATION PERIOD

Units : Rainfall in mm Discharge in Cumec

STORM NO. 1 (19-06-1985 TO 03-07-1985)

DATE	THE	REE INPUTS	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
		_					
19.06.85	0.000	0.000	0.000	0.000	0.000	0.000	65.2
20.06.85	0.000	0.000	0.000	0.000	0.000	0.000	35
21.06.85	0.464	0.000	0.000	0.464	0.000	0.161	12.8
22.06.85	2.152	0.000	0.000	2.152	0.000	0.744	8.3
23.06.85	0.276	2.902	4.319	0.276	3.505	2.388	10
24.06.85	6.059	10.369	6.096	6.059	8.564	7.698	6.7
25.06.85	25.992	78.051	31.945	25.992	58.510	47.268	14.9
26.06.85	54.028	55.451	84.446	54.028	67.720	62.982	597.2
27.06.85	3.004	22.007	34.993	3.004	27.501	19.027	1374.5
28.06.85	2.452	5.129	2.372	2.452	3.961	3.440	1848
29.06.85	0.000	0.000	0.000	0.000	0.000	0.000	491.7
30.06.85	0.000	0.000	0.000	0.000	0.000	0.000	150
01.07.85	0.000	0.000	0.000	0.000	0.000	0.000	70.9
02.07.85	0.000	0.000	0.000	0.000	0.000	0.000	47.5
03.07.85	0.000	0.055	0.000	0.000	0.032	0.021	22.1

STORM NO. 2 (01-08-1985 TO 20-08-1985)

DATE	ТНГ	REE INPUT	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
01.08.85	8.608	2.851	2.491	8.608	2.701	4.743	74.7
02.08.85	12.396	1.176	0.843	12.396	1.036	4.964	61.9
03.08.85	2.978	9.953	26.237	2.978	16.854	12.056	113
04.08.85	1.008	1.321	0.454	1.008	0.954	0.973	680
05.08.85	0.015	0.000	0.000	0.015	0.000	0.005	192.8
06.08.85	0.478	0.155	0.295	0.478	0.214	0.306	131.9
07.08.85	9.883	10.878	12.233	9.883	11.440	10.901	121.1
08.08.85	19.882	18.824	15.016	19.882	17.216	18.140	384.2
09.08.85	23.258	9.380	5.619	23.258	7.791	13.141	319.8
10.08.85	5.676	2.052	1.515	5.676	1.823	3.155	147
11.08.85	0.351	4.546	7.782	0.351	5.911	3.987	220
12.08.85	5.680	27.038	6.356	5.680	18.277	13.921	564.2
13.08.85	1.955	27.530	33.167	1.955	29.914	20.242	1064.2
14.08.85	2.176	4.902	8.357	2.176	6.371	4.920	3391.4
15.08.85	5.440	7.515	15.740	5.440	10.991	9.072	1239.2
16.08.85	6.825	25.537	0.750	6.825	15.044	12.201	595.4
17.08.85	7.497	16.815	21.800	7.497	18.941	14.984	190.4
18.08.85	0.424	1.301	2.325	0.424	1.732	1.279	1075
19.08.85	0.010	0.077	0.134	0.010	0.101	0.070	464.5
20.08.85	0.411	1.321	0.000	0.411	0.762	0.641	183.5

DATE	THF	REE INPUTS	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
<u> </u>	· · ·		· · ·	•		<u>`</u>	,
02.08.86	2.460	8.556	7.687	2.460	8.189	6.205	234.1
03.08.86	0.107	0.522	3.577	0.107	1.815	1.225	130
04.08.86	4.780	3.635		4.780	12.706	9.970	123.1
05.08.86	6.551	11.483	11.977	6.551	11.691	9.915	92.6
06.08.86	21.292	27.888	18.253	21.292	23.810	22.937	485.9
07.08.86	52.838	30.840	18.698	52.838	25.702	35.085	1891.2
08.08.86	7.904	. 6.676		7.904	8.577	8.347	1158.5
09.08.86	4.432	9.211	9.720	4.432	9.427	7.697	913.4
10.08.86	28.014	. 52.308	29.075	28.014	42.475	37.469	1860
11.08.86	13.860	25.046	27.683	13.860	26.161	21.907	4786.2
12.08.86	6.490	22.907	96.406	6.490	54.009	37.585	2492.2
13.08.86	13.314	49.952	58.955	13.314	53.763	39.769	5500
14.08.86	61.940	147.911	130.399	61.940	140.507	113.303	9640
15.08.86	69.052	37.065	43.047	69.052	39.602	49.783	10400
16.08.86	6.055	0.000	0.087	6.055	0.037	2.120	9300
17.08.86	4.065	0.067	0.000	4.065	0.039	1.432	4152.3
18.08.86	0.400	0.000	0.123	0.400	0.052	0.172	726.6
19.08.86	0.194	0.869	0.424	0.194	0.681	0.512	477.2
20.08.86	0.518	0.032	0.116	0.518		0.224	495.4
21.08.86	0.009	0.227	0.158			0.133	432.7
22.08.86	0.119	0.456	0.441	0.119		0.335	366.6
23.08.86	0.000	0.000	0.000	0.000	0.000	0.000	346.8
24.08.86	0.000	0.000	0.000	0.000	0.000	0.000	240
25.08.86	0.000	0.000	0.000	0.000	0.000	0.000	224.6
26.08.86	0.000	0.000	0.000	0.000	0.000	0.000	182.6
27.08.86	0.000	0.000	0.000	0.000	0.000	0.000	174.9

STORM NO.3 (02-08-1986 TO 27-08-1986)

STORM NO. 4 (01-07-1988 TO 11-08-1988)

DATE	THF	REE INPUT	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
					·	*	
01.07.88	3.609	0.234	1.388	3.609		1.721	70
02.07.88	0.317	8.502	27.737	0.317		11.057	90
03.07.88	34.976	34.364	35.516	34.976	35.145	35.089	100
04.07.88	7.701	6.164	4.202	7.701	5.205	6.070	
05.07.88	5.072	7.825	5.501	5.072	6.905	6.270	195
06.07.88	2.262	7.028	12.015	2.262	9.013	6.679	625
07.07.88	0.260	2.010	0.217	0.260	1.213	0.883	300
08.07.88	5.716	3.953	2.156	5.716	3.019	3.952	277.3
09.07.88	31.998	11.752	26.033	31.998	17.680	22.636	323.2
10.07.88	17.331	12.740	15.372	17.331	13.705	14.961	1179
11.07.88	7.578	1.239	6.025	7.578	3.277	4.767	433.5
12.07.88	9.381	18.802	7.986	9.381	14.273	12.579	402.2
13.07.88	18.762	20.239	21.505	18.762	20.969	20.203	565.7
14.07.88	26.930	29.813	43.351	26.930	35.206	32.345	1437
15.07.88	6.391	0.946	3.016	6.391	1.788	3.381	1183
16.07.88	2.089	0.532	0.620	2.089	0.557	1.087	315.7
17.07.88	0.201	1.922	7.706	0.201	4.370	2.928	200
18.07.88	16.367	8.493	11.029	16.367	8.865	11.466	320

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	19.07.88	47.379	47.742	38.217	47.379	43.164	44.623	3910
Ŀ	20.07.88	2.192	28.675	4.476	2.192	18.430	12.809	1863
	21.07.88	0.957	6.085	4.285	0.957	5.279	3.784	1590
Ľ	22.07.88	27.685	32.001	30.894	27.685	31.443	30.139	3500
·L	23.07.88	10.763	23.188	16.045	10.763	20.203	16.936	3500
L	24.07.88	7.258	2.410	2.313	7.258	2.405	4.085	1590
	25.07.88	6.279	7.288	7.030	6.279	7.105	6.820	1880
	26.07.88	28.932	42.047	53.876	28.932	47.066	40.792	2410
L	27.07.88	3.579	11.252	7.275	3.579	9.582	7.505	3520
· .	28.07.88	0.119	2.103	0.000	0.119	1.213	0.834	1460
Ŀ	29.07.88	0.190	0.587	1.178	0.190	0.810	0.596	750
	30.07.88	6.787	2.746	4.011	6.787	3.154	4.411	500
	31.07.88	6.124	3.651	1.457	6.124	2.672	3.866	2300
	01.08.88	0.237	0.580	0.660	0.237	0.531	0.430	1750
	02.08.88	3.935	6.541	8.907	3.935	7.665	6.375	570
	03.08.88	26.318	33.564	25.971	26.318	29.905	28.664	449.4
	04.08.88	16.773	7.240	4.607	16.773	6.120	9.805	413.7
	05.08.88	6.011	6.193	2.593	6.011	4.696	5.150	432
	06.08.88	3.361	0.077	0.000	3.361	0.034	1.185	394.5
	07.08.88	0.418	0.434	0.222	0.418	0.344	0.370	350
	08.08.88	0.000	0.011	0.000	0.000	0.005	0.003	274.6
	09.08.88	0.000	0.000	0.019	0.000	0.008	0.005	174.6
	10.08.88	0.175	0.727	0.443	0.175	0.607	0.457	129.8
	11.08.88	1.771	0.440	0.396	1.771	0.424	0.890	100.4

STORM NO. 5 (15-08-1988 TO 28-09-1988)

DATE	THF	REE INPUT	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
	-		· · · · · · · · · · · · · · · · · · ·				
15-Aug-88	0.000			0.000	0.000	0.000	70
16-Aug-88	0.000	0.039	0.000	0.000	0.017	0.011	70
17-Aug-88	0.000	0.066	0.349	0.000	0.177	0.116	60
18-Aug-88	16.491	16.130	9.252	16.491	12.988	14.202	60
19-Aug-88		17.033	20.984	19.654	18.982	19.215	2820
20-Aug-88		10.497	27.968	8.757	17.773	14.657	1615
21-Aug-88	16.039	12.893	9.656	16.039	11.499	13.070	1390
22-Aug-88	9.747	15.962	49.502	9.747	30.032	23.021	1145
23-Aug-88	18.436	11.116	17.089	18.436	13.450	15.174	3360
24-Aug-88	0.139	6.367	12.733	0.139	9.172	6.047	2770
25-Aug-88	1.433	2.291	2.456	1.433	2.431	2.086	1615
26-Aug-88	0.277	5.792	3.015	0.277	4.071	2.759	1080
27-Aug-88	7.196	0.555	3.017	7.196	1.571	3.518	850
28-Aug-88	12.560	10.534	32.710	12.560	19.762	17.272	730
29-Aug-88	7.765	13.039	27.616	7.765	19.351	15.344	1345
30-Aug-88	5.781	9.167	16.457	5.781	12.370	10.090	1320
31-Aug-88	6.707	13.415	1.395	6.707	8.041	7.578	730
1-Sep-88	0.599	6.857	6.220	0.599	6.586	4.514	1440
2-Sep-88	28.592	7.167	11.529	28.592	9.132	15.870	1360
3-Sep-88	16.826	13.848	15.567	16.826	14.633	15.391	1615
4-Sep-88	5.839	5.276	2.861	5.839	4.238	4.791	1590
5-Sep-88	5.993	2.629	2.709	5.993	2.649	3.806	1619
6-Sep-88	6.885	6.521	19.442	6.885	11.989	10.226	857.1
7-Sep-88	0.585	25.342	53.017	0.585	37.216	24.543	2130
8-Sep-88	0.129	4.119	3.689	0.129	4.070	2.706	2083

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9-Sep-88	15.302	2.725	4.583	15.302	3.381	7.506	1435
10-Sep-88	20.157	1.823	5.702	20.157	3.466	9.239	1410
11-Sep-88	5.784	0.160	0.000	5.784	0.070	2.047	1540
12-Sep-88	0.000	0.000	0.000	0.000	0.000	0.000	740.7
13-Sep-88	0.000	0.000	0.000	0.000	0.000	0.000	361.6
14-Sep-88	2.795	4.577	17.853	2.795	10.195	7.638	276
15-Sep-88	1.104	0.000	2.114	1.104	0.895	0.968	525
16-Sep-88	2.716	1.786	0.078	2.716	1.063	1.635	345.3
17-Sep-88	0.000	0.000	0.039	0.000	0.016	0.011	367.8
18-Sep-88		2.045	4.801	12.982	2.976	6.440	355
19-Sep-88		10.842	0.225	5.261	6.302	5.941	445
20-Sep-88		4.160	2.864	7.511	3.628	4.972	700
21-Sep-88		11.352	8.928	11.117	10.214	10.527	2900
22-Sep-88		19.080	2.346	22.073	11.993	15.480	1410
23-Sep-88		3.090	6.640	23.214	4.612	11.048	1085
24-Sep-88		5.473	6.529	3.366	5.785	4.949	1211
25-Sep-88		0.135	0.000	0.035	0.078	0.063	945
26-Sep-88		0.000	0.000	0.000	0.000	0.000	377.5
27-Sep-88		0.000	0.000	0.606	0.000		286.8
28-Sep-88		0.714	1:154	7.964	0.928	3.363	215

STORM NO. 6 (11-08-1989 TO 14-09-1989)

DATE	THF	REE INPUTS	S		NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARG
						<u> </u>	· · · · · · · · · · · · · · · · · · ·
11-Aug-89	6.883	3.600	1.722	6.883	2.798	4.211	29.6
12-Aug-89	5.624	13.979	4.636	5.624	10.025	8.501	101.
13-Aug-89	1.933	1.599	2.463		1.978	1.962	103.
14-Aug-89	1.889	3.019	2.706	1.889	2.883	2.539	17
15-Aug-89	0.517	1.054	0.177	0.517	0.537	0.530	70.3
16-Aug-89	2.344	0.311	0.273	2.344	0.295	1.004	31.5
17-Aug-89		14.012	20.028	24.569	16.663	19.396	
18-Aug-89		10.868	12.813	11.035	11.536	11.363	310.
19-Aug-89		52.608	19.186	33.890	38.220	36.717	184
20-Aug-89		3.464	19.930	1.519	10.390	7.325	207
21-Aug-89		5.286	10.274	0.705	7.393	5.080	900.
22-Aug-89		28.915	57.792	13.659	41.009	31.556	
23-Aug-89	1.431	16.542	14.432	1.431	15.708	10.770	553.
24-Aug-89	18.219	4.244	6.558	18.219	5.213	9.713	184
25-Aug-89		2.232	6.995	7.293	4.282	5.323	
26-Aug-89		2.516	2.463	3.079	2.342	2.597	679.
27-Aug-89			6.293	9.208	2.959	5.120	390.
28-Aug-89	·			0.000	11.708	7.662	33
29-Aug-89		2.473		0.000	8.593	5.624	303.
30-Aug-89		<u> </u>		7.886	7.492	7.630	194.
31-Aug-89			37.172	22.286	48.678	39.546	96
1-Sep-89		34.188		24.321	31.963	29.319	242
2-Sep-89		1.553		0.000	3.737	2.445	175
3-Sep-89		0.373				0.980	904.
4-Sep-89		0.000			0.000	0.037	56
5-Sep-89		0.000		0.000		0.000	276.
6-Sep-89			16.206			5.381	191.
7-Sep-89		2.313		0.000		5.260	
8-Sep-89		0.066	0.000	0.000	0.029	0.019	178.

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9-Sep-89	0.000	0.139	0.949	0.000	0.482	0.315	155.7
10-Sep-89	5.866	7.702	8.937	5.866	8.190	7.386	116.1
11-Sep-89	10.704	19.917	13.042	10.704	16.896	14.755	433.6
12-Sep-89	0.893	0.718	1.585	0.893	1.069	1.008	512.7
13-Sep-89	0.000	0.055	0.000	0.000	0.024	0.016	255.8
14-Sep-89	0.000	3.049	19.032	0.000	9.679	6.334	190.2

STORM NO. 7 (08-06-1990 TO 30-06-1990)

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DATE	THE	REE INPUT	S	TWO I	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
8-Jun-90	0.163	5.118	3.885	0.163	4.596	3.061	56.51
9-Jun-90	1.106	2.763	0.000	1:106	1.460	1.338	43.42
10-Jun-90	9.562	3.417	7.996	9.562	5.411	6.846	55
11-Jun-90	16.128	1.126	1.448	16.128	1.228	6.382	37.66
12-Jun-90	7.740	18.973	9.332	7.740	15.034	12.510	33.27
13-Jun-90	1.620	25.540	25.410	1.620	25.567	17.283	32.78
14-Jun-90	0.218	4.359	0.409	0.218	2.081	1.437	85
15-Jun-90	3.873	12.271	2.530	3.873	8.065	6.615	148.3
16-Jun-90	12.890	12.268	19.957	12.890	15.556	14.636	209.6
17-Jun-90	52.193	73.409	63.544	52.193	69.438	63.470	1115
18-Jun-90	38.645	79.894	109.381	38.645	92.486	73.865	4420
19-Jun-90	3.235	2.268	1.204	3.235	1.815	2.306	4020
20-Jun-90	4.441	1.415	0.365	4.441	0.963	2.168	1210
21-Jun-90	22.001	33.693	38.863	22.001	35.999	31.155	465
22-Jun-90	1.664	8.997	10.762	1.664	9.774	6.968	1155
23-Jun-90	1.001	0.098	0.460	1.001	0.251	0.511	530
24-Jun-90	0.198	0.000	0.019	0.198	0.008	0.074	255
25-Jun-90	4.411	0.754	2.000	4.411	1.281	2.364	105.6
26-Jun-90	0.218	0.294	6.467	0.218	2.901	1.973	85.21
27-Jun-90	0.000	0.000	0.446	0.000	0.189	0.124	62.99
28-Jun-90	7.600	5.363	1.080	7.600	3.412	4.861	54.2
29-Jun-90	7.486	0.405	0.543	7.486	0.464	2.894	45.7
30-Jun-90	6.395	7.553	4.090	6.395	6.078	6.187	39.59

STORM NO. 8 (12-07-1990 TO 31-07-1990)

	ONE INPUT	NPUTS	TWO II	S	REE INPUTS	ТНГ	DATE
DISCHARGE	RAIN (1)	RAIN (2)	RAIN (1)	RAIN (3)	RAIN (2)	RAIN(1)	
		-					
50.33	0.623	0.156	1.505	0.369	0.000	1.505	12-Jul-90
50.09	0.111	0.013	0.296	0.019	0.011	0.296	13-Jul-90
46.36	1.322	1.464	1.053	1.729	1.245	1.053	14-Jul-90
40	6.874	9.698	1.538	3.906	14.151	1.538	15-Jul-90
44.53	7.157	1.985	16.922	1.756	2.159	16.922	16-Jul-90
105.2	10.159	13.457	3.921	17.564	10.484	3.921	17-Jul-90
223.9	8.802	12.337	2.116	16.115	9.587	2.116	18-Jul-90
420	6.074	8.567	1.363	8.343	9.313	1.363	19-Jul-90
660	22.711	28.339	12.074	29.459	27.135	12.074	20-Jul-90
1200	42.492	49.757	28.762	50.376	49.383	28.762	21-Jul-90
1470	8.852	6.757	12.816	9.322	4.892	12.816	22-Jul-90
530	18.209	22.734	9.661	24.475	21.653	9.661	23-Jul-90
3550	59.634	73.282	33.835	63.962	80.951	33.835	24-Jul-90

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	<u> </u>			F 0 (0)	40.000	0.700	4060
25-Jul-90	5.613	14.128	5.270	5.613	10.350	8.709	
26-Jul-90	2.233	1.935	1.296	2.233	1.602	1.820	
27-Jul-90	0.691	0.945	1.226	0.691	1.080	0.945	865
28-Jul-90		0.756	5.096	0.000	2.597	1.699	405
		4.059	11.326	6.014		6.794	320
29-Jul-90				3.063	0.037	1.084	207.4
30-Jul- <u>90</u>	3.063	0.011	0.073				
31-Jul-90	0.000	0.000	0.000	0.000	0.000	0.000	191.5

VERIFICATION PERIOD

STORM NO. 9 (04-08-1990 TO 21-09-1990)

DATE	THF	REE INPUTS	6			ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
	· · · · · · · · · · · · · · · · · · ·	, <u></u>					
4-Aug-90	1.797	2.245	0.000	1.797	1.215		108.4
5-Aug-90		0.000	0.000			0.007	
6-Aug-90		0.177	0.000		0.077		
7-Aug-90		18.358	4.772		12.580	14.221	
8-Aug-90		60.567	108.809		81.252		789
9-Aug-90		22.735	1.404		13.703		
10-Aug-90		0.000	0.000		0.000		
11-Aug-90		3.833	17.329		9.528	+	
12-Aug-90		0.000	0.000	2.078	0.000		
13-Aug-90			8.757	1.593	9.216		
14-Aug-90			3.441				
15-Aug-90			3.402	1.713			
16-Aug-90		·	125.366	36.988	112.516		
17-Aug-90			43.177		38.023		4460
18-Aug-90	·		8.534	0.736	9.503		
19-Aug-90			1.448	4.547		the second se	
20-Aug-90			17.271	10.311			
21-Aug-90			5.215	0.673			
22-Aug-90		18.291	12.984			the second se	
23-Aug-90			162.594		· · · · · · · · · · · · · · · · · · ·		
24-Aug-90		0.896	0.602				
25-Aug-90		1.978	1.125				
26-Aug-90		0.119					
27-Aug-90		55.540					
28-Aug-90		0.110	0.000				
29-Aug-90		29.356	15.857				
30-Aug-90		35.179	30.761				
31-Aug-90		26.810	26.095				
1-Sep-90	1.294	0.897	0.649				
2-Sep-90		1.064	3.907				
3-Sep-90		0.000					
4-Sep-90		0.033	0.096				
5-Sep-90		1.287					
6-Sep-90		4.872					
7-Sep-90		10.154					
8-Sep-90							
9-Sep-90							
10-Sep-90					1		
11-Sep-90							
12-Sep-90	0.682	0.000	0.000	0.682	0.000		323.9

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13-Sep-90		0.673	0.000	0.000	0.293	0.192	250.1
14-Sep-90	1.186	2.542	2.024	1.186	1.994	1.715	238.7
15-Sep-90		3.086	3.152	3.068	3.211	3.162	269.4
16-Sep-90		0.000	0.000	0.059	0.000	0.021	240
17-Sep-90	0.262	0.608	0.000	0.262	0.351	0.320	192.1
18-Sep-90		0.000	0.000	0.000	0.000	0.000	157.2
19-Sep-90		0.000	0.000	0.000	0.000	0.000	159.5
20-Sep-90	1.256	0.000	0.000	1.256	0.000	0.435	153.2
21-Sep-90	0.000	0.000	0.000	0.000	0.000	0.000	136.4

STORM NO. 10 (21-07-1993 TO 17-08-1993)

DATE	THREE INPUTS			TWO I	NPUTS	ONE INPUT				
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE			
21-Jul-93	0.000	0.000	0.000	0.000	0.000	0.000	28.56			
22-Jul-93	0.000	0.000	0.000	0.000	0.000	0.000	25.26			
23-Jul-93	0.000	0.000	0.000	0.000	0.000	0.000	21.19			
24-Jul-93	0.000	0.000	1.340	0	0.567	0.371	17.55			
25-Jul-93	0.000	0.358	0.336	0	0.354	0.232	14.5			
26-Jul-93	0.316	10.066	12.405	0.316	11.181	7.423	28.8			
27-Jul-93	0.423	7.537	12.790	0.423	9.868	6.602	111.9			
28-Jul-93	23.944	18.704	17.666	23.944	18.273	20.236	121.6			
29-Jul-93	7.917	15.533	21.193	7.917	18.005	14.516	422.1			
30-Jul-93	0.547	17.306	13.359	0.547	15.749	10.490	1274			
31-Jul-93	1.391	27.688	12.000	1.391	31.101	20.820	2014			
1-Aug-93	4.757	5.368	17.162	4.757	10.355	8.418	969.9			
2-Aug-93	5.985	12.915	14.613	5.985	13.625	10.983	290.4			
3-Aug-93	0.334	15.294	13.185	0.334	14.557	9.636	387.5			
4-Aug-93	21.467	17.385	16.052	21.467	16.864	18.457	1247			
5-Aug-93	31.223	9.279	17.735	31.223	12.841	19.200	636.1			
6-Aug-93	5.086	13.946	15.063	5.086	14.476	11.228	484.4			
7-Aug-93	0.587	3.507	8.332	0.587	5.548	3.832	253.9			
8-Aug-93	0.770	0.186	0.500	0.770	0.319	0.474	159.7			
9-Aug-93	0.000	0.000	0.772	0.000	0.327	0.214	111.4			
10-Aug-93	0.000	0.019	0.000	0.000	0.011	0.007	71.47			
11-Aug-93	0.262	2.619	2.239	0.262	2.497	1.724	49.21			
12-Aug-93	0.000	0.467	1.053	0.000	0.715	0.468	40.09			
13-Aug-93	0.000	1.944	0.000	0.000	1.121	0.733	31.23			
14-Aug-93	2.586	0.793	0.451	2.586	0.627	1.305	27.06			
15-Aug-93	0.000	0.371	0.681	0.000	0.503	0.329	23.58			
16-Aug-93	12.339	3.084	12.095	12.339	6.878	8.768	22.62			
17-Aug-93	5.556	11.219	21.728	5.556	15.666	12.168	27.47			

STORM NO. 11 (13-07-1995 TO 31-07-1995)

DATE	THREE INPUTS			TWO I	NPUTS	ONE INPUT		
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE	
13-Jul-95	7.435	4.981	2.568	7.435	3.998	5.187	38.1	
14-Jul-95	6.548	12.436	11.739	6.548	12.154	10.215	144.8	
_15-Jul-95	18.907	39.352	32.954	18.907	36.645	30.506	121.7	
16-Jul-95	10.958	14.378	8.669	10.958	11.951	11.606	604.9	
17-Jul-95	7.457	3.024	9.465	7.457	5.736	6.331	339	

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139.4	4.253	5.796	1.331	6.174	5.463	1.331	18-Jul-95
127.8	13.208	16.401	7.172	13.766	18.321	7.172	19-Jul-95
548.2	36.830	45.442	20.547	45.227	45.364	20.547	20-Jul-95
661.9	9.549	9.883	.8.920	6.744	12.254	8.920	21-Jul-95
526.1	7.910	8.297	7.182	8.795	7.949	7.182	22-Jul-95
336.5	3.893	5.046	1.708	6.610	3.889	1.708	23-Jul-95
190.6	25.619	26.487	23.982	22.255	29.610	23.982	24-Jul-95
2162	39.764	34.395	49.918	29.667	37.920	49.918	25-Jul-95
952.3	3.472	2.705	4.919	0.169	4.592	4.919	26-Jul-95
687.6	2.236	1.309	3.990	0.634	1.785	3.990	27-Jul-95
470.5	0.239	0.365	0.000	0.863	0.000	. 0.000	28-Jul-95
317.2	3.563	2.456	5.653	3.347	1.818	5.653	29-Jul-95
271.6	9.827	9.756	9.962	5.571	12.861	9.962	30-Jul-95
456.3	1.871	2.373	0.917	2.702	2.154	0.917	31-Jul-95

STORM NO.12 (24-08-1995 TO 14-09-1995)

DATE	THREE INPUTS			TWO	NPUTS	ONE INPUT	
	RAIN(1)	RAIN (2)	RAIN (3)	RAIN (1)	RAIN (2)	RAIN (1)	DISCHARGE
24-Aug-95	1.521	0.956	2.120	1.521	1.449		
25-Aug-95	0.041	1.541	0.910	0.041	1.273	0.847	51.02
26-Aug-95	0.017	8.356	12.264	0.017	9.975	6.532	53.18
27-Aug-95	10.712	2.178	4.615	10.712	3.194	5.796	81.32
28-Aug-95	1.377	26.014	24.288	1.377	25.260	16.990	
29-Aug-95	0.065	2.026	1.827	0.065	1.937	1.289	
30-Aug-95	1.944	8.855	1.771	1.944	5.858	4.507	142.1
31-Aug-95	9.934	17.163	17.336	9,934	17.186	14.681	168.4
1-Sep-95	11.381	82.408	98.719	11.381	89.233	62.303	2081
2-Sep-95	85.949	66.587	63.542	85.949	65.144	72.345	5661
3-Sep-95	23.442	10.168	3.739	23.442	7.458	12.987	5024
4-Sep-95	2.743	3.169	7.033	2.743	4.813	4.096	1448
5-Sep-95	0.000	0.000	0.000	0.000	0.000	0.000	567.8
6-Sep-95	0.000	0.000	0.000	0.000	0.000	0.000	
7-Sep-95	0.000	0.000	0.000	0.000	0.000	0.000	243.2
8-Sep-95	0.000	3.674	0.000	0.000	2.117	1.386	522.4
9-Sep-95	0.000	0.000	0.860	0.000	0.364	0.238	
10-Sep-95	0.000	0.000	0.000	0.000	0.000	0.000	229.6
11-Sep-95	0.000	0.000	0.000	0.000	0.000	0.000	230.4
12-Sep-95	3.783	7.545	5.748	3.783		5.756	
13-Sep-95	0.753	8.749	9.456	0.753		6.159	
14-Sep-95	1.803	14.996	33.054	1.803	22.541	15.371	319.4