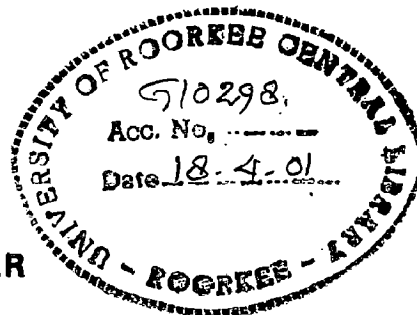


GROUNDWATER MODELLING USING AN IMPROVED FINITE DIFFERENCE SCHEME

A DISSERTATION

submitted in partial fulfilment of the
requirements for the award of the degree
of
MASTER OF ENGINEERING
in
IRRIGATION WATER MANAGEMENT

By
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CANDIDATE'S DECLARATION

I hereby declare that the work, which is being presented in this dissertation entitled "**GROUNDWATER MODELLING USING AN IMPROVED FINITE DIFFERENCE SCHEME**" in the partial fulfillment of the requirement for the award of Degree of **Master of Engineering in Irrigation Water Management** and submitted in the department of Water Resources Development training center of the University, is an authentic record of my own work carried out during a period of July 2000 to Feb. 2001 under the supervision of **Dr. G.C. Mishra**, Professor, Water Resources Development Training Center, University of Roorkee, Roorkee.

The matter presented in this dissertation has not been submitted by me for award of any other degree.

Dated: February, 2001

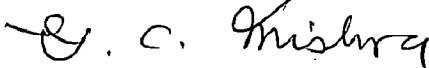
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This is to certify that the statement made by the candidate is correct to the best of my knowledge.

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**Trainee officer,
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NOTATIONS

D	thickness of the aquifer, (L);
$h(j, k)$	piezometric head at node (j) during k^{th} time step, (L);
K	hydraulic conductivity of the aquifer, (LT^{-1});
t	time, (T);
T	transmissivity of the aquifer, (L^2T^{-1});
$T_{HM2(j)}$	Harmonic mean transmissivity at interface 2 of node (j), (L^2T^{-1});
$T_{HM4(j)}$	Harmonic mean transmissivity at interface 4 of node (j), (L^2T^{-1});
x	distance measured from stream aquifer interface, (L);
S	storage coefficient of the aquifer, (dimensionless);
β	hydraulic diffusivity of the aquifer, (L^2T^{-1});
Γ	reach transmissivity of the stream, (L^2T^{-1});
$f(t)$	time varying boundary perturbation;
$f'(t)$	time derivative of the input function;
$\alpha(x, \Delta t, m)$	discrete pulse kernel (fully penetrating stream);
$\delta(x, \Delta t, m)$	discrete ramp kernel (fully penetrating stream);
Δt	size of uniform time step, (T);
Δv	volume of water entering during time step, (L^3);

SYNOPSIS

In the existing finite difference method, the flow (inflow/outflow) is assumed to follow a linear variation with time where as the spatial variation is non-linear and quadratic in nature. In case of a non-homogeneous, semi-infinite aquifer bounded by a fully penetrating stream, the flow rate at the boundary subsequent to a sudden change in boundary head varies inversely to a square root of time. Therefore the variation of flow at any section can be presumed to be non-linear with time. In improved finite difference scheme, non-linear temporal variation i.e. quadratic in nature has been taken in account. Further in a non-homogeneous case the head variation is sharp within small distance. Therefore a spatial variation may follow a polynomial equation of higher degree. This spatial variation is also accounted in Improved finite difference method. Thus proposed finite difference method that includes both temporal and spatial variation in consideration may give efficient results.

All numerical methods exhibit oscillations in computed head. This oscillation is prominent at grids adjacent to the boundary. In all these methods, inflow is not accounted truly. The oscillation can be minimized if the inflow is properly accounted for.

CHAPTER 1

INTRODUCTION

1.1 GENERAL

With the advancement of high-speed computers, numerical methods are exclusively used in analyzing groundwater flow problems. For ideal situations, groundwater flow problems are solved by combining Darcy's equation and continuity equation. The resulting differential equations describe the hydraulic relations within an aquifer. To solve the equations, the aquifer geometry, hydraulic characteristics, initial and boundary conditions should be known. An exact analytical solution can be obtained only if the equations, characteristic and conditions are simple. There are many groundwater flow problems for which analytic solutions are difficult. The reason is that these problems are complex, possessing non-linear features that cannot be included in analytical solutions. Owing to these difficulties, there has been a need for some techniques that enable meaningful solution to the above problems. Such technique exists in numerical modeling.

In most numerical techniques, an approximate solution is obtained by replacing the basic differential equations by another sets of equations that can be solved easily by a computer. Finite difference method is one of them.

1.2 FINITE DIFFERENCE METHOD

In finite difference method space are divided into small but finite intervals. The small areas thus formed are called nodal areas. There is a point called node in each small area, which is considered to be the representative of its nodal area. A certain storage coefficient and transmissivity is assigned to each node. Now for each node point, an equation is written combining Darcy's and continuity equation. The resulting equation thus obtained are classified into explicit, implicit and crank nicholson approximation based on the assumption of variables at different space and time. In case of implicit and crank nicholson scheme, a set of equations are obtained which can be solved either by

Gauss elimination or Gauss-Siedel iteration method. In this thesis both schemes are used to analyze interaction of a fully penetrating stream and a semi-infinite aquifer. A comparative study is done for step input and ramp input.

1.3 IMPROVED FINITE DIFFERENCE METHOD

In existing finite difference method the flow (inflow/outflow) is assumed to vary linearly with time. However flow may vary non-linearly with time. The hydraulic head is also assumed to vary linearly with distance between the grid while mass balance is carried out or when the higher order term are neglected to write the finite difference of the governing differential equation.

In improved finite difference method, it has been assumed that:

i) flow variation with time at a particular section follows a quadratic distribution.

$$\text{i.e. } h(x,t) = f(t) = a_1 + b_1 t + c_1 t^2$$

ii) head between nodes at a particular time follows a polynomial equation as given below:

$$h(x,t) = a + b x + c x^2 + d x^3$$

Where a_1, b_1, c_1 are derived in terms of $h(j, t-\Delta t), h(j, t), h(j, t+\Delta t)$ and a, b, c, d are derived in terms of $h(j-1, t), h(j, t), h(j+1, t)$ and $h(j+2, t)$.

1.4 ANALYTIC METHOD

The unit step response function that relates rise in piezometric surface in an initially steady-state semiinfinite homogeneous and isotropic confined aquifer, bounded by a fully penetrating straight stream, to a step rise in stream stage has been derived by Carslaw and Jaegar(1959) for an analogous heat conduction problem. The unit step response function is:

$$K(x,t) = \text{erfc} \left\{ \frac{x}{\sqrt{4\beta t}} \right\} \quad \dots(1.1)$$

Where x = distance from the bank of the stream,

t = time measured since the onset of change in stream stage,

β = hydraulic diffusivity of the aquifer defined as ratio of transmissivity to storage coefficient,

$erfc\{\cdot\}$ = complementary error function.

For varying stream stage, $\sigma(t)$, the rise in piezometric surface, $s(x, t)$, according to Duhamel's integral (Thomson 1950) is given by

$$s(x, t) = \sigma_0 K(x, t) + \int_0^t K(x, t - \tau) \frac{d\sigma(\tau)}{d\tau} d\tau \quad \dots (1.2)$$

Where σ_0 = initial sudden rise in the stream stage,

τ = time variable.

Duhamel's integral, which can be expressed in two different forms (Thomson, 1950), has been used extensively for solving stream-aquifer interaction problems (Pinder et al. 1969; Venetis 1970; Hall and Moench 1972; Abdulrazzak and Morel- Seytoux 1983; Morel - Seytoux 1988). The time span is discretized into uniform time steps of size Δt . The rate of change of stream stage, $d\sigma(\tau)/d\tau$, is assumed to be a constant within a time step which may vary from one time step to the next. Equation 2 is rewritten in terms of discrete kernel coefficient as:

$$s(x, n\Delta t) = \sigma_0 \operatorname{erfc}\left\{\frac{x}{\sqrt{4\beta n\Delta t}}\right\} + \sum_{\gamma=1}^n [(\sigma_\gamma - \sigma_{\gamma-1})\delta_\gamma(x, \Delta t, n - \gamma + 1)] \quad \dots (1.3)$$

1.5 THE SCOPE OF STUDY

CASE1:

In numerical method the head at node near the boundary sometimes exceeds the boundary head even though there is no external recharge other than the stream, and the head at the node near the boundary oscillate exhibiting unacceptable values. It is intended

to study whether oscillation is caused because of the boundary condition i.e. sudden change in stream stage causing infinite rate in flow or due to coarse time and space grid. The analysis has been considering a step input and a ramp input. Crank Nicholson method, completely implicit scheme and non-linear variation in flow rate have been considered separately to study the oscillation and convergence encountered in numerical method.

CASE2:

Polynomial spatial variation in head at a particular time has been considered and aquifer response to step and ramp variation has been obtained. The results obtained using numerical method have been compared with analytical results. The performance of the methods has been evaluated. The stream aquifer interaction has been used to study the performance.

CHAPTER 2
REVIEW OF LITERATURE

2.1 FINITE DIFFERENCE METHOD

Groundwater flow problem is solved by numerical methods. Finite difference method is one of them which is fairly simple and straight forward but the application of the model to a given physical system can be complex and requires considerable judgement and skill in setting up the problem and in interpretation of the result. Thus it should not be viewed as a replacement for the analytic method, but rather as a tool for the evaluation of complex groundwater flows. Here we consider a simple one-dimensional flow in homogeneous, isotropic and confined aquifer.

2.2 ONE DIMENSIONAL FLOW IN A CONFINED AQUIFER

Let us consider the nonsteady, one-dimensional flow in a confined aquifer.

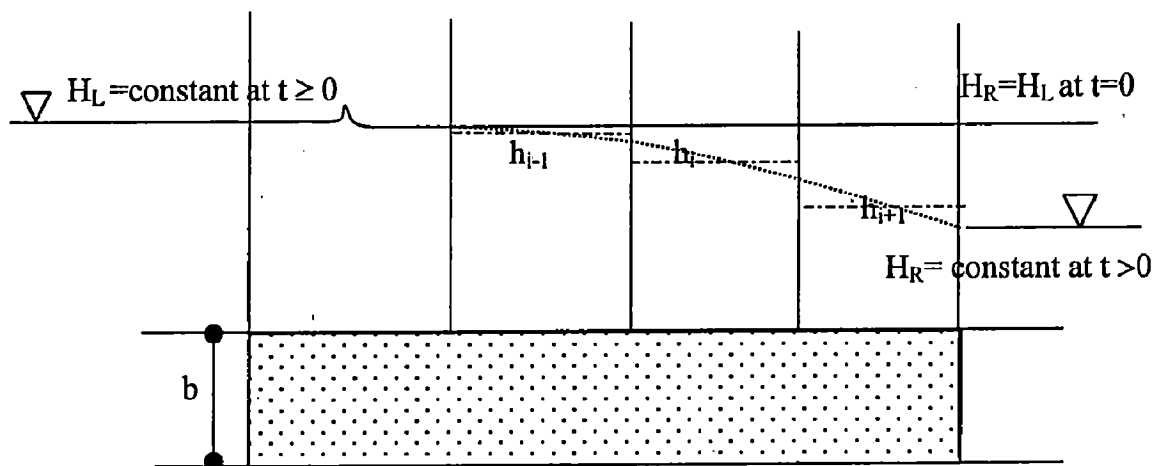


Fig. 2.1: Sectional view of a one-dimensional flow domain

Schematic diagrams showing sectional view and plan of a one-dimensional confined flow domain are shown in fig.2.1 and fig.2.2 respectively.

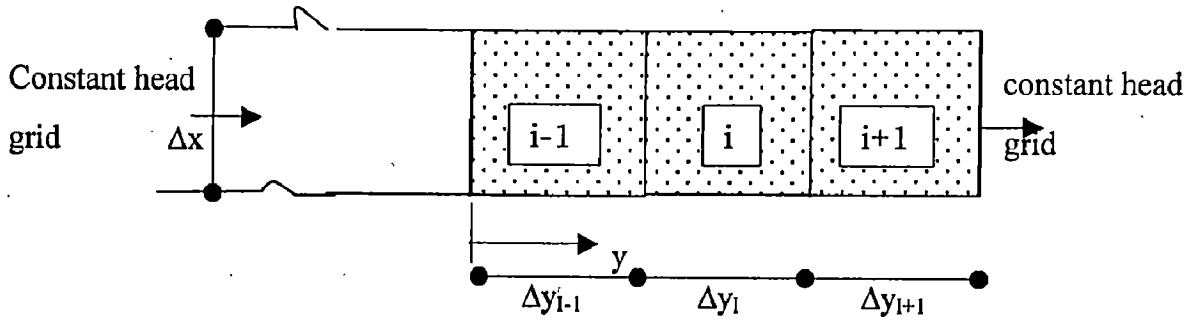


Fig. 2.2: Plan of the one dimensional aquifer

Let for grid (i), K_i be the hydraulic conductivity, Δy_i be the grid dimension,

b be the aquifer thickness, S be the storage coefficient and h_i be the initial value of head .

Let us consider a homogeneous and isotropic aquifer of constant thickness.

Let $\Delta x=1$; $\Delta y_{i-1} = \Delta y_i = \Delta y_{i+1} = \Delta y$;

Now for grid (i), inflow ($Q_{i-1 \rightarrow i}$) is given as:

$$Q_{i-1 \rightarrow i} = - kA \frac{h(i, n) - h(i-1, n)}{\Delta y}$$

where in $h(i,n)$, i refers to the grid number and n to the selected time.

Now the area A is the product of Δx and b , equation becomes:

$$Q_{i-1 \rightarrow i} = - T \frac{h(i, n) - h(i-1, n)}{\Delta y} \quad \dots(2.1)$$

where T be the transmissivity of the aquifer.

Likewise for grid (i), outflow ($Q_{i \rightarrow i+1}$) is given by:

$$Q_{i \rightarrow i+1} = - T \frac{h(i+1, n) - h(i, n)}{\Delta y} \quad \dots(2.2)$$

Performing the mass balance over a time period Δt

Inflow-outflow = change in storage

$$(Q_{i-1 \rightarrow i} - Q_{i \rightarrow i+1})\Delta t = \Delta v_i$$

$$\text{where } \Delta v_i = S \Delta y \{h(i, t + \Delta t) - h(i, t)\} \quad \dots(2.3)$$

Introducing (2.1) & (2.2) in (2.3) and simplifying

$$\left[-T \left\{ \frac{h(i, n) - h(i-1, n)}{\Delta y} \right\} \right] - \left[-T \left\{ \frac{h(i+1, n) - h(i, n)}{\Delta y} \right\} \right] = S \Delta y \left\{ \frac{h(i, t + \Delta t) - h(i, t)}{\Delta t} \right\}$$

This can be rearranged to yield

$$h(i+1, n) - 2h(i, n) + h(i-1, n) = \frac{S}{T} \frac{(\Delta y)^2}{\Delta t} \{h(i, t + \Delta t) - h(i, t)\} \quad \dots(2.4)$$

If $n = t$ (the present known value), then *the explicit or forward difference equation* is obtained. On the other hand if $n = t + \Delta t$, then it becomes an *implicit or backward equation*.

2.2.1 Forward Difference Equation or Explicit Solution

The forward difference equation is expressed as:

$$h(i, t + \Delta t) = \frac{T \Delta t}{S (\Delta y)^2} \{h(i+1, t) + h(i-1, t)\} + h(i, t) \left(1 - \frac{2T \Delta t}{S \Delta y^2} \right) \quad \dots(2.5)$$

The space derivative are centered at the beginning of time step and the only unknown is $h(i, t + \Delta t)$ which results from time derivatives. The solution represented by above equation is only an approximation of the exact solution. The degree to which the equation approximates to the exact solution depends upon the selection of Δy and Δt . For a particular value of Δy and Δt , the difference between the approximate and exact solution may grow as t increases. The approximate solution is said to be unstable in this case.

In a one-dimensional case a stable solution is ensured, if

$$\frac{T\Delta t}{S(\Delta y)^2} < \frac{1}{2} \quad \dots(2.6)$$

Consequently the time increment cannot be selected independently of the space increment.

2.2.2 Backward Difference Equation or Implicit Solution

The backward difference equation is obtained by putting $n = t + \Delta t$.

$$h(i+1, t + \Delta t) - 2h(i, t + \Delta t) + h(i-1, t + \Delta t) = \frac{S\Delta y^2}{T\Delta t} \{h(i, t + \Delta t) - h(i, t)\}$$

Rearranging the above equation, we have

$$h(i+1, t + \Delta t) - \left(2 + \frac{S\Delta y^2}{T\Delta t}\right) h(i, t + \Delta t) + h(i-1, t + \Delta t) = -\left(\frac{S\Delta y^2}{T\Delta t}\right) h(i, t) \quad \dots(2.7)$$

Here the head in grid (i) at time $t+\Delta t$ depends upon the value of head in the adjacent grid (i+1) and (i-1). Thus equations represent a set of algebraic equations that can be solved simultaneously. By analysis it is seen that stability is not a problem with the backward difference equation and space increment (Δy) and (Δt) can be selected independent of each other. The selection of the values for space and time increment depends upon the user's requirement, for accuracy, detail of analysis and availability of data.

2.2.3 Crank Nicholson Approximation

The Crank Nicholson equation for one-dimensional flow in a homogeneous, isotropic and confined aquifer is expressed as:

$$w \left\{ \frac{h(i+1, t + \Delta t) - 2h(i, t + \Delta t) + h(i-1, t + \Delta t)}{(\Delta y)^2} \right\} + (1-w) \left\{ \frac{h(i+1, t) - 2h(i, t) + h(i-1, t)}{(\Delta y)^2} \right\} = \frac{S}{T\Delta t} \{h(i, t + \Delta t) - h(i, t)\}$$

In Crank Nicholson Scheme, $w = 1/2$. Above equation shows that Crank Nicholson approximation is the result of successive application of the explicit and implicit method. It can be rearranged as:

$$h(i+1, t + \Delta t) - \left\{ 2 + 2 \frac{S(\Delta y)^2}{T\Delta t} \right\} h(i, t + \Delta t) + h(i-1, t + \Delta t) = - \frac{S\Delta y^2}{T\Delta t} h(i, t) - \left\{ h(i+1, t) - \left(2 + \frac{S\Delta y^2}{T\Delta t} \right) h(i, t) + h(i-1, t) \right\} \quad \dots(2.8)$$

The equation is identical to the implicit equation and its solution procedure is also same.

The Crank Nicholson equation, although stable for all values of Δy and Δt , has the potential for severe oscillations of the computed heads. The solution oscillates about the true value and for some cases, the oscillations become insignificant after sufficiently long period of time (Rushton 1973). The oscillation cannot be predicted in advance but the severity depends upon the boundary and initial conditions. Small values of Δt tend to reduce the severity of oscillations.

2.3 ANALYTIC SOLUTION

To find the aquifer responses (piezometric head, flow, volume etc.) for any arbitrary variation in the stream stage, convolution principle (also known as Duhamel's theorem), which utilizes the respective unit response function and the boundary perturbation is applicable. The response of a linear stream- aquifer system to a unit step perturbation is a basic property of the system. Many investigators (Hall 1968, 1969, Venetis 1970; Moench and Kisiel 1970; Morel -Seytoux 1975; Morel-Seytoux and Daly 1975) have applied convolution principles for solving groundwater flow problems. Response of a linear system to a time varying input using convolution integral may be written (Thomson 1957, Venetis 1970) in two ways as;

$$y(x,t) = \int_0^t f(\tau)u(x,t-\tau)d\tau \quad \dots(2.9)$$

$$\text{or } y''(x,t) = \int_0^t f'(\tau)U(x,t-\tau)d\tau \quad \dots(2.10)$$

where $y(x,t)$ = Response of the system after time t since the beginning of the system input(boundary perturbation).

$f(t)$ = time varying boundary perturbation.

$u(x,t)$ = instantaneous response function of the system.

$U(x,t)$ = unit step response function of the system.

$f'(x,t)$ = Time derivative of the input function.

If the system response is not zero at $t = 0$, equation 2 gets modified as:

$$y(x,t) = f(0)U(t) + \int_0^t f'(\tau)U(x,t-\tau)d\tau \quad \dots(2.11)$$

The convolution integrals appearing in equation 2.9 & 2.11 may be solved by using two discrete kernels approach i.e. discrete pulse kernel and discrete ramp kernel approach.

2.3.1 Discrete Pulse Kernel

Discretizing the time step into uniform time steps and assuming the input to be invariant during a time step equation 2.9 can be written as:

$$y(x, n\Delta t) = \sum_{\gamma=1}^n f(\gamma \Delta t) \int_{(\gamma-1)\Delta t}^{\gamma \Delta t} u(x, n\Delta t - \tau) d\tau$$

$$\text{or } y(x, n\Delta t) = \sum_{\gamma=1}^n f(\gamma) \alpha(x, \Delta t, n - \gamma + 1) \quad \dots(2.12)$$

where $\alpha(\cdot)$ is the discrete pulse kernel expressed as:

$$\alpha(x, \Delta t, m) = \int_{(m-1)\Delta t}^{m\Delta t} u(x, \tau) d\tau = U(x, m\Delta t) - U(x, (m-1)\Delta t) \quad \dots(2.13)$$

In case of a stream, the discrete pulse kernel is the response of the aquifer to a unit step rise in stream stage which continues only for a period Δt . The application of this kernel requires the time variation of input to be discretized as a train of pulses of uniform duration Δt and input is considered uniform over a time step.

$$w \left\{ \frac{h(i+1, t+\Delta t) - 2h(i, t+\Delta t) + h(i-1, t+\Delta t)}{(\Delta y)^2} \right\} + (1-w) \left\{ \frac{h(i+1, t) - 2h(i, t) + h(i-1, t)}{(\Delta y)^2} \right\} = \frac{S}{T\Delta t} \{h(i, t+\Delta t) - h(i, t)\}$$

In Crank Nicholson Scheme, $w = 1/2$. Above equation shows that Crank Nicholson approximation is the result of successive application of the explicit and implicit method. It can be rearranged as:

$$h(i+1, t+\Delta t) - \left\{ 2 + 2 \frac{S(\Delta y)^2}{T\Delta t} \right\} h(i, t+\Delta t) + h(i-1, t+\Delta t) = - \frac{S\Delta y^2}{T\Delta t} h(i, t) - \left\{ h(i+1, t) - \left(2 + \frac{S\Delta y^2}{T\Delta t} \right) h(i, t) + h(i-1, t) \right\} \quad \dots(2.8)$$

The equation is identical to the implicit equation and its solution procedure is also same.

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where $y(x,t)$ = Response of the system after time t since the beginning of the system input(boundary perturbation).

$f(t)$ = time varying boundary perturbation.

$u(x,t)$ = instantaneous response function of the system.

$U(x,t)$ = unit step response function of the system.

$f'(x,t)$ = Time derivative of the input function.

If the system response is not zero at $t = 0$, equation 2 gets modified as:

$$y(x,t) = f(0)U(t) + \int_0^t f'(\tau)U(x,t-\tau)d\tau \quad \dots(2.11)$$

The convolution integrals appearing in equation 2.9 & 2.11 may be solved by using two discrete kernels approach i.e. discrete pulse kernel and discrete ramp kernel approach.

2.3.1 Discrete Pulse Kernel

Discretizing the time step into uniform time steps and assuming the input to be invariant during a time step equation 2.9 can be written as:

$$y(x,n\Delta t) = \sum_{\gamma=1}^n f(\gamma \Delta t) \int_{(\gamma-1)\Delta t}^{\gamma \Delta t} u(x,n\Delta t-\tau)d\tau$$

$$\text{or } y(x,n\Delta t) = \sum_{\gamma=1}^n f(\gamma)\alpha(x,\Delta t,n-\gamma+1) \quad \dots(2.12)$$

where $\alpha(\cdot)$ is the discrete pulse kernel expressed as:

$$\alpha(x,\Delta t,m) = \int_{(m-1)\Delta t}^{m\Delta t} u(x,\tau)d\tau = U(x,m\Delta t) - U(x,(m-1)\Delta t) \quad \dots(2.13)$$

In case of a stream, the discrete pulse kernel is the response of the aquifer to a unit step rise in stream stage which continues only for a period Δt . The application of this kernel requires the time variation of input to be discretized as a train of pulses of uniform duration Δt and input is considered uniform over a time step.

2.3.2 Discrete Ramp Kernel

Assuming slope of the input to be invariant during a time step, equation 2.10 may be written in discretized form as:

$$y(x, n\Delta t) = \sum_{\gamma=1}^n \frac{f(\gamma \Delta t) - f(\gamma-1)\Delta t}{\Delta t} \int_{(\gamma-1)\Delta t}^{\gamma\Delta t} U(x, n\Delta t - \tau) d\tau$$

$$y(x, n\Delta t) = \sum_{\gamma=1}^n \frac{f(\gamma\Delta t) - f(\gamma-1)\Delta t}{\Delta t} \delta(x, \Delta t, n - \gamma + 1) \quad \dots(2.14)$$

where $\delta(\cdot)$ is defined as discrete ramp kernel.

The application of this kernel requires the time variation of input to be approximated as a series of incremental discrete ramps. This approach assumes that the slope of the perturbation (input) is constant during a time step. Therefore the use of discrete ramp kernel logically, should give superior results as compared to that obtained during discrete pulse kernel.

CHAPTER 3
AN IMPROVED FINITE DIFFERENCE SCHEME
ACCOUNTING TEMPORAL VARIATION

3.1 INTRODUCTION

In Crank Nicholson finite difference scheme it is implied that the variation of flow with time during t_0 to $t_0+\Delta t$ is linear. In completely implicit scheme it is implied that flow rate is constant within the time step Δt and is equal to the rate that prevails at $t_0+\Delta t$. In the explicit scheme it is implied that the flow rate during the time interval is also constant but equal to the flow rate that prevails at the initial time t_0 . The Crank Nicholson technique though rigorously accounts for mass balance, it is found that piezometric head computed by Crank Nicholson scheme exhibits oscillation. The oscillation may be due to sudden step rise in boundary head causing mathematically infinite rate of inflow at the boundary at time t_0 . It is known that the flow rate at the boundary subsequent to a sudden change in boundary head varies inversely to square root of time. Therefore the variation of flow with time at any section can be presumed to be non-linear. A finite difference scheme is developed that accounts for non-linear variation of flow at any section.

3.2 STATEMENT OF THE PROBLEM

In the proposed finite difference scheme, it is assumed that during a time interval $(t_0-\Delta t_2)$ to $(t_0+\Delta t_1)$, the flow at a section follows a quadratic distribution. The flow, $q(t)$, is expressed as:

$$q(t) = a_1 + b_1(t-t_0) + c_1(t-t_0)^2$$

in which a_1, b_1, c_1 are constants to be determined.

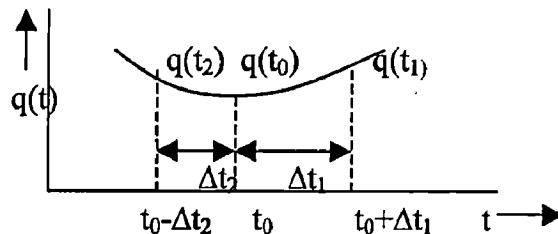


Fig.3.1 Variation of flow with time at a particular section

Since at $t = t_0$, $q(t) = q(t_0)$

$$a_1 = q(t_0) \quad \dots(3.1)$$

At $t = t_0 + \Delta t_1$, $q(t) = q(t_1)$

$$= a_1 + b_1 \Delta t_1 + c_1 \Delta t_1^2 \quad \dots(3.2)$$

At $t = t_0 - \Delta t_2$, $q(t) = q(t_2)$

$$= a_1 - b_1 \Delta t_2 + c_1 \Delta t_2^2 \quad \dots(3.3)$$

From equation (3.1), (3.2), & (3.3)

$$a_1 = q(t_0)$$

$$b_1 = \frac{q(t_1) - q(t_0)}{\Delta t_1} - \frac{\Delta t_1}{\Delta t_1 + \Delta t_2} \left\{ \frac{q(t_1) - q(t_0)}{\Delta t_1} + \frac{q(t_2) - q(t_0)}{\Delta t_2} \right\}$$

$$c_1 = \frac{1}{\Delta t_1 + \Delta t_2} \left\{ \frac{q(t_1) - q(t_0)}{\Delta t_1} + \frac{q(t_2) - q(t_0)}{\Delta t_2} \right\}$$

The volume of flow $V(\Delta t_1)$ passing through the section during time interval t_0 to $t_0 + \Delta t_1$

$$\begin{aligned} &= \int_{t_0}^{t_0 + \Delta t_1} q(t) dt \\ &= \int_{t_0}^{t_0 + \Delta t_1} \{ a_1 + b_1(t - t_0) + c_1(t - t_0)^2 \} dt \\ &= \int_0^{\Delta t_1} (a_1 + b_1 \tau + c_1 \tau^2) d\tau \\ &= a_1 \Delta t_1 + b_1 \frac{\Delta t_1^2}{2} + c_1 \frac{\Delta t_1^3}{3} \end{aligned}$$

Putting the values of a_1 , b_1 , c_1 we get

$$\begin{aligned} V(\Delta t_1) &= q(t_0) \Delta t_1 + \left[\frac{q(t_1) - q(t_0)}{\Delta t_1} - \frac{\Delta t_1}{\Delta t_1 + \Delta t_2} \left\{ \frac{q(t_1) - q(t_0)}{\Delta t_1} + \frac{q(t_2) - q(t_0)}{\Delta t_2} \right\} \right] \frac{\Delta t_1^2}{2} \\ &\quad + \frac{1}{\Delta t_1 + \Delta t_2} \left\{ \frac{q(t_1) - q(t_0)}{\Delta t_1} + \frac{q(t_2) - q(t_0)}{\Delta t_2} \right\} \frac{\Delta t_1^3}{3} \\ &= q(t_0) \left\{ \Delta t_1 - \frac{\Delta t_1^2}{2} + \frac{\Delta t_1^2}{2(\Delta t_1 + \Delta t_2)} + \frac{\Delta t_1^3}{2\Delta t_2(\Delta t_1 + \Delta t_2)} - \frac{\Delta t_1^2}{3(\Delta t_1 + \Delta t_2)} - \frac{\Delta t_1^3}{3\Delta t_2(\Delta t_1 + \Delta t_2)} \right\} \\ &\quad + q(t_1) \left\{ \frac{\Delta t_1}{2} - \frac{\Delta t_1^2}{2(\Delta t_1 + \Delta t_2)} + \frac{\Delta t_1^2}{3(\Delta t_1 + \Delta t_2)} \right\} - q(t_2) \left\{ \frac{\Delta t_1^3}{2(\Delta t_1 + \Delta t_2)\Delta t_2} - \frac{\Delta t_1^3}{3(\Delta t_1 + \Delta t_2)\Delta t_2} \right\} \end{aligned}$$

If $\Delta t_1 = \Delta t_2 = \Delta t$

$$v(\Delta t) = \left(\Delta t - \frac{\Delta t}{2} + \frac{\Delta t}{4} + \frac{\Delta t}{4} - \frac{\Delta t}{6} - \frac{\Delta t}{6} \right) q(t_0) + \left(\frac{\Delta t}{2} - \frac{\Delta t}{4} + \frac{\Delta t}{6} \right) q(t_0 + \Delta t) - \left(\frac{\Delta t}{4} - \frac{\Delta t}{6} \right) q(t_0 - \Delta t)$$

$$= \frac{2}{3} q(t_0) \Delta t + \frac{5}{12} q(t_0 + \Delta t) \Delta t - \frac{1}{12} q(t_0 - \Delta t) \Delta t$$

$$= -\frac{1}{12} q(t_0 - \Delta t) \Delta t + \frac{2}{3} q(t_0) \Delta t + \frac{5}{12} q(t_0 + \Delta t) \Delta t$$

Thus the inflow or outflow during Δt is given by

$$\int_t^{t+\Delta t} q(t) dt = \{w_1 q(t - \Delta t) + w_2 q(t) + w_3 q(t + \Delta t)\} \Delta t$$

where $w_1 = -1/12$, $w_2 = 2/3$, $w_3 = 5/12$

3.3 A CASE STUDY

The proposed finite difference scheme is applied to solve an unsteady flow in a finite isotropic confined aquifer bounded by fully penetrating streams consequent to a step or ramp change in stream stage. The aquifer is non-homogeneous.

3.3.1 Need For Considering Harmonic Mean Transmissivity

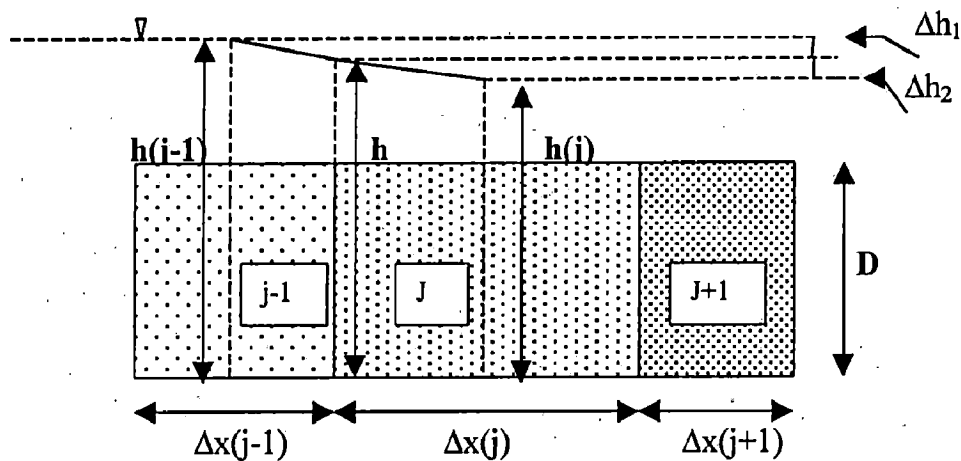


Fig.3.2 Flow in a non-homogeneous & isotropic aquifer

Let us consider the zone between the two adjacent nodes.

Let $\Delta x(j-1)$, $\Delta x(j)$ be the length, T_1, T_2 be the transmissivity and K_1, K_2 be hydraulic conductivity of the two adjacent zones respectively.

Let the flow be in steady state condition. Let $h(j-1)$ and $h(j)$ be the hydraulic head at $(j-1)^{\text{th}}$ & j^{th} node respectively and let h be the head at the interface of the grids. The flow being steady

$$-K_1 D \frac{h-h(j-1)}{0.5\Delta x(j-1)} = -K_2 D \frac{h(j)-h}{0.5\Delta x(j)}$$

Solving for h ,

$$h = \frac{T_1 \Delta x(j) h(j-1) + T_2 \Delta x(j-1) h(j)}{T_1 \Delta x(j) + T_2 \Delta x(j-1)}$$

The hydraulic gradient in zone 1 is

$$i_1 = \frac{h-h(j-1)}{0.5\Delta x(j-1)}$$

$$= \frac{2T_2 \{h(j)-h(j-1)\}}{T_1 \Delta x(j) + T_2 \Delta x(j-1)}$$

The hydraulic gradient in zone 2 is

$$i_2 = \frac{h(j)-h}{0.5\Delta x(j)}$$

$$= \frac{2T_1 \{h(j)-h(j-1)\}}{T_1 \Delta x(j) + T_2 \Delta x(j-1)}$$

Thus $i_1 \neq i_2$, and the graph of the head vs. distance is not differentiable at the interface of the zones of different conductivity. In numerical method for computing inflow (outflow) to carry out mass balance in a grid area, it is necessary to convert the two zones between node $j-1$ and j to a fictitious zone so that the head is differentiable at each point within two consecutive grid nodes.

The gradient in fictitious zone between grid $(j-1)$ and j is

$$i = \frac{h(j)-h(j-1)}{\frac{\Delta x(j-1) + \Delta x(j)}{2}}$$

Let T_e be the effective transmissivity of the zone between grid $j-1$ & j .

For conservation of mass

$$-T_1 i_1 = -T_2 i_2 = -T_e i$$

$$\frac{T_1 T_2 \{h(j) - h(j-1)\}}{T_1 \Delta x(j) + T_2 \Delta x(j-1)} = T_e \frac{h(j) - h(j-1)}{\frac{\Delta x(j-1) + \Delta x(j)}{2}}$$

$$\text{or } T_e = \frac{T_1 T_2 \{\Delta x(j-1) + \Delta x(j)\}}{T_1 \Delta x(j) + T_2 \Delta x(j-1)} = \frac{\Delta x(j-1) + \Delta x(j)}{\frac{\Delta x(j-1)}{T_1} + \frac{\Delta x(j)}{T_2}}$$

T_e is the harmonic mean transmissivity, which should be used in formulating the numerical scheme.

3.4 DEVELOPMENT OF THE FINITE DIFFERENCE SCHEME

Carrying out water balance for the control volume containing node (j) for a time period of Δt during $(k-1)^{\text{th}}$ to $(k)^{\text{th}}$ time step and applying Darcy's law, the finite difference equations are derived. The equations are written for three zones containing

- Interior node (j) where $j = 2, j_{\max}-1$
- Boundary node (left) i.e. $j = 1$
- Boundary node (right) i.e. $j = j_{\max}$

3.4.1 Equation For Interior Node ($j = 2, j_{\max}-1$)

The water balance i.e. Inflow – outflow = change of storage, can be written as:

$$\begin{aligned} & w1 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k-2) - h(j, k-2)}{\frac{\Delta X(j-1) + \Delta X(j)}{2}} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k-2) - h(j, k-2)}{\frac{\Delta X(j) + \Delta X(j+1)}{2}} \right\} \right] \Delta t \\ & + w2 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k-1) - h(j, k-1)}{\frac{\Delta X(j-1) + \Delta X(j)}{2}} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k-1) - h(j, k-1)}{\frac{\Delta X(j) + \Delta X(j+1)}{2}} \right\} \right] \Delta t \\ & + w3 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k) - h(j, k)}{\frac{\Delta X(j-1) + \Delta X(j)}{2}} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k) - h(j, k)}{\frac{\Delta X(j) + \Delta X(j+1)}{2}} \right\} \right] \Delta t \\ & = S(j) \{h(j, k) - h(j, k-1)\} \Delta X(j) \end{aligned}$$

Dividing both sides by $\Delta X(j) \cdot \Delta t$ we get

$$\begin{aligned}
& w1 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k-2) - h(j, k-2)}{2} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k-2) - h(j, k-2)}{2} \right\} \right] \\
& + w2 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k-1) - h(j, k-1)}{2} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k-1) - h(j, k-1)}{2} \right\} \right] \\
& + w3 \left[T_{HM4}(j) \left\{ \frac{h(j-1, k) - h(j, k)}{2} \right\} + T_{HM2}(j) \left\{ \frac{h(j+1, k) - h(j, k)}{2} \right\} \right] \\
& = S(j) \{h(j, k) - h(j, k-1)\} \frac{1}{\Delta t}
\end{aligned}$$

where S(j) be the storage coefficient.

Designating $w3 \frac{T_{HM2}(j)}{(\Delta X(j) + \Delta X(j+1)) \Delta X(j)} = F_2(j)$

$$w3 \frac{T_{HM4}(j)}{(\Delta X(j) + \Delta X(j-1)) \Delta X(j)} = F_4(j)$$

$$- F_2(j) - F_4(j) - \frac{S(j)}{\Delta t} = F_1(j)$$

The above equation can be written as:

$$\begin{aligned}
& w1 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-2) - h(j, k-2)\} + F_2(j) \frac{1}{w3} \{h(j+1, k-2) - h(j, k-2)\} \right] \\
& + w2 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-1) - h(j, k-1)\} + F_2(j) \frac{1}{w3} \{h(j+1, k-1) - h(j, k-1)\} \right] \\
& + [F_4(j) \{h(j-1, k) - h(j, k)\} + F_2(j) \{h(j+1, k) - h(j, k)\}] \\
& = S(j) \{h(j, k) - h(j, k-1)\} \frac{1}{\Delta t}
\end{aligned}$$

$$\text{Or, } F_4(j)h(j-1, k) + F_2(j)h(j+1, k) + \left\{ -F_4(j) - F_2(j) - \frac{S(j)}{\Delta t} \right\} h(j, k)$$

$$+ w1 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-2) - h(j, k-2)\} + F_2(j) \frac{1}{w3} \{h(j+1, k-2) - h(j, k-2)\} \right]$$

$$+ w2 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-1) - h(j, k-1)\} + F_2(j) \frac{1}{w3} \{h(j+1, k-1) - h(j, k-1)\} \right]$$

$$+ S(j) h(j, k-1) \frac{1}{\Delta t} = 0$$

The equation is finally be written as:

$$F_4(j) h(j-1, k) + F_1(j) h(j, k) + F_2(j) h(j+1, k) + F_6(j, k) = 0$$

where

$$\begin{aligned}
F_6(j,k) = w & \left[F_4(j) \frac{1}{w\beta} \{h(j-1,k-2) - h(j,k-2)\} + F_2(j) \frac{1}{w\beta} \{h(j+1,k-2) - h(j,k-2)\} \right] \\
& + w \left[F_4(j) \frac{1}{w\beta} \{h(j-1,k-1) - h(j,k-1)\} + F_2(j) \frac{1}{w\beta} \{h(j+1,k-1) - h(j,k-1)\} \right] \\
& + S(j) h(j,k-1) \frac{1}{\Delta t}
\end{aligned}$$

3.4.2 Equation For Boundary Node (left) i.e. $j = 1$

Let Γ_r be the reach transmissivity of the stream.

Let $h_r(k-2)$, $h_r(k-1)$, $h_r(k)$ be the head in the stream at $(k-2)$, $(k-1)$ & k^{th} time step respectively.

Let $h(j,k-2)$, $h(j,k-1)$, $h(j,k)$ be the head of node (j) at $(k-2)$, $(k-1)$ & k^{th} time step respectively.

Inflow from stream to the aquifer will be equal to the multiplication of reach transmissivity and the head difference between the stream and left node of the aquifer.

The water balance equation is given by:

$$\begin{aligned}
& w \left[\Gamma_r \{h_r(k-2) - h(j,k-2)\} + T_{HM2}(j) \left\{ \frac{h(j+1,k-2) - h(j,k-2)}{\frac{\Delta x(j) + \Delta x(j+1)}{2}} \right\} \right] \Delta t \\
& + w \left[\Gamma_r \{h_r(k-1) - h(j,k-1)\} + T_{HM2}(j) \left\{ \frac{h(j+1,k-1) - h(j,k-1)}{\frac{\Delta x(j) + \Delta x(j+1)}{2}} \right\} \right] \Delta t \\
& + w \left[\Gamma_r \{h_r(k) - h(j,k)\} + T_{HM2}(j) \left\{ \frac{h(j+1,k) - h(j,k)}{\frac{\Delta x(j) + \Delta x(j+1)}{2}} \right\} \right] \Delta t \\
& = S(j) \{h(j,k) - h(j,k-1)\} \Delta X(j)
\end{aligned}$$

Dividing both sides by $\Delta X(j) \Delta t$

$$\begin{aligned}
& w \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j,k-2)\} + T_{HM2}(j) \left\{ \frac{h(j+1,k-2) - h(j,k-2)}{\frac{\Delta x(j) + \Delta x(j+1)}{2} \Delta X(j)} \right\} \right] \\
& + w \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j,k-1)\} + T_{HM2}(j) \left\{ \frac{h(j+1,k-1) - h(j,k-1)}{\frac{\Delta x(j) + \Delta x(j+1)}{2} \Delta X(j)} \right\} \right]
\end{aligned}$$

$$+ w3 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k) - h(j, k)\} + T_{HM2}(j) \left\{ \frac{h(j+1, k) - h(j, k)}{\frac{\Delta x(j) + \Delta x(j+1)}{2} \Delta X(j)} \right\} \right]$$

$$= S(j) \frac{1}{\Delta t} \{h(j, k) - h(j, k-1)\}$$

Designating, $w3 \frac{T_{HM2}(j)}{\frac{\Delta x(j) + \Delta x(j+1)}{2} \Delta X(j)} = F_2(j)$.

$$- F_2(j) - w3 \frac{\Gamma_r}{\Delta X(j)} - \frac{S(j)}{\Delta t} = F_1(j)$$

The above equation reduces to:

$$w1 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} + \frac{F_2(j)}{w3} \{h(j+1, k-2) - h(j, k-2)\} \right]$$

$$+ w2 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} + \frac{F_2(j)}{w3} \{h(j+1, k-1) - h(j, k-1)\} \right]$$

$$+ \left[w3 \frac{\Gamma_r}{\Delta X(j)} \{h_r(k) - h(j, k)\} + F_2(j) \{h(j+1, k) - h(j, k)\} \right]$$

$$= S(j) \frac{1}{\Delta t} \{h(j, k) - h(j, k-1)\}$$

$$\text{Or } \left\{ -w3 \frac{\Gamma_r}{\Delta X(j)} - F_2(j) - \frac{S(j)}{\Delta t} \right\} h(j, k) + F_2(j) h(j+1, k)$$

$$+ w1 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} + \frac{F_2(j)}{w3} \{h(j+1, k-2) - h(j, k-2)\} \right]$$

$$+ w2 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} + \frac{F_2(j)}{w3} \{h(j+1, k-1) - h(j, k-1)\} \right]$$

$$+ S(j) \frac{1}{\Delta t} h(j, k-1) + w3 \frac{\Gamma_r}{\Delta X(j)} h_r(k) = 0$$

The equation is finally written as:

$$F_1(j) h(j, k) + F_2(j) h(j+1, k) + F_6(j, k) = 0$$

where

$$F_6(j, k) = w1 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} + \frac{F_2(j)}{w3} \{h(j+1, k-2) - h(j, k-2)\} \right]$$

$$+ w2 \left[\Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} + \frac{F_2(j)}{w3} \{h(j+1, k-1) - h(j, k-1)\} \right]$$

$$+ S(j) \frac{1}{\Delta t} h(j, k-1) + w3 \frac{\Gamma_r}{\Delta X(j)} h_r(k)$$

3.4.3 Equation For Boundary Node (right) i.e. $j = j_{\max}$

Let Γ_r be the reach transmissivity of the stream.

Let $h(j,k-2)$, $h(j,k-1)$, $h(j,k)$ be the head in the right boundary node of the aquifer at $(k-2)$, $(k-1)$, k^{th} time step respectively.

Let $h_r(k-2)$, $h_r(k-1)$, $h_r(k)$ be the head in the right stream at $(k-2)$, $(k-1)$, k^{th} time step respectively.

$S(j)$ be the storage coefficient of the aquifer.

Now the water balance equation can be written as:

$$\begin{aligned}
 & w1 \left[T_{HM4}(j) \frac{h(j-1, k-2) - h(j, k-2)}{\Delta X(j-1) + \Delta X(j)} + \Gamma_r \{h_r(k-2) - h(j, k-2)\} \right] \Delta t \\
 & + w2 \left[T_{HM4}(j) \frac{h(j-1, k-1) - h(j, k-1)}{\Delta X(j-1) + \Delta X(j)} + \Gamma_r \{h_r(k-1) - h(j, k-1)\} \right] \Delta t \\
 & + w3 \left[T_{HM4}(j) \frac{h(j-1, k) - h(j, k)}{\Delta X(j-1) + \Delta X(j)} + \Gamma_r \{h_r(k) - h(j, k)\} \right] \Delta t \\
 & = S(j) \{h(j, k) - h(j, k-1)\} \Delta X(j)
 \end{aligned}$$

Dividing both sides by $\Delta X(j) \Delta t$ we get

$$\begin{aligned}
 & w1 \left[T_{HM4}(j) \frac{h(j-1, k-2) - h(j, k-2)}{\Delta X(j) + \Delta X(j-1)} \frac{1}{\Delta X(j)} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} \right] \\
 & + w2 \left[T_{HM4}(j) \frac{h(j-1, k-1) - h(j, k-1)}{\Delta X(j) + \Delta X(j-1)} \frac{1}{\Delta X(j)} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} \right] \\
 & + w3 \left[T_{HM4}(j) \frac{h(j-1, k) - h(j, k)}{\Delta X(j) + \Delta X(j-1)} \frac{1}{\Delta X(j)} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k) - h(j, k)\} \right] \\
 & = S(j) \frac{1}{\Delta t} \{h(j, k) - h(j, k-1)\}
 \end{aligned}$$

Designate $w3 \frac{T_{HM4}(j)}{\{\Delta X(j) + \Delta X(j-1)\} \Delta X(j)} = F_4(j)$

$- F_4(j) - \frac{\Gamma_r}{\Delta X(j)} w3 - \frac{S(j)}{\Delta t} = F_1(j)$

Now the equation can be written as:

$$\begin{aligned}
& w1 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-2) - h(j, k-2)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} \right] \\
& + w2 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-1) - h(j, k-1)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} \right] \\
& + \left[F_4(j) \{h(j-1, k) - h(j, k)\} + \Gamma_r \frac{w3}{\Delta X(j)} \{h_r(k) - h(j, k)\} \right] \\
& = S(j) \frac{1}{\Delta t} \{h(j, k) - h(j, k-1)\}
\end{aligned}$$

$$\begin{aligned}
\text{Or } & F_4(j) h(j-1, k) + \left\{ -F_4(j) - \Gamma_r \frac{w3}{\Delta X(j)} - S(j) \frac{1}{\Delta t} \right\} h(j, k) \\
& + w1 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-2) - h(j, k-2)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} \right] \\
& + w2 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-1) - h(j, k-1)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} \right] \\
& + S(j) \frac{1}{\Delta t} h(j, k-1) + w3 \frac{\Gamma_r}{\Delta X(j)} h_r(k) = 0
\end{aligned}$$

Finally the equation can be written as:

$$F_4(j) h(j-1, k) + F_1(j) h(j, k) + F_6(j, k) = 0$$

Where $F_6(j, k) = \frac{S(j)}{\Delta t} h(j, k-1) + w3 \frac{\Gamma_r}{\Delta X(j)} h_r(k)$

$$\begin{aligned}
& + w1 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-2) - h(j, k-2)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-2) - h(j, k-2)\} \right] \\
& + w2 \left[F_4(j) \frac{1}{w3} \{h(j-1, k-1) - h(j, k-1)\} + \Gamma_r \frac{1}{\Delta X(j)} \{h_r(k-1) - h(j, k-1)\} \right]
\end{aligned}$$

The equation for each node can be written in matrix form as:

$$\begin{bmatrix} F_1(1) & F_2(1) & \dots & \dots & \dots & \dots \\ F_4(2) & F_1(2) & F_2(2) & \dots & \dots & \dots \\ \dots & F_4(3) & F_1(3) & F_2(3) & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & F_4(j_{\max-1}) & F_1(j_{\max-1}) & F_2(j_{\max-1}) & h(j_{\max-1}, k) \\ \dots & \dots & \dots & F_4(j_{\max}) & F_1(j_{\max}) & h(j_{\max}, k) \end{bmatrix} \begin{bmatrix} h(1, k) \\ h(2, k) \\ h(3, k) \\ \dots \\ h(j_{\max-1}, k) \\ h(j_{\max}, k) \end{bmatrix} = \begin{bmatrix} F_6(1, k) \\ F_6(2, k) \\ F_6(3, k) \\ \dots \\ F_6(j_{\max-1}, k) \\ F_6(j_{\max}, k) \end{bmatrix}$$

Or

$$\begin{aligned}
& [h(1, k), h(2, k), \dots, h(j_{\max}, k)]^T = \\
& \begin{bmatrix} F_1(1) & F_2(1) & \dots & \dots & \dots & \dots \\ F_4(2) & F_1(2) & F_2(2) & \dots & \dots & \dots \\ \dots & F_4(3) & F_1(3) & F_2(3) & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & F_4(j_{\max-1}) & F_1(j_{\max-1}) & F_2(j_{\max-1}) & \\ \dots & \dots & \dots & F_4(j_{\max}) & F_1(j_{\max}) & \end{bmatrix}^{-1} \begin{bmatrix} -F_6(1, k) \\ -F_6(2, k) \\ -F_6(3, k) \\ \dots \\ -F_6(j_{\max-1}, k) \\ -F_6(j_{\max}, k) \end{bmatrix}
\end{aligned}$$

CHAPTER 4

AN IMPROVED FINITE DIFFERENCE SCHEME ACCOUNTING SPATIAL VARIATION

4.1 INTRODUCTION

In the existing finite difference scheme, it is implied that the spatial head distribution at a particular time follows a second-degree polynomial (see Appendix-1). In the improved finite difference scheme, the spatial variation of hydraulic head is assumed to follow a three-degree polynomial, the scheme has been written for uniform grid size as well as non-uniform grid size.

4.2 FINITE DIFFERENCE SCHEME FOR UNIFORM GRID SIZE

For the finite difference method, following two assumptions are made:

- Flow variation with time at a particular section follows a quadratic distribution;
- Variation of head between nodes at a particular time follows a polynomial equation as given below:

$h(x) = a + bx + cx^2 + dx^3$, where a, b, c, d are the unknown constants to be derived in terms of $h(j-1), h(j), h(j+1), h(j+2)$.

Let us consider a non-homogeneous, isotropic, one-dimensional confined aquifer system bounded by fully penetrating stream. Let us discretise the aquifer into grids of equal sizes. Four types of grids for which the equations are to be written are:

- a. All interior nodes i.e. $j = 2, j_{\max}-2$
- b. The boundary node (left) i.e. $j = 1$
- c. The interior node i.e. $j = j_{\max}-1$
- d. The boundary node (right) i.e. $j = j_{\max}$

4.2.1. Equation For Interior Nodes i.e. $j = 2, j_{\max}-2$:

Selecting the origin at j^{th} node, the head $h(x), j-1 \leq x \leq j+2$ is expressed as:

$$h(x) = a + bx + cx^2 + dx^3$$

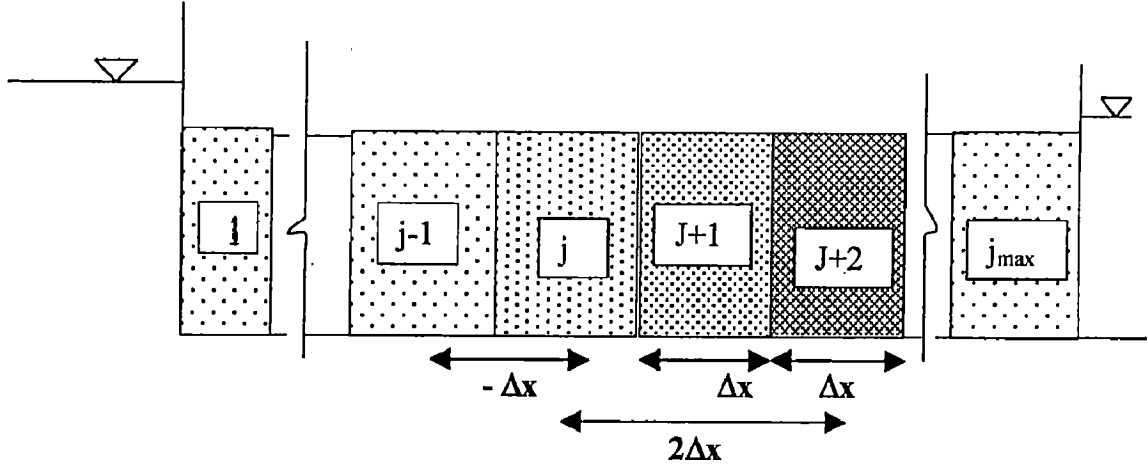


Fig.4.1: Discretisation of flow domain, origin at j ($2 \leq j \leq j_{\max}-2$)

$$\text{At } x = 0, \quad h(0) = h(j) = a$$

$$\text{At } x = -\Delta x, \quad h(-\Delta x) = h(j-1) = a - b \Delta x + c \Delta x^2 - d \Delta x^3$$

$$\text{At } x = \Delta x, \quad h(\Delta x) = h(j+1) = a + b \Delta x + c \Delta x^2 + d \Delta x^3$$

$$\text{At } x = 2\Delta x, \quad h(2\Delta x) = h(j+2) = a + 2b \Delta x + 4c \Delta x^2 + 8d \Delta x^3$$

Solving above equations we get,

$$a = h(j)$$

$$b = \{-h(j+2) + 6h(j+1) - 3h(j) - 2h(j-1)\} / (6\Delta x)$$

$$c = \{h(j+1) - 2h(j) + h(j-1)\} / (2\Delta x^2)$$

$$d = \{h(j+2) - 3h(j+1) + 3h(j) - h(j-1)\} / (6\Delta x^3)$$

The derivative $dh/dx = b + 2cx + 3dx^2$

$$\frac{dh}{dx} \text{ at } x = -\Delta x/2 = \{-h(j+2) + 3h(j+1) + 21h(j) - 23h(j-1)\} \frac{1}{24\Delta x}$$

$$\frac{dh}{dx} \text{ at } x = \Delta x/2 = \{-h(j+2) + 27h(j+1) - 27h(j) + h(j-1)\} \frac{1}{24\Delta x}$$

The water balance equation is written as:

Inflow-outflow = change in storage

$$\text{Or } \left\{ -T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} - \left\{ -T_{HM2}(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

$$- \left\{ T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} + \left\{ T_{HM2}(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

Taking into account of the variation of flow during different time steps i.e. (k-2), (k-1) & kth time steps, the water balance equation is written as:

$$\begin{aligned}
& -w1T_{HM}(j) \{-h(j+2, k-2) + 3h(j+1, k-2) + 21h(j, k-2) - 23h(j-1, k-2)\} \\
& +w1T_{HM2}(j) \{-h(j+2, k-2) + 27h(j+1, k-2) - 27h(j, k-2) + h(j-1, k-2)\} \\
& -w2T_{HM4}(j) \{-h(j+2, k-1) + 3h(j+1, k-1) + 21h(j, k-1) - 23h(j-1, k-1)\} \\
& +w2T_{HM2}(j) \{-h(j+2, k-1) + 27h(j+1, k-1) - 27h(j, k-1) + h(j-1, k-1)\} \\
& -w3T_{HM4}(j) \{-h(j+2, k) + 3h(j+1, k) + 21h(j, k) - 23h(j-1, k)\} \\
& +w3T_{HM2}(j) \{-h(j+2, k) + 27h(j+1, k) - 27h(j, k) + h(j-1, k)\} \\
& = S\{h(j, k) - h(j, k-1)\} \frac{24\Delta x^2}{\Delta t}
\end{aligned}$$

The above equation is rearranged as:

$$\begin{aligned}
& -w3T_{HM4}(j) \{-h(j+2, k) + 3h(j+1, k) + 21h(j, k) - 23h(j-1, k)\} \\
& +w3T_{HM2}(j) \{-h(j+2, k) + 27h(j+1, k) - 27h(j, k) + h(j-1, k)\} \\
& -w1T_{HM4}(j) \{-h(j+2, k-2) + 3h(j+1, k-2) + 21h(j, k-2) - 23h(j-1, k-2)\} \\
& +w1T_{HM2}(j) \{-h(j+2, k-2) + 27h(j+1, k-2) - 27h(j, k-2) + h(j-1, k-2)\} \\
& -w2T_{HM4}(j) \{-h(j+2, k-1) + 3h(j+1, k-1) + 21h(j, k-1) - 23h(j-1, k-1)\} \\
& +w2T_{HM2}(j) \{-h(j+2, k-1) + 27h(j+1, k-1) - 27h(j, k-1) + h(j-1, k-1)\} \\
& -S\{h(j, k) - h(j, k-1)\} \frac{24\Delta x^2}{\Delta t} = 0
\end{aligned}$$

Designating, $w3\{T_{HM4}(j) - T_{HM2}(j)\} = F_{22}(j)$

$$w3\{-3T_{HM4}(j) + 27T_{HM2}(j)\} = F_2(j)$$

$$-24S \frac{\Delta x^2}{\Delta t} + w3\{-21T_{HM4}(j) - 27T_{HM2}(j)\} = F_1(j)$$

$$w3\{23T_{HM4}(j) + T_{HM2}(j)\} = F_4(j)$$

$$F_6(j, k) = -w1T_{HM4}(j) \{-h(j+2, k-2) + 3h(j+1, k-2) + 21h(j, k-2) - 23h(j-1, k-2)\}$$

$$+w1T_{HM2}(j) \{-h(j+2, k-2) + 27h(j+1, k-2) - 27h(j, k-2) + h(j-1, k-2)\}$$

$$-w2T_{HM4}(j) \{-h(j+2, k-1) + 3h(j+1, k-1) + 21h(j, k-1) - 23h(j-1, k-1)\}$$

$$+w2T_{HM2}(j) \{-h(j+2, k-1) + 27h(j+1, k-1) - 27h(j, k-1) + h(j-1, k-1)\} + S h(j, k-1) \frac{24\Delta x^2}{\Delta t}$$

The water balance equation for interior node is written as:

$$F_{22}(j)h(j+2, k) + F_2(j)h(j+1, k) + F_1(j)h(j, k) + F_4(j)h(j-1, k) + F_6(j, k) = 0$$

4.2.2. Equation For Boundary Node (left) i.e. $j = 1$

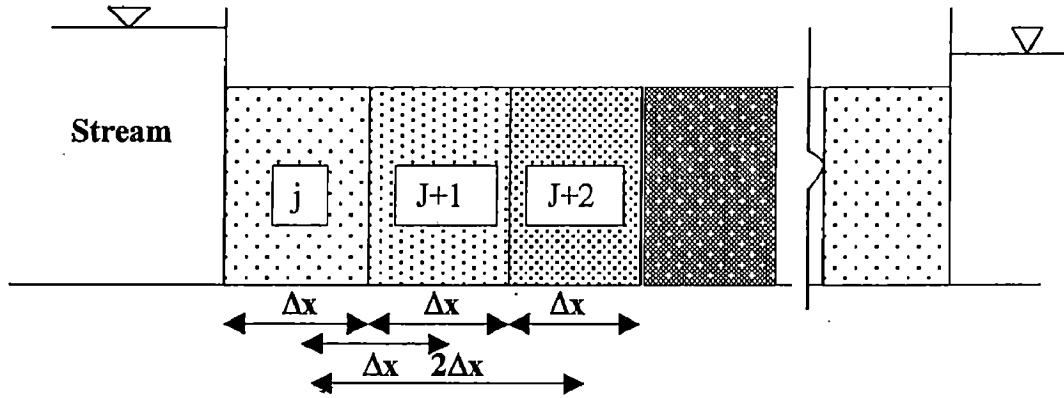


Fig.4.2: Discretisation of flow domain origin at node 1

Let head for $-\Delta x/2 \leq x \leq 2\Delta x$ is expressed as:

$h(x) = a + bx + cx^2 + dx^3$, constants a, b, c, d are derived in terms of $h(j-1), h(j), h(j+1),$

$h(j+2)$.

$$\text{At } x = 0 \quad h(0) = h(j) = a$$

$$\text{At } x = -\frac{\Delta x}{2} \quad h(-\Delta x/2) = h(j-1) = h(j) - \frac{b}{2}\Delta x + \frac{c}{4}\Delta x^2 - \frac{d}{8}\Delta x^3$$

$$\text{At } x = \Delta x \quad h(\Delta x) = h(j+1) = h(j) + b\Delta x + c\Delta x^2 + d\Delta x^3$$

$$\text{At } x = 2\Delta x \quad h(2\Delta x) = h(j+2) = h(j) + 2b\Delta x + 4c\Delta x^2 + 8d\Delta x^3$$

Solving above we get the value of a, b, c, d :

$$a = h(j)$$

$$b = \frac{-3h(j+2) + 20h(j+1) + 15h(j) - 32h(j-1)}{30\Delta x}$$

$$c = \frac{-h(j+2) + 10h(j+1) - 25h(j) + 16h(j-1)}{10\Delta x^2}$$

$$d = \frac{6h(j+2) - 20h(j+1) + 30h(j) - 16h(j-1)}{30\Delta x^3}$$

The gradient $\frac{dh}{dx} = b + 2cx + 3dx^2$,

$$\frac{dh}{dx} \Big|_{x=-\Delta x/2} = \frac{18h(j+2) - 100h(j+1) + 450h(j) - 368h(j-1)}{120\Delta x}$$

$$\frac{dh}{dx} \Big|_{x=\Delta x/2} = \frac{-6h(j+2) + 140h(j+1) - 150h(j) + 16h(j-1)}{120\Delta x}$$

The water balance equation is written as:

Inflow-outflow = change in storage

$$\left\{ -T(j) \frac{dh}{dx} \Big|_{atx=-\Delta x/2} \right\} - \left\{ -T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x/2} \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

$$\left\{ -T(j) \frac{dh}{dx} \Big|_{atx=-\Delta x/2} \right\} + \left\{ T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x/2} \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

Taking into account the variation of flow during time step (k-2), (k-1), and kth, the water balance equation can be written as:

$$\begin{aligned} & -w1T(j) \{18h(j+2, k-2) - 100h(j+1, k-2) + 450h(j, k-2) - 368h(j-1, k-2)\} \frac{1}{120\Delta x} \\ & + w1T_{HM2}(j) \{-6h(j+2, k-2) + 140h(j+1, k-2) - 150h(j, k-2) + 16h(j-1, k-2)\} \frac{1}{120\Delta x} \\ & - w2T(j) \{18h(j+2, k-1) - 100h(j+1, k-1) + 450h(j, k-1) - 368h(j-1, k-1)\} \frac{1}{120\Delta x} \\ & + w2T_{HM2}(j) \{-6h(j+2, k-1) + 140h(j+1, k-1) - 150h(j, k-1) + 16h(j-1, k-1)\} \frac{1}{120\Delta x} \\ & - w3T(j) \{18h(j+2, k) - 100h(j+1, k) + 450h(j, k) - 368h(j-1, k)\} \frac{1}{120\Delta x} \\ & + w3T_{HM2}(j) \{-6h(j+2, k) + 140h(j+1, k) - 150h(j, k) + 16h(j-1, k)\} \frac{1}{120\Delta x} \\ & = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t} \end{aligned}$$

The above equation is rearranged as:

$$\begin{aligned} & -w3T(j) \{18h(j+2, k) - 100h(j+1, k) + 450h(j, k) - 368h(j-1, k)\} \\ & + w3T_{HM2}(j) \{-6h(j+2, k) + 140h(j+1, k) - 150h(j, k) + 16h(j-1, k)\} \\ & - 120 \frac{\Delta x^2}{\Delta t} S h(j, k) = -120 \frac{\Delta x^2}{\Delta t} S h(j, k-1) \\ & + w1T(j) \{18h(j+2, k-2) - 100h(j+1, k-2) + 450h(j, k-2) - 368h(j-1, k-2)\} \\ & - w1T_{HM2}(j) \{-6h(j+2, k-2) + 140h(j+1, k-2) - 150h(j, k-2) + 16h(j-1, k-2)\} \\ & + w2T(j) \{18h(j+2, k-1) - 100h(j+1, k-1) + 450h(j, k-1) - 368h(j-1, k-1)\} \\ & - w2T_{HM2}(j) \{-6h(j+2, k-1) + 140h(j+1, k-1) - 150h(j, k-1) + 16h(j-1, k-1)\} \end{aligned}$$

$$\text{Designating, } w3\{-18T(j) - 6T_{HM2}(j)\} = F_{22}(j)$$

$$w3\{100T(j) + 140T_{HM2}(j)\} = F_2(j)$$

$$-120 \frac{\Delta x^2}{\Delta t} S + w_3 \{-450T(j) - 150T_{HM2}(j)\} = F_1(j)$$

$$F_6(j, k) = 120 \frac{\Delta x^2}{\Delta t} S h(j, k-1) + w_3 \{368T(j) + 16T_{HM2}(j)\}$$

$$\begin{aligned} & -w_1 T(j) \{18h(j+2, k-2) - 100h(j+1, k-2) + 450h(j, k-2) - 368h(j-1, k-2)\} \\ & + w_1 T_{HM2}(j) \{-6h(j+2, k-2) + 140h(j+1, k-2) - 150h(j, k-2) + 16h(j-1, k-2)\} \\ & - w_2 T(j) \{18h(j+2, k-1) - 100h(j+1, k-1) + 450h(j, k-1) - 368h(j-1, k-1)\} \\ & + w_2 T_{HM2}(j) \{-6h(j+2, k-1) + 140h(j+1, k-1) - 150h(j, k-1) + 16h(j-1, k-1)\} \end{aligned}$$

The water balance equation is written as:

$$F_{22}(j) h(j+2, k) + F_2(j) h(j+1, k) + F_1(j) h(j, k) + F_6(j, k) = 0$$

4.2.3. Equation For Interior Node i.e. $j = j_{\max}-1$

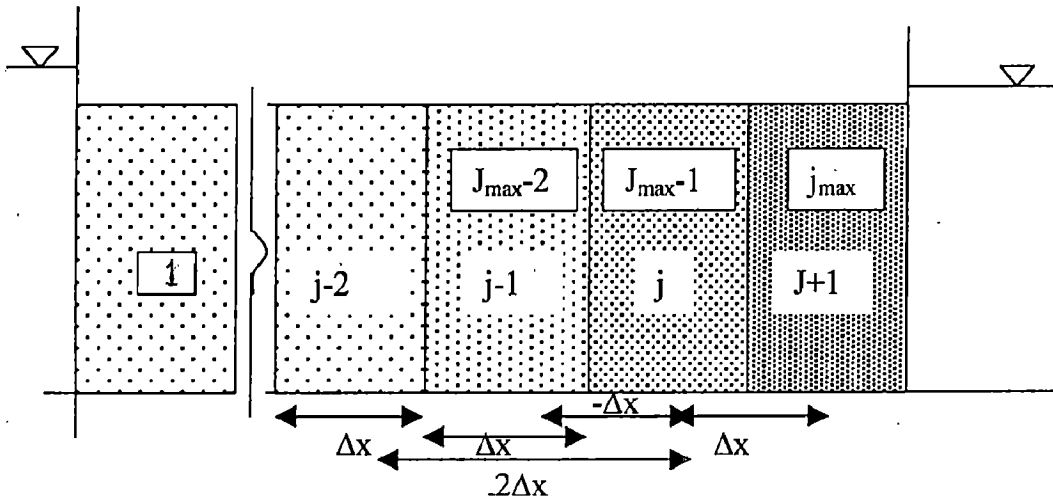


Fig.4.3: Discretisation of flow domain, origin at $J_{\max}-1$

Let node j be origin. Let in the region $(j_{\max}-3) \leq x \leq j_{\max}$ the head be expressed as:

$$h(x) = a + bx + cx^2 + dx^3$$

where a, b, c, d are derived in terms of $h(j-2), h(j-1), h(j), h(j+1)$.

$$\text{At } x = 0, \quad h(0) = h(j) = a$$

$$\text{At } x = \Delta x, \quad h(\Delta x) = h(j+1) = a + b \Delta x + c \Delta x^2 + d \Delta x^3$$

$$\text{At } x = -\Delta x, \quad h(-\Delta x) = h(j-1) = a - b \Delta x + c \Delta x^2 - d \Delta x^3$$

$$\text{At } x = -2\Delta x, \quad h(-2\Delta x) = h(j-2) = a - 2b \Delta x + 4c \Delta x^2 - 8d \Delta x^3$$

Solving above equation we get,

$$a = h(j)$$

$$b = \{h(j-2) - 6h(j-1) + 3h(j) + 2h(j+1)\} / (6\Delta x)$$

$$c = \{h(j+1) - 2h(j) + h(j-1)\} / (2\Delta x^2)$$

$$d = \{-h(j-2) + 3h(j-1) - 3h(j) + h(j+1)\} / (6\Delta x^3)$$

The differential $dh/dx = b + 2cx + 3dx^2$

$$\frac{dh}{dx} \text{ at } x = -\Delta x/2 = \{h(j-2) - 27h(j-1) + 27h(j) - h(j+1)\} \frac{1}{24\Delta x}$$

$$\frac{dh}{dx} \text{ at } x = \Delta x/2 = \{h(j-2) - 3h(j-1) - 21h(j) + 23h(j+1)\} \frac{1}{24\Delta x}$$

The water balance equation is written as:

Inflow-outflow = change in storage

$$\text{Or } \left\{ -T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} - \left\{ -T_{HM2}(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

$$- \left\{ T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} + \left\{ T_{HM2}(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

Taking into account of the variation in flow during time steps (k-2), (k-1) & kth, the water balance equation is written as:

$$\begin{aligned} & -w1T_{HM4}(j) \{h(j-2, k-2) - 27h(j-1, k-2) + 27h(j, k-2) - h(j+1, k-2)\} \\ & + w1T_{HM2}(j) \{h(j-2, k-2) - 3h(j-1, k-2) - 21h(j, k-2) + 23h(j+1, k-2)\} \\ & - w2T_{HM4}(j) \{h(j-2, k-1) - 27h(j-1, k-1) + 27h(j, k-1) - h(j+1, k-1)\} \\ & + w2T_{HM2}(j) \{h(j-2, k-1) - 3h(j-1, k-1) - 21h(j, k-1) + 23h(j+1, k-1)\} \\ & - w3T_{HM4}(j) \{h(j-2, k) - 27h(j-1, k) + 27h(j, k) - h(j+1, k)\} \\ & + w3T_{HM2}(j) \{h(j-2, k) - 3h(j-1, k) - 21h(j, k) + 23h(j+1, k)\} \\ & = S \{h(j, k) - h(j, k-1)\} \frac{24\Delta x^2}{\Delta t} \end{aligned}$$

Designating,

$$w3\{-T_{HM4}(j) + T_{HM2}(j)\} = F_{44}(j)$$

$$w3\{27T_{HM4}(j) - 3T_{HM2}(j)\} = F_4(j)$$

$$-24S \frac{\Delta x^2}{\Delta t} + w3\{-27T_{HM4}(j) - 21T_{HM2}(j)\} = F_1(j)$$

$$w3\{T_{HM4}(j) + 23T_{HM2}(j)\} = F_2(j)$$

$$F_6(j, k) = -w1T_{HM4}(j)\{h(j-2, k-2) - 27h(j-1, k-2) + 27h(j, k-2) - h(j+1, k-2)\}$$

$$+ w1T_{HM2}(j)\{h(j-2, k-2) - 3h(j-1, k-2) - 21h(j, k-2) + 23h(j+1, k-2)\}$$

$$- w2T_{HM4}(j)\{h(j-2, k-1) - 27h(j-1, k-1) + 27h(j, k-1) - h(j+1, k-1)\}$$

$$+ w2T_{HM2}(j)\{h(j-2, k-1) - 3h(j-1, k-1) - 21h(j, k-1) + 23h(j+1, k-1)\}$$

$$+ Sh(j, k-1) \frac{24\Delta x^2}{\Delta t}$$

The water balance equation is written as:

$$F_{44}(j)h(j-2, k) + F_4(j)h(j-1, k) + F_1(j)h(j, k) + F_2(j)h(j+1, k) + F_6(j, k) = 0$$

4.2.4. Equation For Boundary Node (right) i.e. = j_{max}

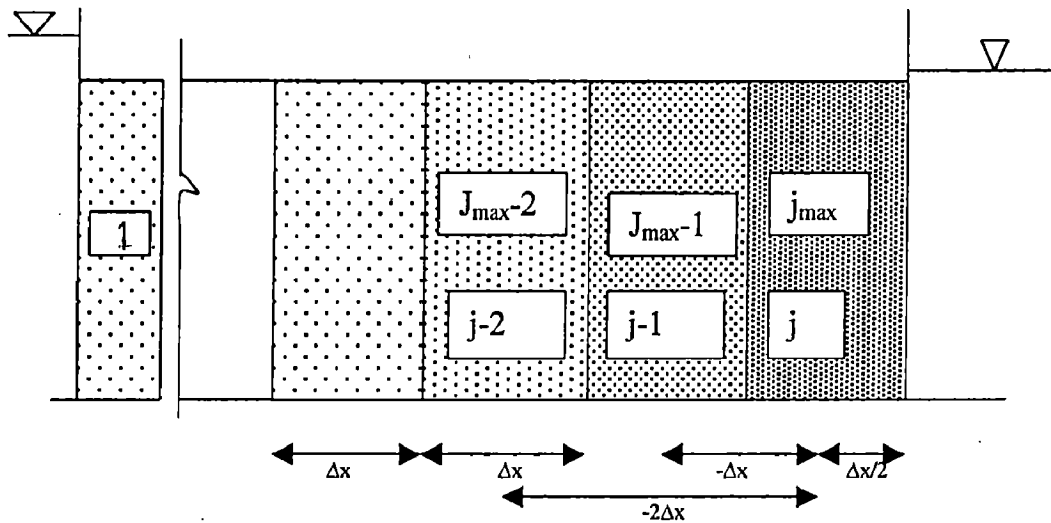


Fig.4.4: Discretisation of flow domain, origin at j_{max}

Let the head for $-2\Delta x \leq x \leq \Delta x/2$ is expressed as:

$$h(x) = a + bx + cx^2 + dx^3, \text{ constants } a, b, c, d \text{ are derived in terms of } h(j-2), h(j-1), h(j), h(j+1).$$

$$\text{At } x = 0, \quad h(0) = h(j) = a$$

$$\text{At } x = \Delta x/2, \quad h(\Delta x/2) = h(j+1) = a + b \Delta x/2 + c \Delta x^2/4 + d \Delta x^3/8$$

$$\text{At } x = -\Delta x, \quad h(-\Delta x) = h(j-1) = a - b \Delta x + c \Delta x^2 - d \Delta x^3$$

$$\text{At } x = -2\Delta x, \quad h(-2\Delta x) = h(j-2) = a - 2b \Delta x + 4c \Delta x^2 - 8d \Delta x^3$$

Solving above equation we get,

$$a = h(j)$$

$$b = \{32h(j+1) - 15h(j) - 20h(j-1) + 3h(j-2)\} / (30\Delta x)$$

$$c = \{16h(j+1) - 25h(j) + 10h(j-1) - h(j-2)\} / (10\Delta x^2)$$

$$d = \{16h(j+1) - 30h(j) + 20h(j-1) - 6h(j-2)\} / (30\Delta x^3)$$

The gradient $dh/dx = b + 2cx + 3dx^2$

$$\frac{dh}{dx} \text{ at } x = -\Delta x/2 = \{-16h(j+1) + 150h(j) - 140h(j-1) + 6h(j-2)\} \frac{1}{120\Delta x}$$

$$\frac{dh}{dx} \text{ at } x = \Delta x/2 = \{368h(j+1) - 450h(j) + 100h(j-1) - 18h(j-2)\} \frac{1}{120\Delta x}$$

The water balance equation can be written as:

Inflow-outflow = change in storage

$$\left\{ -T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} - \left\{ -T(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

$$- \left\{ T_{HM4}(j) \frac{dh}{dx} \text{ at } x = -\Delta x/2 \right\} + \left\{ T(j) \frac{dh}{dx} \text{ at } x = \Delta x/2 \right\} = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

Taking into account the variation of flow during different time steps (k-2), (k-1), kth, the water balance equation will be written as:

$$\begin{aligned} & -w1T_{HM4}(j) \{-16h(j+1, k-2) + 150h(j, k-2) - 140h(j-1, k-2) + 6h(j-2, k-2)\} \frac{1}{120\Delta x} \\ & + w1T(j) \{368h(j+1, k-2) - 450h(j, k-2) + 100h(j-1, k-2) - 18h(j-2, k-2)\} \frac{1}{120\Delta x} \\ & - w2T_{HM4}(j) \{-16h(j+1, k-1) + 150h(j, k-1) - 140h(j-1, k-1) + 6h(j-2, k-1)\} \frac{1}{120\Delta x} \\ & + w2T(j) \{368h(j+1, k-1) - 450h(j, k-1) + 100h(j-1, k-1) - 18h(j-2, k-1)\} \frac{1}{120\Delta x} \\ & - w3T_{HM4}(j) \{-16h(j+1, k) + 150h(j, k) - 140h(j-1, k) + 6h(j-2, k)\} \frac{1}{120\Delta x} \\ & + w3T(j) \{368h(j+1, k) - 450h(j, k) + 100h(j-1, k) - 18h(j-2, k)\} \frac{1}{120\Delta x} \\ & = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t} \end{aligned}$$

The equation is rearranged as:

$$-w3T_{HM4}(j) \{-16h(j+1, k) + 150h(j, k) - 140h(j-1, k) + 6h(j-2, k)\}$$

$$\begin{aligned}
& +w3T(j)\{368h(j+1, k) - 450h(j, k) + 100h(j-1, k) - 18h(j-2, k)\} \\
& -120S \frac{\Delta x^2}{\Delta t} h(j, k) = -120S \frac{\Delta x^2}{\Delta t} h(j, k-1) \\
& +w1T_{HM4}(j)\{-16h(j+1, k-2) + 150h(j, k-2) - 140h(j-1, k-2) + 6h(j-2, k-2)\} \\
& -w1T(j)\{368h(j+1, k-2) - 450h(j, k-2) + 100h(j-1, k-2) - 18h(j-2, k-2)\} \\
& +w2T_{HM4}(j)\{-16h(j+1, k-1) + 150h(j, k-1) - 140h(j-1, k-1) + 6h(j-2, k-1)\} \\
& -w2T(j)\{368h(j+1, k-1) - 450h(j, k-1) + 100h(j-1, k-1) - 18h(j-2, k-1)\}
\end{aligned}$$

Designating,

$$-120S \frac{\Delta x^2}{\Delta t} + \{-150T_{HM4}(j) - 450T(j)\}w3 = F_1(j)$$

$$\{140T_{HM4}(j) + 100T(j)\}w3 = F_4(j)$$

$$\{-6T_{HM4}(j) - 18T(j)\}w3 = F_{44}(j)$$

$$F_6(j, k) = 120S \frac{\Delta x^2}{\Delta t} h(j, k-1) + w3\{16T_{HM4}(j) + 368T(j)\}h(j+1, k)$$

$$-w1T_{HM4}(j)\{-16h(j+1, k-2) + 150h(j, k-2) - 140h(j-1, k-2) + 6h(j-2, k-2)\}$$

$$+w1T(j)\{368h(j+1, k-2) - 450h(j, k-2) + 100h(j-1, k-2) - 18h(j-2, k-2)\}$$

$$-w2T_{HM4}(j)\{-16h(j+1, k-1) + 150h(j, k-1) - 140h(j-1, k-1) + 6h(j-2, k-1)\}$$

$$+w2T(j)\{368h(j+1, k-1) - 450h(j, k-1) + 100h(j-1, k-1) - 18h(j-2, k-1)\}$$

The water balance equation is written as:

$$F_1(j)h(j, k) + F_4(j)h(j-1, k) + F_{44}(j)h(j-2, k) + F_6(j, k) = 0$$

4.3 FINITE DIFFERENCE SCHEME FOR NON-UNIFORM GRID SIZE

Let us consider a non-homogeneous, isotropic, one-dimensional confined aquifer bounded by fully penetrating stream. Let us discretise the aquifer into grids of unequal sizes. Four types of grid for which equations are to be written:

- All interior nodes i.e. $j = 2, j_{\max}-2$
- The boundary node (left) i.e. $j = 1$
- The interior node i.e. $j = j_{\max}-1$
- The boundary node right i.e. $j = j_{\max}$

4.3.1. Equation For Interior Nodes i.e. $j = 2, j_{\max}-2$

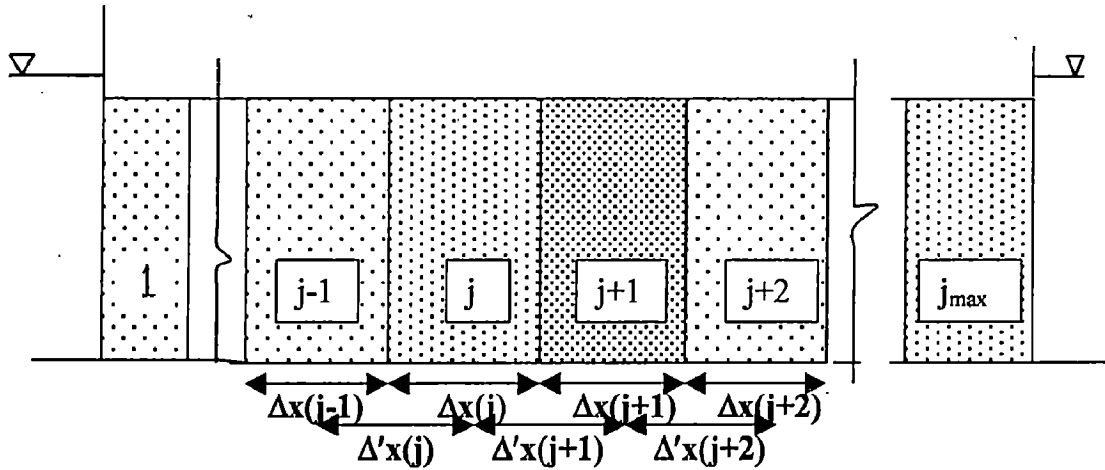


Fig.4.5: Discretisation of flow domain, origin at $j, 2 \leq j \leq j_{\max}-2$

Selecting the origin at j^{th} node, the head $h(x), j-1 \leq x \leq j+2$ is expressed as:

$$h(x) = a + bx + cx^2 + dx^3$$

where constants a, b, c, d are derived in terms of $h(j-1), h(j), h(j+1), h(j+2)$.

$$\text{Designate, } \Delta'x(j) = \{\Delta x(j-1) + \Delta x(j)\} / 2$$

$$\Delta'x(j+1) = \{\Delta x(j) + \Delta x(j+1)\} / 2$$

$$\Delta'x(j+2) = \{\Delta x(j+1) + \Delta x(j+2)\} / 2$$

$$\text{Hence at } x = 0, \quad h(0) = h(j) = a$$

$$\text{At } x = -\Delta'x(j), \quad h\{-\Delta'x(j)\} = h(j-1),$$

$$h(j-1)-h(j) = -b\Delta'x(j) + c\Delta'x^2(j) - d\Delta'x^3(j) \quad \dots(4.1)$$

$$\text{At } x = \Delta'x(j+1), \quad h\{\Delta'x(j+1)\} = h(j+1)$$

$$h(j+1)-h(j) = b\Delta'x(j+1) + c\Delta'x^2(j+1) + d\Delta'x^3(j+1) \quad \dots(4.2)$$

$$\text{At } x = \Delta'x(j+1) + \Delta'x(j+2), \quad h\{\Delta'x(j+1) + \Delta'x(j+2)\} = h(j+2)$$

$$h(j+2)-h(j) = b\{\Delta'x(j+1) + \Delta'x(j+2)\} + c\{\Delta'x(j+1) + \Delta'x(j+2)\}^2 + d\{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \quad \dots(4.3)$$

Above equations (4.1), (4.2), (4.3) are solved for getting b, c, d :

$$\text{Designating, } D = \begin{vmatrix} -\Delta'x(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ \Delta'x(j+1) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \\ \{\Delta'x(j+1) + \Delta'x(j+2)\} & \{\Delta'x(j+1) + \Delta'x(j+2)\}^2 & \{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \end{vmatrix}$$

$$\therefore b = \begin{vmatrix} h(j-1) - h(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ h(j+1) - h(j) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \\ h(j+2) - h(j) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^2 & \{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Or } b = \begin{vmatrix} h(j-1) - h(j) & h(j+1) - h(j) & h(j+2) - h(j) \\ \Delta'x^2(j) & \Delta'x^2(j+1) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^2 \\ -\Delta'x^3(j) & \Delta'x^3(j+1) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x^2(j+1) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^2 \\ \Delta'x^3(j+1) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \end{vmatrix} / D = D_1$$

$$\begin{vmatrix} \Delta'x^2(j) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^2 \\ -\Delta'x^3(j) & \{\Delta'x(j+1) + \Delta'x(j+2)\}^3 \end{vmatrix} / D = D_2$$

$$\begin{vmatrix} \Delta'x^2(j) & \Delta'x^2(j+1) \\ -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D = D_3$$

$$\begin{aligned} \text{Hence } b &= \{h(j-1) - h(j)\}D_1 - \{h(j+1) - h(j)\}D_2 + \{h(j+2) - h(j)\}D_3 \\ &= D_1h(j-1) + (-D_1 + D_2 - D_3)h(j) - D_2h(j+1) + D_3h(j+2) \quad \dots(4.4) \end{aligned}$$

$$\text{Now } c = \begin{vmatrix} -\Delta'x(j) & h(j-1)-h(j) & -\Delta'x^3(j) \\ \Delta'x(j+1) & h(j+1)-h(j) & \Delta'x^3(j+1) \\ \{\Delta'x(j+1)+\Delta'x(j+2)\} & h(j+2)-h(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Or } c = - \begin{vmatrix} h(j-1)-h(j) & h(j+1)-h(j) & h(j+2)-h(j) \\ -\Delta'x(j) & \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ -\Delta'x^3(j) & \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_4$$

$$\begin{vmatrix} -\Delta'x(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ -\Delta'x^3(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_5$$

$$\begin{vmatrix} -\Delta'x(j) & \Delta'x(j+1) \\ -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D = D_6$$

$$\begin{aligned} \text{Hence } c &= -\{h(j-1)-h(j)\}D_4 + \{h(j+1)-h(j)\}D_5 - \{h(j+2)-h(j)\}D_6 \\ &= -D_4h(j-1) + (D_4 - D_5 + D_6)h(j) + D_5h(j+1) - D_6h(j+2) \end{aligned} \quad \dots(4.5)$$

$$d = \begin{vmatrix} -\Delta'x(j) & \Delta'x^2(j) & h(j-1)-h(j) \\ \Delta'x(j+1) & \Delta'x^2(j+1) & h(j+1)-h(j) \\ \{\Delta'x(j+1)+\Delta'x(j+2)\} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 & h(j+2)-h(j) \end{vmatrix} / D$$

$$d = \begin{vmatrix} h(j-1)-h(j) & h(j+1)-h(j) & h(j+2)-h(j) \\ -\Delta'x(j) & \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^2(j) & \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{vmatrix} / D = D_7$$

$$\begin{vmatrix} -\Delta'x(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^2(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{vmatrix} / D = D_8$$

$$\begin{vmatrix} -\Delta'x(j) & \Delta'x(j+1) \\ \Delta'x^2(j) & \Delta'x^2(j+1) \end{vmatrix} / D = D_9$$

$$\begin{aligned} \text{Hence } d &= \{h(j-1) - h(j)\}D_7 - \{(h(j+1) - h(j))\}D_8 + \{h(j+2) - h(j)\}D_9 \\ &= D_7h(j-1) + (-D_7 + D_8 - D_9)h(j) - D_8h(j+1) + D_9h(j+2) \end{aligned} \quad \dots(4.6)$$

The gradient, $dh/dx = b + 2cx + 3dx^2$

$$\begin{aligned} \frac{dh}{dx_{atx=-\Delta x(j)/2}} &= D_1h(j-1) + (-D_1 + D_2 - D_3)h(j) - D_2h(j+1) + D_3h(j+2) \\ &- \{-D_4h(j-1) + (D_4 - D_5 + D_6)h(j) + D_5h(j+1) - D_6h(j+2)\}\Delta x(j) \\ &+ \{D_7h(j-1) + (-D_7 + D_8 - D_9)h(j) - D_8h(j+1) + D_9h(j+2)\}\frac{3}{4}\Delta x^2(j) \end{aligned}$$

$dh/dx_{atx=-\Delta x(j)/2} =$

$$\begin{aligned} &h(j-1)\left\{D_1 + D_4\Delta x(j) + D_7\frac{3}{4}\Delta x^2(j)\right\} \\ &+ h(j)\left\{-D_1 + D_2 - D_3 - (D_4 - D_5 + D_6)\Delta x(j) + (-D_7 + D_8 - D_9)\frac{3}{4}\Delta x^2(j)\right\} \\ &+ h(j+1)\left\{-D_2 - D_5\Delta x(j) - D_8\frac{3}{4}\Delta x^2(j)\right\} + h(j+2)\left\{D_3 + D_6\Delta x(j) + D_9\frac{3}{4}\Delta x^2(j)\right\} \end{aligned}$$

$$\begin{aligned} \frac{dh}{dx_{atx=\Delta x(j)/2}} &= D_1h(j-1) + (-D_1 + D_2 - D_3)h(j) - D_2h(j+1) + D_3h(j+2) \\ &+ \{-D_4h(j-1) + (D_4 - D_5 + D_6)h(j) + D_5h(j+1) - D_6h(j+2)\}\Delta x(j) \\ &+ \{D_7h(j-1) + (-D_7 + D_8 - D_9)h(j) - D_8h(j+1) + D_9h(j+2)\}\frac{3}{4}\Delta x^2(j) \end{aligned}$$

$dh/dx_{atx=\Delta x(j)/2} =$

$$\begin{aligned} &h(j-1)\left\{D_1 - D_4\Delta x(j) + D_7\frac{3}{4}\Delta x^2(j)\right\} \\ &+ h(j)\left\{-D_1 + D_2 - D_3 + (D_4 - D_5 + D_6)\Delta x(j) + (-D_7 + D_8 - D_9)\frac{3}{4}\Delta x^2(j)\right\} \\ &+ h(j+1)\left\{-D_2 + D_5\Delta x(j) - D_8\frac{3}{4}\Delta x^2(j)\right\} + h(j+2)\left\{D_3 - D_6\Delta x(j) + D_9\frac{3}{4}\Delta x^2(j)\right\} \end{aligned}$$

The water balance equation is given by:

Inflow-outflow = change in storage

$$\begin{aligned} -T_{HM4}(j)\frac{dh}{dx_{atx=-\Delta x(j)/2}} - \left\{-T_{HM2}(j)\frac{dh}{dx_{atx=\Delta x(j)/2}}\right\} &= S\{h(j,k) - h(j,k-1)\}\frac{\Delta x(j)}{\Delta t} \\ -T_{HM4}(j)\frac{dh}{dx_{atx=-\Delta x(j)/2}} + \left\{T_{HM2}(j)\frac{dh}{dx_{atx=\Delta x(j)/2}}\right\} &= S\{h(j,k) - h(j,k-1)\}\frac{\Delta x(j)}{\Delta t} \end{aligned}$$

Taking into account of the variation of flow during time step $(k-2)$, $(k-1)$, k^{th} , the water balance equation is written as:

$$w1 \left[-T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x/2} \right] + w2 \left[-T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x/2} \right] \\ + w3 \left[-T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x/2} \right] = S \{h(j, k) - h(j, k-1)\} \frac{\Delta x}{\Delta t}$$

$$\text{Designating, } F_4(j) = -w3T_{HM4}(j) \left\{ D_1 + D_4 \Delta x(j) + D_7 \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ w3T_{HM2}(j) \left\{ D_1 - D_4 \Delta x(j) + D_7 \frac{3}{4} \Delta x^2(j) \right\}$$

$$F_1(j) = -w3T_{HM4}(j) \left\{ -D_1 + D_2 - D_3 - (D_4 - D_5 + D_6) \Delta x(j) + (-D_7 + D_8 - D_9) \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ w3T_{HM2}(j) \left\{ -D_1 + D_2 - D_3 + (D_4 - D_5 + D_6) \Delta x(j) + (-D_7 + D_8 - D_9) \frac{3}{4} \Delta x^2(j) \right\} - S \frac{\Delta x(j)}{\Delta t}$$

$$F_2(j) = -w3T_{HM4}(j) \left\{ -D_2 - D_5 \Delta x(j) - D_8 \frac{3}{4} \Delta x^2(j) \right\} + w3T_{HM2}(j) \left\{ -D_2 + D_5 \Delta x(j) - D_8 \frac{3}{4} \Delta x^2(j) \right\}$$

$$F_{22}(j) = -w3T_{HM4}(j) \left\{ D_3 + D_6 \Delta x(j) + D_9 \frac{3}{4} \Delta x^2(j) \right\} + w3T_{HM2}(j) \left\{ D_3 - D_6 \Delta x(j) + D_9 \frac{3}{4} \Delta x^2(j) \right\}$$

$$F_6(j, k) = -S \frac{\Delta x}{\Delta t} h(j, k) - w1T_{HM4}(j) \left\{ \frac{dh}{dx} \Big|_{atx=(-\Delta x/2)} \right\} + w1T_{HM2}(j) \left\{ \frac{dh}{dx} \Big|_{atx=(\Delta x/2)} \right\}$$

$$- w2T_{HM4}(j) \left\{ \frac{dh}{dx} \Big|_{atx=(-\Delta x/2)} \right\} + w2T_{HM2}(j) \left\{ \frac{dh}{dx} \Big|_{atx=(\Delta x/2)} \right\}$$

Finally the water balance equation becomes:

$$F_4(j)h(j-1, k) + F_1(j)h(j, k) + F_2(j)h(j+1, k) + F_{22}(j)h(j+2, k) + F_6(j, k) = 0$$

4.3.2 Equation for Boundary Node (left) i.e. j=1:

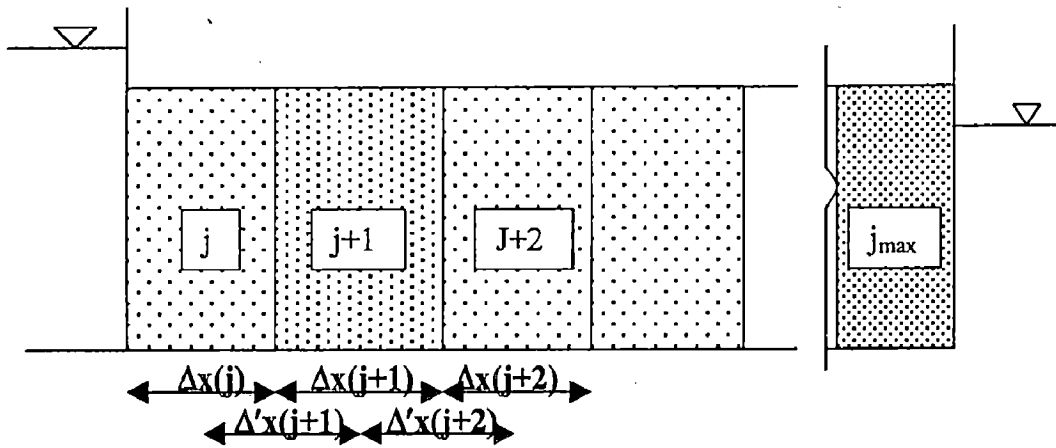


Fig.4.6: Discretisation of flow domain origin at node 1

Let head for $-\Delta x/2 \leq x \leq 2\Delta x$ is expressed as:

$$h(x) = a + b x + c x^2 + d x^3$$

Where constants a, b, c, d are derived in terms of $h(j-1)$, $h(j)$, $h(j+1)$, $h(j+2)$.

Let node (j) be the origin.

Designating, $\Delta'x(j+1) = \{\Delta x(j) + \Delta x(j+1)\}/2$

$$\Delta'x(j+2) = \{\Delta x(j+1) + \Delta x(j+2)\}/2$$

Hence at $x=0$, $h(0) = h(j) = a$,

At $x = \Delta'x(j+1)$, $h\{\Delta'x(j+1)\} = h(j+1)$,

Or $h(j+1) - h(j) = b\Delta'x(j+1) + c\Delta'^2x(j+1) + d\Delta'^3x(j+1)$

At $x = \Delta'x(j+1) + \Delta'x(j+2)$, $h\{\Delta'x(j+1) + \Delta'x(j+2)\} = h(j+2)$

Or $h(j+2) - h(j) = b\{\Delta'x(j+1) + \Delta'x(j+2)\} + c\{\Delta'x(j+1) + \Delta'x(j+2)\}^2 + d\{\Delta'x(j+1) + \Delta'x(j+2)\}^3$

At $x = -\Delta x(j)/2$, $h\{-\Delta x(j)/2\} = h(j-1)$

Or $h(j-1) - h(j) = -b\{\Delta x(j)/2\} + c\{\Delta x(j)/2\}^2 - d\{\Delta x(j)/2\}^3$

$$= -b\{\Delta x(j)/2\} + c\{\Delta x^2(j)/4\} - d\{\Delta^3x(j)/8\}$$

Now the above equations are rearranged as:

$$h(j-1) - h(j) = -b\{\Delta x(j)/2\} + c\{\Delta x^2(j)/4\} + d\{\Delta^3x(j)/8\} \quad \dots(4.7)$$

$$h(j+1)-h(j) = b\Delta'x(j+1)+c\Delta'x^2(j+1)+d\Delta'x^3(j+1) \quad \dots(4.8)$$

$$h(j+2)-h(j) = b\{\Delta'x(j+1)+\Delta'x(j+2)\}+c\{\Delta'x(j+1)+\Delta'x(j+2)\}^2+d\{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \quad \dots(4.9)$$

$$\text{Designating, } D = \begin{vmatrix} \frac{-\Delta x(j)}{2} & \frac{\Delta x^2(j)}{4} & \frac{-\Delta x^3(j)}{8} \\ \Delta'x(j+1) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \\ \{\Delta'x(j+1)+\Delta'x(j+2)\} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix}$$

$$\text{Now } b = \begin{vmatrix} h(j-1)-h(j) & \frac{\Delta x^2(j)}{4} & \frac{-\Delta x^3(j)}{8} \\ h(j+1)-h(j) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \\ h(j+2)-h(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Or } b = \begin{vmatrix} h(j-1)-h(j) & h(j+1)-h(j) & h(j+2)-h(j) \\ \frac{\Delta x^2(j)}{4} & \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \\ \frac{-\Delta x^3(j)}{8} & \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \\ \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_{41}$$

$$\begin{vmatrix} \frac{\Delta x^2(j)}{4} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \\ \frac{-\Delta x^3(j)}{8} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_{42}$$

$$\begin{vmatrix} \frac{\Delta x^2(j)}{4} & \Delta'x^2(j+1) \\ \frac{-\Delta x^3(j)}{8} & \Delta'x^3(j+1) \end{vmatrix} / D = D_{43}$$

$$\begin{aligned} \text{Hence } b &= \{h(j-1)-h(j)\}D_{41} - \{h(j+1)-h(j)\}D_{42} + \{h(j+2)-h(j)\}D_{43} \\ &= D_{41}h(j-1) + (-D_{41} + D_{42} - D_{43})h(j) - D_{42}h(j+1) + D_{43}h(j+2) \quad \dots(4.10) \end{aligned}$$

$$\text{Now } c = \begin{vmatrix} \frac{-\Delta x(j)}{2} & h(j-1)-h(j) & -\frac{\Delta x^3(j)}{8} \\ \Delta'x(j+1) & h(j+1)-h(j) & \Delta'x^3(j+1) \\ \{\Delta'x(j+1)+\Delta'x(j+2)\} & h(j+2)-h(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Or } c = - \begin{vmatrix} h(j-1)-h(j) & \frac{-\Delta x(j)}{2} & -\frac{\Delta x^3(j)}{8} \\ h(j+1)-h(j) & \Delta'x(j+1) & \Delta'x^3(j+1) \\ h(j+2)-h(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Or } c = - \begin{vmatrix} h(j-1)-h(j) & h(j+1)-h(j) & h(j+2)-h(j) \\ \frac{\Delta x(j)}{2} & \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ -\frac{\Delta x^3(j)}{8} & \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^3(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_{44}$$

$$\begin{vmatrix} \frac{\Delta x(j)}{2} & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \frac{\Delta x^3(j)}{8} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^3 \end{vmatrix} / D = D_{45}$$

$$\begin{vmatrix} \frac{\Delta x(j)}{2} & \Delta'x(j+1) \\ \frac{\Delta x^3(j)}{8} & \Delta'x^3(j+1) \end{vmatrix} / D = D_{46}$$

$$\begin{aligned} \text{Hence } c &= -\{h(j-1)-h(j)\}D_{44} + \{h(j+1)-h(j)\}D_{45} - \{h(j+2)-h(j)\}D_{46} \\ &= -D_{44}h(j-1) + (D_{44} - D_{45} + D_{46})h(j) + D_{45}h(j+1) - D_{46}h(j+2) \end{aligned} \quad \dots(4.11)$$

$$\text{Now } d = \begin{vmatrix} \frac{-\Delta x(j)}{2} & \frac{\Delta x^2(j)}{4} & h(j-1)-h(j) \\ \Delta'x(j+1) & \Delta'x^2(j+1) & h(j+1)-h(j) \\ \{\Delta'x(j+1)+\Delta'x(j+2)\} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 & h(j+2)-h(j) \end{vmatrix} / D$$

$$\text{Or } d = \left| \begin{array}{ccc} h(j-1)-h(j) & \frac{-\Delta x(j)}{2} & \frac{\Delta x^2(j)}{4} \\ h(j+1)-h(j) & \Delta'x(j+1) & \Delta'x^2(j+1) \\ h(j+2)-h(j) & \{\Delta'x(j+1)+\Delta'x(j+2)\} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{array} \right| / D$$

$$\text{Or } d = \left| \begin{array}{ccc} h(j-1)-h(j) & h(j+1)-h(j) & h(j+2)-h(j) \\ \frac{\Delta x(j)}{2} & \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \frac{\Delta x^2(j)}{4} & \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{array} \right| / D$$

$$\text{Designating, } \left| \begin{array}{cc} \Delta'x(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \Delta'x^2(j+1) & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{array} \right| / D = D_{47}$$

$$\left| \begin{array}{cc} \frac{\Delta x(j)}{2} & \{\Delta'x(j+1)+\Delta'x(j+2)\} \\ \frac{\Delta x^2(j)}{4} & \{\Delta'x(j+1)+\Delta'x(j+2)\}^2 \end{array} \right| / D = D_{48}$$

$$\left| \begin{array}{cc} \frac{\Delta x(j)}{2} & \Delta'x(j+1) \\ \frac{\Delta x^2(j)}{4} & \Delta'x^2(j+1) \end{array} \right| / D = D_{49}$$

$$\begin{aligned} \text{hence } d &= \{h(j-1)-h(j)\}D_{47} - \{h(j+1)-h(j)\}D_{48} + \{h(j+2)-h(j)\}D_{49} \\ &= D_{47}h(j-1) + (-D_{47} + D_{48} - D_{49})h(j) - D_{48}h(j+1) + D_{49}h(j+2) \quad \dots(4.12) \end{aligned}$$

$$\frac{dh}{dx} = b + 2cx + 3dx^2$$

$$\begin{aligned} \frac{dh}{dx_{ax=-\Delta x(j)/2}} &= b - c\Delta x(j) + \frac{3}{4}d\Delta x^2(j) \\ &= D_{41}h(j-1) + (-D_{41} + D_{42} - D_{43})h(j) - D_{42}h(j+1) + D_{43}h(j+2) \\ &\quad - \{ -D_{44}h(j-1) + (D_{44} - D_{45} + D_{46})h(j) + D_{45}h(j+1) - D_{46}h(j+2) \} \Delta x(j) \\ &\quad + \{ D_{47}h(j-1) + (-D_{47} + D_{48} - D_{49})h(j) - D_{48}h(j+1) + D_{49}h(j+2) \} \frac{3}{4}\Delta x^2(j) \end{aligned}$$

$$\begin{aligned} \frac{dh}{dx_{ax=-\Delta x(j)/2}} &= h(j-1) \left\{ D_{41} + D_{44}\Delta x(j) + D_{47}\frac{3}{4}\Delta x^2(j) \right\} \\ &\quad + h(j) \left\{ -D_{41} + D_{42} - D_{43} - (D_{44} - D_{45} + D_{46})\Delta x(j) + (-D_{47} + D_{48} - D_{49})\frac{3}{4}\Delta x^2(j) \right\} \end{aligned}$$

$$\begin{aligned}
& + h(j+1) \left\{ -D_{42} - D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+2) \left\{ D_{43} + D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\} \\
\frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} & = b + c \Delta x(j) + \frac{3}{4} d \Delta x^2(j) \\
& = D_{41} h(j-1) + (-D_{41} + D_{42} - D_{43}) h(j) - D_{42} h(j+1) + D_{43} h(j+2) \\
& + \left\{ -D_{44} h(j-1) + (D_{44} - D_{45} + D_{46}) h(j) + D_{45} h(j+1) - D_{46} h(j+2) \right\} \Delta x(j) \\
& + \left\{ D_{47} h(j-1) + (-D_{47} + D_{48} - D_{49}) h(j) - D_{48} h(j+1) + D_{49} h(j+2) \right\} \frac{3}{4} \Delta x^2(j) \\
\frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} & = h(j-1) \left\{ D_{41} - D_{44} \Delta x(j) + D_{47} \frac{3}{4} \Delta x^2(j) \right\}
\end{aligned}$$

$$\begin{aligned}
& + h(j) \left\{ -D_{41} + D_{42} - D_{43} + (D_{44} - D_{45} + D_{46}) \Delta x(j) + (-D_{47} + D_{48} - D_{49}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+1) \left\{ -D_{42} + D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+2) \left\{ D_{43} - D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\}
\end{aligned}$$

Taking into account the variation of flow during time steps (k-2), (k-1), & kth, the water balance equation is written as:

Inflow-outflow = change in storage

$$\begin{aligned}
w1 \left\{ -T(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} & + w2 \left\{ -T(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
+ w3 \left\{ -T(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} & = S \frac{\Delta x(j)}{\Delta t} \{h(j, k) - h(j, k-1)\}
\end{aligned}$$

Equation is rearranged as:

$$\begin{aligned}
& -w3T(j) \left[h(j-1, k) \left\{ D_{41} + D_{44} \Delta x(j) + D_{47} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j, k) \left\{ -D_{41} + D_{42} - D_{43} - (D_{44} - D_{45} + D_{46}) \Delta x(j) + (-D_{47} + D_{48} - D_{49}) \frac{3}{4} \Delta x^2(j) \right\} \\
& \left. + h(j+1, k) \left\{ -D_{42} - D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} + h(j+2, k) \left\{ D_{43} + D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\} \right]
\end{aligned}$$

$$\begin{aligned}
& +w3T_{HM2}(j) \left[h(j-1, k) \left\{ D_{41} - D_{44} \Delta x(j) + D_{47} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j, k) \left\{ -D_{41} + D_{42} - D_{43} + (D_{44} - D_{45} + D_{46}) \Delta x(j) + (-D_{47} + D_{48} - D_{49}) \frac{3}{4} \Delta x^2(j) \right\} \\
& \left. + h(j+1, k) \left\{ -D_{42} + D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} + h(j+2, k) \left\{ D_{43} - D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\} \right] \\
& + w1 \left\{ -T(j) \frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\} + w2 \left\{ -T(j) \frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\} \\
& = S \frac{\Delta x(j)}{\Delta t} \{h(j, k) - h(j, k-1)\}
\end{aligned}$$

Designating,

$$\begin{aligned}
F_1(j) &= -w3T(j) \left\{ -D_{41} + D_{42} - D_{43} - (D_{44} - D_{45} + D_{46}) \Delta x(j) + (-D_{47} + D_{48} - D_{49}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + w3T_{HM2}(j) \left\{ -D_{41} + D_{42} - D_{43} + (D_{44} - D_{45} + D_{46}) \Delta x(j) + (-D_{47} + D_{48} - D_{49}) \frac{3}{4} \Delta x^2(j) \right\} - S \frac{\Delta x(j)}{\Delta t} \\
F_2(j) &= -w3T(j) \left\{ -D_{42} - D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} + w3T_{HM2}(j) \left\{ -D_{42} + D_{45} \Delta x(j) - D_{48} \frac{3}{4} \Delta x^2(j) \right\} \\
F_{22}(j) &= -w3T(j) \left\{ D_{43} + D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\} + w3T_{HM2}(j) \left\{ D_{43} - D_{46} \Delta x(j) + D_{49} \frac{3}{4} \Delta x^2(j) \right\} \\
F_6(j, k) &= S \frac{\Delta x(j)}{\Delta t} h(j, k-1) - T(j)w3 \left\{ D_{41} + D_{44} \Delta x(j) + D_{47} \frac{3}{4} \Delta x^2(j) \right\} \\
& + w3T_{HM2}(j) \left\{ D_{41} - D_{44} \Delta x(j) + D_{47} \frac{3}{4} \Delta x^2(j) \right\} \\
& + w1 \left\{ -T(j) \frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\} \\
& + w2 \left\{ -T(j) \frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\}
\end{aligned}$$

Finally the equation becomes:

$$F_1(j)h(j, k) + F_2(j)h(j+1, k) + F_{22}(j)h(j+2, k) + F_6(j, k) = 0$$

4.3.3 Equation For The Interior Node i.e. $j = j_{\max}-1$

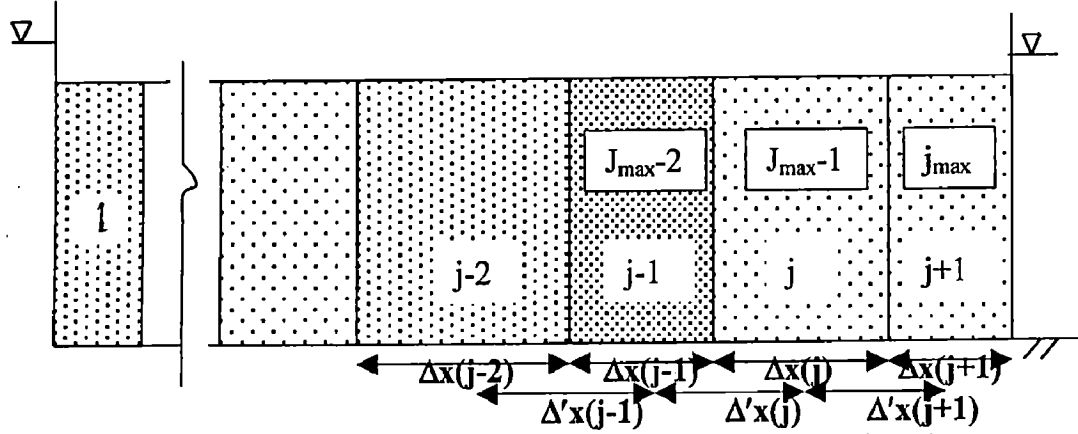


Fig.4.7: Discretisation of flow domain origin at $j_{\max}-1$

Let the head in the region $(j_{\max}-3) \leq x \leq j_{\max}$ be expressed as:

$$h(x) = a + bx + cx^2 + dx^3$$

where constants a, b, c, d are derived in terms of $h(j+1)$, $h(j)$, $h(j-1)$, $h(j-2)$.

Designating, $\Delta'x(j-1) = \{\Delta x(j-2) + \Delta x(j-1)\} / 2$

$$\Delta'x(j) = \{\Delta x(j-1) + \Delta x(j)\} / 2$$

$$\Delta'x(j+1) = \{\Delta x(j) + \Delta x(j+1)\} / 2$$

Let node j be the origin.

Hence at $x = 0$, $h(0) = h(j) = a$

At $x = -\{\Delta'x(j) + \Delta'x(j-1)\}$, $h\{-\Delta'x(j) - \Delta'x(j-1)\} = h(j-2)$

$$h(j-2) - h(j) = -b\{\Delta'x(j) + \Delta'x(j-1)\} + c\{\Delta'x(j) + \Delta'x(j-1)\}^2 - d\{\Delta'x(j) + \Delta'x(j-1)\}^3 \quad \dots(4.13)$$

At $x = -\Delta'x(j)$, $h\{-\Delta'x(j)\} = h(j-1)$

$$h(j-1) - h(j) = -b\Delta'x(j) + c\Delta'x^2(j) - d\Delta'x^3(j) \quad \dots(4.14)$$

At $x = \Delta'x(j+1)$, $h\{\Delta'x(j+1)\} = h(j+1)$

$$h(j+1) - h(j) = b\Delta'x(j+1) + c\Delta'x^2(j+1) + d\Delta'x^3(j+1) \quad \dots(4.15)$$

Above equations are solved for getting b, c, d:

$$\text{Designating, } D = \begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & \{\Delta'x(j) + \Delta'x(j-1)\}^2 & -\{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ -\Delta'x(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ \Delta'x(j+1) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \end{vmatrix}$$

$$\therefore b = \begin{vmatrix} h(j-2) - h(j) & \{\Delta'x(j) + \Delta'x(j-1)\}^2 & -\{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ h(j-1) - h(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ h(j+1) - h(j) & \Delta'x^2(j+1) & \Delta'x^3(j+1) \end{vmatrix} / D$$

$$\text{Or } b = \begin{vmatrix} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) & \Delta'x^2(j+1) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x^2(j) & \Delta'x^2(j+1) \\ -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D = D_{31}$$

$$\begin{vmatrix} \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j+1) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & \Delta'x^3(j+1) \end{vmatrix} / D = D_{32}$$

$$\begin{vmatrix} \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) \end{vmatrix} / D = D_{33}$$

$$\text{Hence } b = \{h(j-2) - h(j)\}D_{31} - \{h(j-1) - h(j)\}D_{32} + \{h(j+1) - h(j)\}D_{33}$$

$$= D_{31}h(j-2) - D_{32}h(j-1) + (-D_{31} + D_{32} - D_{33})h(j) + D_{33}h(j+1) \quad \dots(4.16)$$

$$\therefore c = \begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & h(j-2) - h(j) & -\{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ -\Delta'x(j) & h(j-1) - h(j) & -\Delta'x^3(j) \\ \Delta'x(j+1) & h(j+1) - h(j) & \Delta'x^3(j+1) \end{vmatrix} / D$$

$$\text{Or } c = \begin{vmatrix} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) & \Delta'x(j+1) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} -\Delta'x(j) & \Delta'x(j+1) \\ -\Delta'x^3(j) & \Delta'x^3(j+1) \end{vmatrix} / D = D_{34}$$

$$\begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & \Delta'x(j+1) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & \Delta'x^3(j+1) \end{vmatrix} / D = D_{35}$$

$$\begin{aligned} & \left| \begin{array}{cc} -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) \end{array} \right| / D = D_{36} \\ c = & -\{h(j-2) - h(j)\}D_{34} + \{h(j-1) - h(j)\}D_{35} - \{h(j+1) - h(j)\}D_{36} \\ = & -D_{34}h(j-2) + D_{35}h(j-1) + (D_{34} - D_{35} + D_{36})h(j) - D_{36}h(j+1) \quad \dots(4.17) \end{aligned}$$

$$\text{Now } d = \left| \begin{array}{ccc} -\{\Delta'x(j) + \Delta'x(j-1)\} & \{\Delta'x(j) + \Delta'x(j-1)\}^2 & h(j-2) - h(j) \\ -\Delta'x(j) & \Delta'x^2(j) & h(j-1) - h(j) \\ \Delta'x(j+1) & \Delta'x^2(j+1) & h(j+1) - h(j) \end{array} \right| / D$$

$$\text{Or } d = \left| \begin{array}{ccc} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) & \Delta'x(j+1) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) & \Delta'x^2(j+1) \end{array} \right| / D$$

$$\text{Designating, } \left| \begin{array}{cc} -\Delta'x(j) & \Delta'x(j+1) \\ \Delta'x^2(j) & \Delta'x^2(j+1) \end{array} \right| / D = D_{37}$$

$$\left| \begin{array}{cc} -\{\Delta'x(j) + \Delta'x(j-1)\} & \Delta'x(j+1) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j+1) \end{array} \right| / D = D_{38}$$

$$\left| \begin{array}{cc} -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) \end{array} \right| / D = D_{39}$$

$$\begin{aligned} d = & \{h(j-2) - h(j)\}D_{37} - \{h(j-1) - h(j)\}D_{38} + \{h(j+1) - h(j)\}D_{39} \\ = & D_{37}h(j-2) - D_{38}h(j-1) + (-D_{37} + D_{38} - D_{39})h(j) + D_{39}h(j+1) \quad \dots(4.18) \end{aligned}$$

$$\frac{dh}{dx} \text{ at } x = -\Delta x(j)/2 = b - c\Delta x(j) + d \frac{3}{4} \Delta x^2(j)$$

$$\begin{aligned} = & D_{31}h(j-2) - D_{32}h(j-1) + (-D_{31} + D_{32} - D_{33})h(j) + D_{33}h(j+1) \\ & - \{-D_{34}h(j-2) + D_{35}h(j-1) + (D_{34} - D_{35} + D_{36})h(j) - D_{36}h(j+1)\}\Delta x(j) \\ & + \{D_{37}h(j-2) - D_{38}h(j-1) + (-D_{37} + D_{38} - D_{39})h(j) + D_{39}h(j+1)\} \frac{3}{4} \Delta x^2(j) \\ = & h(j-2) \left\{ D_{31} + D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{32} - D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\} \\ & + h(j) \left\{ -D_{31} + D_{32} - D_{33} - (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39}) \frac{3}{4} \Delta x^2(j) \right\} \\ & + h(j+1) \left\{ D_{33} + D_{36}\Delta x(j) + D_{39} \frac{3}{4} \Delta x^2(j) \right\} \end{aligned}$$

$$\frac{dh}{dx} \text{ at } x = \Delta x(j)/2 = b + c\Delta x(j) + d \frac{3}{4} \Delta x^2(j)$$

$$\begin{aligned} = & D_{31}h(j-2) - D_{32}h(j-1) + (-D_{31} + D_{32} - D_{33})h(j) + D_{33}h(j+1) \\ & + \{-D_{34}h(j-2) + D_{35}h(j-1) + (D_{34} - D_{35} + D_{36})h(j) - D_{36}h(j+1)\}\Delta x(j) \end{aligned}$$

$$\begin{aligned}
& + \left\{ D_{37}h(j-2) - D_{38}h(j-1) + (-D_{37} + D_{38} - D_{39})h(j) + D_{39}h(j+1) \right\} \frac{3}{4} \Delta x^2(j) \\
& = h(j-2) \left\{ D_{31} - D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{32} + D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j) \left\{ -D_{31} + D_{32} - D_{33} + (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+1) \left\{ D_{33} - D_{36}\Delta x(j) + D_{39} \frac{3}{4} \Delta x^2(j) \right\}
\end{aligned}$$

Taking into account of the variation in flow during time steps (k-2), (k-1) & kth, the water balance equation is written as:

$$\begin{aligned}
& w1 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
& + w2 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
& + w3 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} = S \frac{\Delta x(j)}{\Delta t} \{h(j, k) - h(j, k-1)\}
\end{aligned}$$

Now rearranging the above equation becomes :

$$\begin{aligned}
& -w3T_{HM4}(j) \left[h(j-2) \left\{ D_{31} + D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{32} - D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j) \left\{ -D_{31} + D_{32} - D_{33} - (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39}) \frac{3}{4} \Delta x^2(j) \right\} \\
& \left. + h(j+1) \left\{ D_{33} + D_{36}\Delta x(j) + D_{39} \frac{3}{4} \Delta x^2(j) \right\} \right] \\
& + w3T_{HM2}(j) \left[h(j-2) \left\{ D_{31} - D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{32} + D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j) \left\{ -D_{31} + D_{32} - D_{33} + (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39}) \frac{3}{4} \Delta x^2(j) \right\} \\
& \left. + h(j+1) \left\{ D_{33} - D_{36}\Delta x(j) + D_{39} \frac{3}{4} \Delta x^2(j) \right\} \right] + w1 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
& + w2 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} + T_{HM2}(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} = S \frac{\Delta x(j)}{\Delta t} \{h(j, k) - h(j, k-1)\}
\end{aligned}$$

$$\text{Designating, } F_{44}(j) = -w3T_{HM4}(j) \left\{ D_{31} + D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\}$$

$$+w3T_{HM2}(j) \left\{ D_{31} - D_{34}\Delta x(j) + D_{37} \frac{3}{4} \Delta x^2(j) \right\}$$

$$F_4(j) = -w3T_{HM4}(j) \left\{ -D_{32} - D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\}$$

$$+w3T_{HM2}(j) \left\{ -D_{32} + D_{35}\Delta x(j) - D_{38} \frac{3}{4} \Delta x^2(j) \right\}$$

$$F_1(j) = -w3T_{HM4}(j) \left\{ -D_{31} + D_{32} - D_{33} - (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39}) \frac{3}{4} \Delta x^2(j) \right\}$$

$$+w3T_{HM2}(j) \left\{ -D_{31} + D_{32} - D_{33} + (D_{34} - D_{35} + D_{36})\Delta x(j) + (-D_{37} + D_{38} - D_{39})\frac{3}{4}\Delta x^2(j) \right\} - S\frac{\Delta x(j)}{\Delta t}$$

$$F_2(j) = -w3T_{HM4}(j) \left\{ D_{33} + D_{36}\Delta x(j) + D_{39}\frac{3}{4}\Delta x^2(j) \right\} + w3T_{HM2}(j) \left\{ D_{33} - D_{36}\Delta x(j) + D_{39}\frac{3}{4}\Delta x^2(j) \right\}$$

$$F_6(j, k) = S\frac{\Delta x(j)}{\Delta t} h(j, k-1) + w1 \left\{ -T_{HM4}(j)\frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j)\frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\}$$

$$+ w2 \left\{ -T_{HM4}(j)\frac{dh}{dx} \Big|_{ax=-\Delta x(j)/2} + T_{HM2}(j)\frac{dh}{dx} \Big|_{ax=\Delta x(j)/2} \right\}$$

Finally the equation can be written as:

$$F_{44}(j)h(j-2, k) + F_4(j)h(j-1, k) + F_1(j)h(j, k) + F_2(j)h(j+1, k) + F_6(j, k) = 0$$

4.3.4 Equation for Boundary Node (right) i.e. $j = j_{\max}$

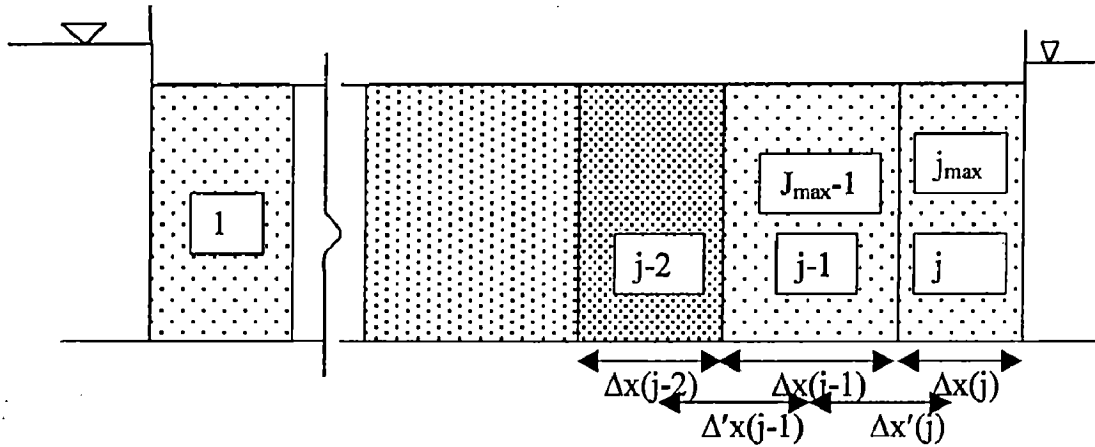


Fig.4.8 Discretisation of flow domain origin at node j_{\max}

Selecting the origin at j th node. Let the head $h(x)$ at $j_{\max}-2 \leq x \leq \Delta x(j)/2$, be expressed as:

$h(x) = a + bx + cx^2 + dx^3$, where constants a, b, c, d are derived in terms of $h(j-2), h(j-1), h(j)$ & $h(j+1)$.

Designating, $\Delta'x(j) = \{\Delta x(j-1) + \Delta x(j)\}/2$

$$\Delta'x(j-1) = \{\Delta x(j-2) + \Delta x(j-1)\}/2$$

Now at $x = 0$, $h(x) = h(j) = a$;

$$\text{At } x = -\{\Delta'x(j) + \Delta'x(j-1)\}, \quad h\{-\Delta'x(j) - \Delta'x(j-1)\} = h(j-2)$$

$$h(j-2) - h(j) = -b\{\Delta'x(j) + \Delta'x(j-1)\} + c\{\Delta'x(j) + \Delta'x(j-1)\}^2 - d\{\Delta'x(j) + \Delta'x(j-1)\}^3 \quad \dots(4.19)$$

$$\begin{aligned}
x &= -\Delta'x(j), & h\{-\Delta'x(j)\} &= h(j-1) \\
h(j-1) - h(j) &= -b\Delta'x(j) + c\Delta'x^2(j) - d\Delta'x^3(j) && \dots(4.20)
\end{aligned}$$

$$\begin{aligned}
x &= \frac{\Delta x(j)}{2}, & h\{\Delta x(j)/2\} &= h(j+1) \\
h(j+1) - h(j) &= b\frac{\Delta x(j)}{2} + c\frac{\Delta x^2(j)}{4} + d\frac{\Delta x^3(j)}{8} && \dots(4.21)
\end{aligned}$$

Above equations are solved for getting b, c, d:

$$\text{Designating, } \begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\}\{\Delta'x(j) + \Delta'x(j-1)\}^2 - \{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ -\Delta'x(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ \frac{\Delta x(j)}{2} & \frac{\Delta x^2(j)}{4} & \frac{\Delta x^3(j)}{8} \end{vmatrix} = D$$

$$\therefore b = \begin{vmatrix} h(j-2) - h(j) & \{\Delta'x(j) + \Delta'x(j-1)\}^2 & -\{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ h(j-1) - h(j) & \Delta'x^2(j) & -\Delta'x^3(j) \\ h(j+1) - h(j) & \frac{\Delta x^2(j)}{4} & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D$$

$$\text{Or } b = \begin{vmatrix} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) & \frac{\Delta x^2(j)}{4} \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} \Delta'x^2(j) & \frac{\Delta x^2(j)}{4} \\ -\Delta'x^3(j) & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D = D_{51}$$

$$\begin{vmatrix} \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \frac{\Delta x^2(j)}{4} \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D = D_{52}$$

$$\begin{vmatrix} \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) \end{vmatrix} / D = D_{53}$$

$$\begin{aligned}
\text{Hence } b &= \{h(j-2) - h(j)\}D_{51} - \{h(j-1) - h(j)\}D_{52} - \{h(j+1) - h(j)\}D_{53} \\
&= D_{51}h(j-2) - D_{52}h(j-1) + (-D_{51} + D_{52} - D_{53})h(j) + D_{53}h(j+1) && \dots(4.22)
\end{aligned}$$

$$\text{Now } c = \begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & h(j-2) - h(j) & -\{\Delta'x(j) + \Delta'x(j-1)\}^3 \\ -\Delta'x(j) & h(j-1) - h(j) & -\Delta'x^3(j) \\ \frac{\Delta x(j)}{2} & h(j+1) - h(j) & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D$$

$$\text{Or } c = \begin{vmatrix} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) & \frac{\Delta x(j)}{2} \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D$$

$$\text{Designating, } \begin{vmatrix} -\Delta'x(j) & \frac{\Delta x(j)}{2} \\ -\Delta'x^3(j) & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D = D_{54}$$

$$\begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & \frac{\Delta x(j)}{2} \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & \frac{\Delta x^3(j)}{8} \end{vmatrix} / D = D_{55}$$

$$\begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\}^3 & -\Delta'x^3(j) \end{vmatrix} / D = D_{56}$$

$$\begin{aligned} \text{Hence } c &= -\{h(j-2) - h(j)\}D_{54} + \{h(j-1) - h(j)\}D_{55} - \{h(j+1) - h(j)\}D_{56} \\ &= -D_{54}h(j-2) + D_{55}h(j-1) + (D_{54} - D_{55} + D_{56})h(j) - D_{56}h(j+1) \end{aligned} \quad \dots(4.23)$$

$$\therefore d = \begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & \{\Delta'x(j) + \Delta'x(j-1)\}^2 & h(j-2) - h(j) \\ -\Delta'x(j) & \Delta'x^2(j) & h(j-1) - h(j) \\ \frac{\Delta x(j)}{2} & \frac{\Delta x^2(j)}{4} & h(j+1) - h(j) \end{vmatrix} / D$$

$$\text{Or } d = \begin{vmatrix} h(j-2) - h(j) & h(j-1) - h(j) & h(j+1) - h(j) \\ -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) & \frac{\Delta x(j)}{2} \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) & \frac{\Delta x^2(j)}{4} \end{vmatrix} / D$$

$$\begin{vmatrix} -\Delta'x(j) & \frac{\Delta x(j)}{2} \\ \Delta'x^2(j) & \frac{\Delta x^2(j)}{4} \end{vmatrix} / D = D_{57}$$

$$\begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & \frac{\Delta x(j)}{2} \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \frac{\Delta x^2(j)}{4} \end{vmatrix} / D = D_{58}$$

$$\begin{vmatrix} -\{\Delta'x(j) + \Delta'x(j-1)\} & -\Delta'x(j) \\ \{\Delta'x(j) + \Delta'x(j-1)\}^2 & \Delta'x^2(j) \end{vmatrix} / D = D_{59}$$

$$d = \{h(j-2) - h(j)\}D_{57} - \{h(j-1) - h(j)\}D_{58} + \{h(j+1) - h(j)\}D_{59}$$

$$= D_{57}h(j-2) - D_{58}h(j-1) + (-D_{57} + D_{58} - D_{59})h(j) + D_{59}h(j+1) \quad \dots(4.24)$$

The gradient, $\frac{dh}{dx_{atx=-\Delta x(j)/2}} = b - c\Delta x(j) + d \frac{3}{4} \Delta x^2(j)$

$$= D_{51}h(j-2) - D_{52}h(j-1) + (-D_{51} + D_{52} - D_{53})h(j) + D_{53}h(j+1)$$

$$- [-D_{54}h(j-2) + D_{55}h(j-1) + (D_{54} - D_{55} + D_{56})h(j) - D_{56}h(j+1)] \Delta x(j)$$

$$+ [D_{57}h(j-2) - D_{58}h(j-1) + (-D_{57} + D_{58} - D_{59})h(j) + D_{59}h(j+1)] \frac{3}{4} \Delta x^2(j)$$

$$= h(j-2) \left\{ D_{51} + D_{54} \Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{52} - D_{55} \Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ h(j) \left\{ -D_{51} + D_{52} - D_{53} - (D_{54} - D_{55} + D_{56}) \Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ h(j+1) \left\{ D_{53} + D_{56} \Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\}$$

$$\frac{dh}{dx_{atx=\Delta x(j)/2}} = b + c\Delta x(j) + d \frac{3}{4} \Delta x^2(j)$$

$$= D_{51}h(j-2) - D_{52}h(j-1) + (-D_{51} + D_{52} - D_{53})h(j) + D_{53}h(j+1)$$

$$+ [-D_{54}h(j-2) + D_{55}h(j-1) + (D_{54} - D_{55} + D_{56})h(j) - D_{56}h(j+1)] \Delta x(j)$$

$$+ [D_{57}h(j-2) - D_{58}h(j-1) + (-D_{57} + D_{58} - D_{59})h(j) + D_{59}h(j+1)] \frac{3}{4} \Delta x^2(j)$$

This can be rearranged as:

$$\frac{dh}{dx_{atx=\Delta x(j)/2}} = h(j-2) \left\{ D_{51} - D_{54} \Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{52} + D_{55} \Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ h(j) \left\{ -D_{51} + D_{52} - D_{53} + (D_{54} - D_{55} + D_{56}) \Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\}$$

$$+ h(j+1) \left\{ D_{53} - D_{56} \Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\}$$

Taking into account of the variation of flow during time steps (k-2), (k-1), kth time steps, the water balance equation is written as:

$$w1 \left\{ -T_{HM4}(j) \frac{dh}{dx_{atx=-\Delta x(j)/2}} \right\} + \left\{ T(j) \frac{dh}{dx_{atx=\Delta x(j)/2}} \right\}$$

$$+ w2 \left\{ -T_{HM4}(j) \frac{dh}{dx_{atx=-\Delta x(j)/2}} \right\} + \left\{ T(j) \frac{dh}{dx_{atx=\Delta x(j)/2}} \right\}$$

$$+ w3 \left\{ -T_{HM4}(j) \frac{dh}{dx_{atx=-\Delta x(j)/2}} \right\} + \left\{ T(j) \frac{dh}{dx_{atx=\Delta x(j)/2}} \right\} = S \frac{\Delta x(j)}{\Delta t} h(j, k) - h(j, k-1)$$

Above equation is rearranged as:

$$\begin{aligned}
& -w3T_{HM4}(j) \left[h(j-2) \left\{ D_{51} + D_{54}\Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} + h(j-1) \left\{ -D_{52} - D_{55}\Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j) \left\{ -D_{51} + D_{52} - D_{53} - (D_{54} - D_{55} + D_{56})\Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+1) \left\{ D_{53} + D_{56}\Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\} \left. \right] + w3T(j) \left[h(j-2) \left\{ D_{51} - D_{54}\Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} \right. \\
& + h(j-1) \left\{ -D_{52} + D_{55}\Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j) \left\{ -D_{51} + D_{52} - D_{53} + (D_{54} - D_{55} + D_{56})\Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + h(j+1) \left\{ D_{53} - D_{56}\Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\} \left. \right] + w1 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} \right\} + w1 \left\{ T(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
& + w2 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} \right\} + w2 \left\{ T(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} = S \frac{\Delta x(j)}{\Delta t} h(j, k) - h(j, k-1)
\end{aligned}$$

Designating,

$$\begin{aligned}
F_{44}(j) &= -w3T_{HM4}(j) \left\{ D_{51} + D_{54}\Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} + w3T(j) \left\{ D_{51} - D_{54}\Delta x(j) + D_{57} \frac{3}{4} \Delta x^2(j) \right\} \\
F_4(j) &= -w3T_{HM4}(j) \left\{ -D_{52} - D_{55}\Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\} + w3T(j) \left\{ -D_{52} + D_{55}\Delta x(j) - D_{58} \frac{3}{4} \Delta x^2(j) \right\} \\
F_1(j) &= -w3T_{HM4}(j) \left\{ -D_{51} + D_{52} - D_{53} - (D_{54} - D_{55} + D_{56})\Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\} \\
& + w3T(j) \left\{ -D_{51} + D_{52} - D_{53} + (D_{54} - D_{55} + D_{56})\Delta x(j) + (-D_{57} + D_{58} - D_{59}) \frac{3}{4} \Delta x^2(j) \right\} - \frac{\Delta x(j)}{\Delta t} S \\
F_6(j, k) &= S \frac{\Delta x(j)}{\Delta t} h(j, k-1) - w3T_{HM4}(j) \left\{ D_{53} + D_{56}\Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\} h(j+1, k) \\
& + w3T(j) \left\{ D_{53} - D_{56}\Delta x(j) + D_{59} \frac{3}{4} \Delta x^2(j) \right\} h(j+1) \\
& + w1 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} \right\} + w1 \left\{ T(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\} \\
& + w2 \left\{ -T_{HM4}(j) \frac{dh}{dx} \Big|_{atx=-\Delta x(j)/2} \right\} + w2 \left\{ T(j) \frac{dh}{dx} \Big|_{atx=\Delta x(j)/2} \right\}
\end{aligned}$$

Finally the equation becomes:

$$F_{44}(j)h(j-2, k) + F_4(j)h(j-1, k) + F_1(j)h(j, k) + F_6(j, k) = 0$$

CHAPTER-5 RESULT AND DISCUSSION

In Appendix-2, a computer programme has been written which calculates heads at nodes using the improved finite difference scheme. In order to compare the improved finite difference scheme with the existing finite difference schemes, numerical results are obtained for the following set of data:

$T = 100\text{m}^2/\text{day}$, $S = 0.02$, initial head = 10m, duration of simulation = 10days,

$\Delta x = 10\text{m}, 50\text{m}, 100\text{m}$, $\Delta t = 0.01, 0.1, 1$

Two types of variation in boundary head is assumed:

- i) A step rise in stream stage at $x = 0$;
- ii) A ramp rise in stream stage at $x = 0$;

There is no rise in stream stage at $x = L$.

For small time step i.e. $\Delta t = 0.01$, the boundary condition at $x = L$ will not be effective and the aquifer will behave like a semi- infinite aquifer bounded by the stream at $x = 0$, for which the analytical solution is given by Carslaw and Jaegar for an analogous heat conduction problem. The numerical results obtained by the finite difference scheme are compared with the analytical solution.

The hydraulic heads computed by improved finite difference scheme, completely implicit scheme and Crank Nicholson Scheme for $\Delta t = 0.1, 0.01$ are presented in Table-5.1, 5.2, 5.3, 5.4, 5.5, 5.6 respectively. It could be seen that the computed heads tally with the analytical results as expected.

Oscillation in the computed head at a grid corresponding to a step rise in stream stage is exhibited in numerical method. The oscillation is very prominent for course time step at grid adjacent to the boundary. Oscillation is caused when the actual boundary inflow is not accounted truly. For a step rise in stream stage the influent seepage rate to the grid adjacent to the boundary is infinite.

It is implied that existing finite difference schemes consider the flow rate during any time step and the actual volume of flow that enters to the grid during the first time step is not accounted correctly leading to oscillation. Oscillation decreases with decreasing time step. The oscillation when a time step sizes are 0.1, 0.01, are presented in Fig.5.1, 5.2,

5.3, 5.4, 5.5, 5.6, 5.7, 5.8 respectively.

Results for ramp input are presented in Table- 5.7, 5.8 and 5.9.

It is seen that for small time step size, as expected all finite difference schemes, the existing one and the proposed one perform equally.

For non- homogeneous case the head variation will be sharp within small distance and the proposed finite difference scheme which takes care of variation of head with time and space will be more efficient.

Table-5.1

Results: by Improved Finite Difference Scheme for Step Input
(For Delt=0.1)

TRANS= 100.000000
 STORC= 2.000000E-02
 JMAX DELTAX
 8 10.00
 NTIME DELT
 10 .10
 BHL BHR HI
 15.00 10.00 10.00

THE RESULTS ARE FOR A STEP INPUT

FIRST TIME STEP

W2= 0.000000E+00

W3= 1.000000

HEAD(METRE) AT DIFFERENT TIMES AND NODES

13.999	12.562	11.637	11.039	10.649	10.388	10.206	10.064
14.849	13.987	12.988	12.114	11.423	10.897	10.491	10.156
14.269	13.623	13.123	12.553	11.942	11.344	10.783	10.257
15.106	14.185	13.274	12.571	11.979	11.417	10.855	10.286
14.066	13.841	13.466	12.835	12.145	11.488	10.875	10.289
15.528	14.189	13.259	12.681	12.145	11.562	10.944	10.316
13.474	13.955	13.636	12.886	12.155	11.510	10.904	10.302
16.438	14.080	13.144	12.731	12.223	11.599	10.950	10.314
12.124	14.164	13.811	12.853	12.111	11.516	10.930	10.315
18.462	13.750	12.952	12.813	12.292	11.599	10.926	10.302

RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY

3.9993	2.5618	1.6366	1.0388	.6487	.3884	.2057	.0642
4.8494	3.9865	2.9877	2.1137	1.4233	.8972	.4909	.1558
4.2692	3.6233	3.1229	2.5532	1.9423	1.3436	.7828	.2567
5.1060	4.1850	3.2737	2.5707	1.9787	1.4174	.8549	.2858
4.0661	3.8415	3.4657	2.8349	2.1450	1.4882	.8749	.2887
5.5283	4.1886	3.2593	2.6806	2.1447	1.5618	.9443	.3156
3.4741	3.9546	3.6359	2.8860	2.1546	1.5096	.9036	.3016
6.4382	4.0804	3.1438	2.7309	2.2227	1.5994	.9499	.3141
2.1241	4.1642	3.8107	2.8532	2.1106	1.5158	.9304	.3146
8.4623	3.7497	2.9519	2.8132	2.2924	1.5995	.9262	.3023

RISE COMPUTED ANALYTICALLY (NODE (1 TO 6)

4.3718	3.1763	2.1460	1.3419	0.7736	0.4100
4.5549	3.6866	2.8808	2.1692	1.5715	1.0938
4.6363	3.9210	3.2404	2.6141	2.0566	1.5765
4.6849	4.0626	3.4632	2.9000	2.3838	1.9225
4.7181	4.1600	3.6184	3.1031	2.6226	2.1834
4.7427	4.2323	3.7344	3.2569	2.8064	2.3884
4.7617	4.2886	3.8254	3.3785	2.9534	2.5547
4.7771	4.3341	3.8993	3.4778	3.0744	2.6930
4.7898	4.3718	3.9607	3.5609	3.1763	2.8104
4.8006	4.4038	4.0129	3.6317	3.2636	2.9116

Table-5.2

□

□

□

Results: by Improved Finite Difference Scheme for Step Input
(for Delt=0.01)

TRANS= 100.000000
 STORC= 2.000000E-02
 JMAX DELTAX
 8 10.00
 NTIME DELT
 10 .01
 BHL BHR HI
 15.00 10.00 10.00
 THE RESULTS ARE FOR A STEP INPUT

FIRST TIME STEP

□

W2= 0.000000E+00

□

W3= 1.000000

□

HEAD(METRE) AT DIFFERENT TIMES AND NODES

□

12.470 10.662 10.177 10.048 10.013 10.003 10.001 10.000

□

13.930 11.421 10.436 10.125 10.035 10.009 10.003 10.000
 13.699 11.982 10.786 10.265 10.082 10.024 10.007 10.001
 14.112 12.242 11.089 10.443 10.158 10.051 10.015 10.003
 14.061 12.529 11.331 10.621 10.255 10.094 10.031 10.007
 14.225 12.692 11.552 10.790 10.361 10.148 10.054 10.013
 14.232 12.860 11.730 10.949 10.470 10.211 10.083 10.021
 14.310 12.976 11.891 11.095 10.579 10.279 10.118 10.032
 14.332 13.087 12.027 11.229 10.685 10.350 10.157 10.044
 14.376 13.175 12.150 11.351 10.787 10.421 10.198 10.057

RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY

□

2.4697 .6618 .1773 .0475 .0127 .0034 .0009 .0002

□

3.9298 1.4206 .4359 .1251 .0348 .0095 .0025 .0004

□

3.6990 1.9821 .7863 .2650 .0816 .0238 .0065 .0012
 4.1122 2.2418 1.0888 .4434 .1580 .0513 .0153 .0030
 4.0607 2.5289 1.3314 .6211 .2550 .0937 .0308 .0066
 4.2250 2.6922 1.5516 .7900 .3609 .1482 .0538 .0127
 4.2320 2.8596 1.7302 .9494 .4703 .2110 .0835 .0211
 4.3101 2.9761 1.8908 1.0946 .5793 .2791 .1184 .0316
 4.3319 3.0873 2.0272 1.2288 .6852 .3498 .1569 .0437
 4.3759 3.1750 2.1496 1.3509 .7869 .4211 .1976 .0568

ANALYTICAL SOLUTION

RISE COMPUTED ANALYTICALLY FOR NODE (1 TO 6)

3.0854 0.6681 0.0621 0.0023 0.0000 0.0000
 3.6184 1.4442 0.3855 0.0666 0.0073 0.0005

3.8642	1.9324	0.7446	0.2165	0.0469	0.0075
4.0129	2.2663	1.0565	0.4006	0.1222	0.0298
4.1153	2.5117	1.3178	0.5876	0.2209	0.0695
4.1913	2.7015	1.5372	0.7652	0.3310	0.1237
4.2505	2.8538	1.7235	0.9294	0.4449	0.1882
4.2984	2.9794	1.8838	1.0796	0.5581	0.2591
4.3382	3.0854	2.0233	1.2167	0.6681	0.3338
4.3718	3.1763	2.1460	1.3419	0.7736	0.4100

Table-5.3

Results: by Implicit Scheme for Step Input
(for Delt=0.1)

THE RESULTS ARE FOR A STEP INPUT
THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELTA						
.100						
TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR	
100.0	.020	10.0	10.0	15.00	10.00	

BOUNDARY CONDITION AT X=0; SRIVL(K)

15.00	15.00	15.00	15.00	15.00	15.00
15.00	15.00	15.00	15.00	15.00	15.00

W2= 0.000000E+00

W3= 1.000000

W1= 0.000000E+00

W2= 0.000000E+00

W3= 1.000000

HEAD (METRE) AT DIFFERENT TIMES AND NODES

13.91	12.50	11.60	11.01	10.63	10.38	10.20	10.06
14.42	13.37	12.48	11.78	11.23	10.79	10.44	10.14
14.56	13.71	12.93	12.23	11.62	11.10	10.63	10.21
14.62	13.87	13.15	12.48	11.86	11.29	10.76	10.25
14.65	13.96	13.28	12.63	12.00	11.41	10.83	10.28
14.67	14.00	13.35	12.71	12.08	11.47	10.88	10.29
14.68	14.03	13.39	12.75	12.13	11.51	10.90	10.30
14.68	14.04	13.41	12.78	12.15	11.53	10.92	10.31
14.68	14.05	13.42	12.79	12.17	11.55	10.93	10.31
14.69	14.06	13.43	12.80	12.18	11.55	10.93	10.31

Table-5.4

Results: by Implicit Scheme for Step Input
(for Delt=0.01)

THE RESULTS ARE FOR A STEP INPUT

THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELT

.010

TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR
100.0	.020	10.0	10.0	15.00	10.00

BOUNDARY CONDITION AT X=0; SRIVL(K)

15.00 15.00 15.00 15.00 15.00

15.00 15.00 15.00 15.00 15.00

W2= 0.000000E+00

W3= 1.000000

W1= 0.000000E+00

W2= 0.000000E+00

W3= 1.000000

HEAD (METRE) AT DIFFERENT TIMES AND NODES

12.11	10.57	10.15	10.04	10.01	10.00	10.00	10.00
13.08	11.15	10.40	10.13	10.04	10.01	10.00	10.00
13.56	11.63	10.67	10.26	10.09	10.03	10.01	10.00
13.82	12.01	10.94	10.40	10.16	10.06	10.02	10.01
13.99	12.30	11.18	10.56	10.25	10.10	10.04	10.01
14.10	12.52	11.40	10.71	10.34	10.15	10.06	10.02
14.18	12.70	11.59	10.86	10.44	10.21	10.09	10.02
14.24	12.85	11.76	11.01	10.54	10.27	10.12	10.03
14.29	12.98	11.91	11.14	10.64	10.33	10.15	10.04
14.33	13.08	12.04	11.26	10.73	10.40	10.19	10.06

Table-5.5

-
-
-
-
-
-
-

Results: by Crank Nicholson Scheme for Step Input
(for Delt=0.1)

THE RESULTS ARE FOR A STEP INPUT

THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELTA					
.100					
TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR
100.0	.020	10.0	10.0	15.00	10.00

BOUNDARY CONDITION AT X=0; SRIVL(K)

15.00	15.00	15.00	15.00	15.00
15.00	15.00	15.00	15.00	15.00

W2= 5.000000E-01

W3= 5.000000E-01

W1= 0.000000E+00

W2= 5.000000E-01

W3= 5.000000E-01

HEAD (METRE) AT DIFFERENT TIMES AND NODES

16.98	13.75	12.01	11.08	10.57	10.30	10.14	10.04
12.74	13.72	13.20	12.35	11.57	10.97	10.52	10.16
15.98	13.72	12.98	12.47	11.93	11.36	10.81	10.27
13.65	14.22	13.47	12.69	12.03	11.43	10.86	10.29
15.45	13.80	13.30	12.77	12.16	11.52	10.90	10.30
14.08	14.26	13.46	12.76	12.14	11.54	10.93	10.31
15.15	13.87	13.41	12.83	12.19	11.55	10.93	10.31
14.32	14.22	13.44	12.79	12.18	11.56	10.94	10.31
14.97	13.93	13.44	12.83	12.19	11.56	10.93	10.31
14.46	14.17	13.43	12.80	12.19	11.56	10.94	10.31

Table-5.6

Results: by Crank Nicholson Scheme for Step Input

(for Delt=0.01)

THE RESULTS ARE FOR A STEP INPUT
 THE INFLOW AT X=0 IS OBTAINED NUMERICALLY
 DELT

.010

TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR
100.0	.020	10.0	10.0	15.00	10.00
BOUNDARY CONDITION AT X=0; SRIVL(K)					
15.00	15.00	15.00	15.00	15.00	
15.00	15.00	15.00	15.00	15.00	

W2= 5.000000E-01

W3= 5.000000E-01

W1= 0.000000E+00

W2= 5.000000E-01

W3= 5.000000E-01

HEAD (METRE) AT DIFFERENT TIMES AND NODES

12.93	10.50	10.09	10.01	10.00	10.00	10.00	10.00
13.54	11.32	10.35	10.08	10.02	10.00	10.00	10.00
13.81	11.84	10.69	10.21	10.06	10.01	10.00	10.00
13.98	12.19	11.00	10.38	10.13	10.04	10.01	10.00
14.09	12.45	11.27	10.56	10.22	10.08	10.02	10.01
14.17	12.65	11.49	10.74	10.32	10.13	10.04	10.01
14.23	12.81	11.68	10.90	10.43	10.19	10.07	10.02
14.28	12.95	11.85	11.05	10.54	10.26	10.11	10.03
14.33	13.06	11.99	11.19	10.65	10.33	10.14	10.04
14.36	13.15	12.11	11.31	10.75	10.40	10.18	10.05

Table-5.7

Results: by Improved Finite Difference Scheme & by Analytical Solution for Ramp Input(Delt=0.1)

Solution by Improved Finite Difference Scheme:

TRANS= 100.000000
 STORC= 2.000000E-02
 JMAX DELTAX
 8 10.00
 NTIME DELT
 10 .10

BHL BHR HI
 15.00 10.00 10.00

FIRST TIME STEP

W2= 0.000000E+00

W3= 1.000000

HEAD (METRE) AT DIFFERENT TIMES AND NODES

10.400	10.256	10.164	10.104	10.065	10.039	10.021	10.006
10.839	10.578	10.390	10.257	10.165	10.101	10.054	10.017
11.294	10.954	10.689	10.485	10.329	10.209	10.116	10.037
11.761	11.343	11.007	10.739	10.522	10.345	10.196	10.063
12.221	11.744	11.343	11.008	10.727	10.490	10.282	10.092
12.699	12.145	11.679	11.283	10.941	10.642	10.373	10.122
13.151	12.552	12.023	11.561	11.156	10.795	10.465	10.153
13.643	12.954	12.363	11.842	11.374	10.950	10.558	10.184
14.076	13.366	12.710	12.121	11.591	11.106	10.651	10.215
14.598	13.762	13.048	12.404	11.811	11.262	10.744	10.246

RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY

.3999 .2562 .1637 .1039 .0649 .0388 .0206 .0064

.8391	.5781	.3897	.2574	.1655	.1012	.0543	.0171
1.2937	.9541	.6891	.4846	.3286	.2094	.1157	.0369
1.7614	1.3434	1.0074	.7385	.5221	.3451	.1960	.0635
2.2207	1.7438	1.3429	1.0076	.7273	.4897	.2820	.0921
2.6989	2.1452	1.6791	1.2828	.9411	.6416	.3726	.1221
3.1511	2.5519	2.0232	1.5609	1.1559	.7950	.4649	.1529
3.6434	2.9541	2.3626	1.8415	1.3745	.9503	.5575	.1837
4.0764	3.3655	2.7096	2.1209	1.5913	1.1060	.6514	.2151
4.5984	3.7624	3.0485	2.4039	1.8112	1.2618	.7443	.2460

Analytical Solution:

PIEZOMETRIC RISE OBTAINED ANALYTICALLY

RISE AT FIRST NODE	.3858	.8337	1.2937	1.7599	2.2302	2.7033	3.1785	3.6555	4.1339	4.6134
RISE AT SECOND NODE	.2200	.5673	.9488	1.3485	1.7599	2.1797	2.6058	3.0370	3.4724	3.9112
RISE AT THIRD NODE	.1180	.3747	.6824	1.0183	1.3728	1.7407	2.1189	2.5052	2.8983	3.2971
RISE AT FORTH NODE	.0593	.2399	.4809	.7575	1.0582	1.3765	1.7085	2.0515	2.4035	2.7632
RISE AT FIFTH NODE	.0278	.1486	.3318	.5548	.8056	1.0775	1.3657	1.6673	1.9800	2.3021

Table-5.8

Results: by Implicit Scheme for Ramp Input

(for Delt=0.1)

THE RESULTS ARE FOR A RAMP INPUT

THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELTA						
.100						
TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR	
100.0	.020	10.0	10.0	15.00	10.00	

BOUNDARY CONDITION AT X=0; SRIVL(K)

10.50	11.00	11.50	12.00	12.50
13.00	13.50	14.00	14.50	15.00

W2= 0.000000E+00

W3= 1.000000

W1= 0.000000E+00

W2= 0.000000E+00

W3= 1.000000

HEAD (METRE) AT DIFFERENT TIMES AND NODES

10.39	10.25	10.16	10.10	10.06	10.04	10.02	10.01
10.83	10.59	10.41	10.28	10.19	10.12	10.06	10.02
11.29	10.96	10.70	10.50	10.35	10.23	10.13	10.04
11.75	11.34	11.02	10.75	10.53	10.36	10.20	10.07
12.22	11.74	11.34	11.01	10.74	10.50	10.29	10.09
12.68	12.14	11.68	11.28	10.94	10.64	10.38	10.12
13.15	12.54	12.02	11.56	11.16	10.80	10.47	10.15
13.62	12.95	12.36	11.84	11.37	10.95	10.56	10.18
14.09	13.35	12.70	12.12	11.59	11.10	10.65	10.21
14.55	13.76	13.04	12.40	11.81	11.26	10.74	10.25

Table-5.9

Results: by Crank Nicholson Scheme for Ramp Input
(for Delt=0.1)

THE RESULTS ARE FOR A RAMP INPUT
THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELT						
.100						
TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR	
100.0	.020	10.0	10.0	15.00	10.00	

BOUNDARY CONDITION AT X=0; SRIVL(K)						
10.50	11.00	11.50	12.00	12.50		
13.00	13.50	14.00	14.50	15.00		

W2= 5.000000E-01
W3= 5.000000E-01
W1= 0.000000E+00
W2= 5.000000E-01
W3= 5.000000E-01

HEAD (METRE) AT DIFFERENT TIMES AND NODES							
10.35	10.19	10.10	10.05	10.03	10.01	10.01	10.00
10.84	10.56	10.36	10.22	10.14	10.08	10.04	10.01
11.27	10.93	10.67	10.47	10.31	10.20	10.11	10.03
11.75	11.33	10.99	10.72	10.51	10.33	10.19	10.06
12.21	11.73	11.33	11.00	10.72	10.48	10.28	10.09
12.68	12.13	11.67	11.27	10.93	10.64	10.37	10.12
13.15	12.54	12.01	11.55	11.15	10.79	10.46	10.15
13.62	12.95	12.35	11.83	11.37	10.95	10.56	10.18
14.08	13.35	12.70	12.11	11.59	11.10	10.65	10.21
14.56	13.76	13.04	12.40	11.80	11.26	10.74	10.25

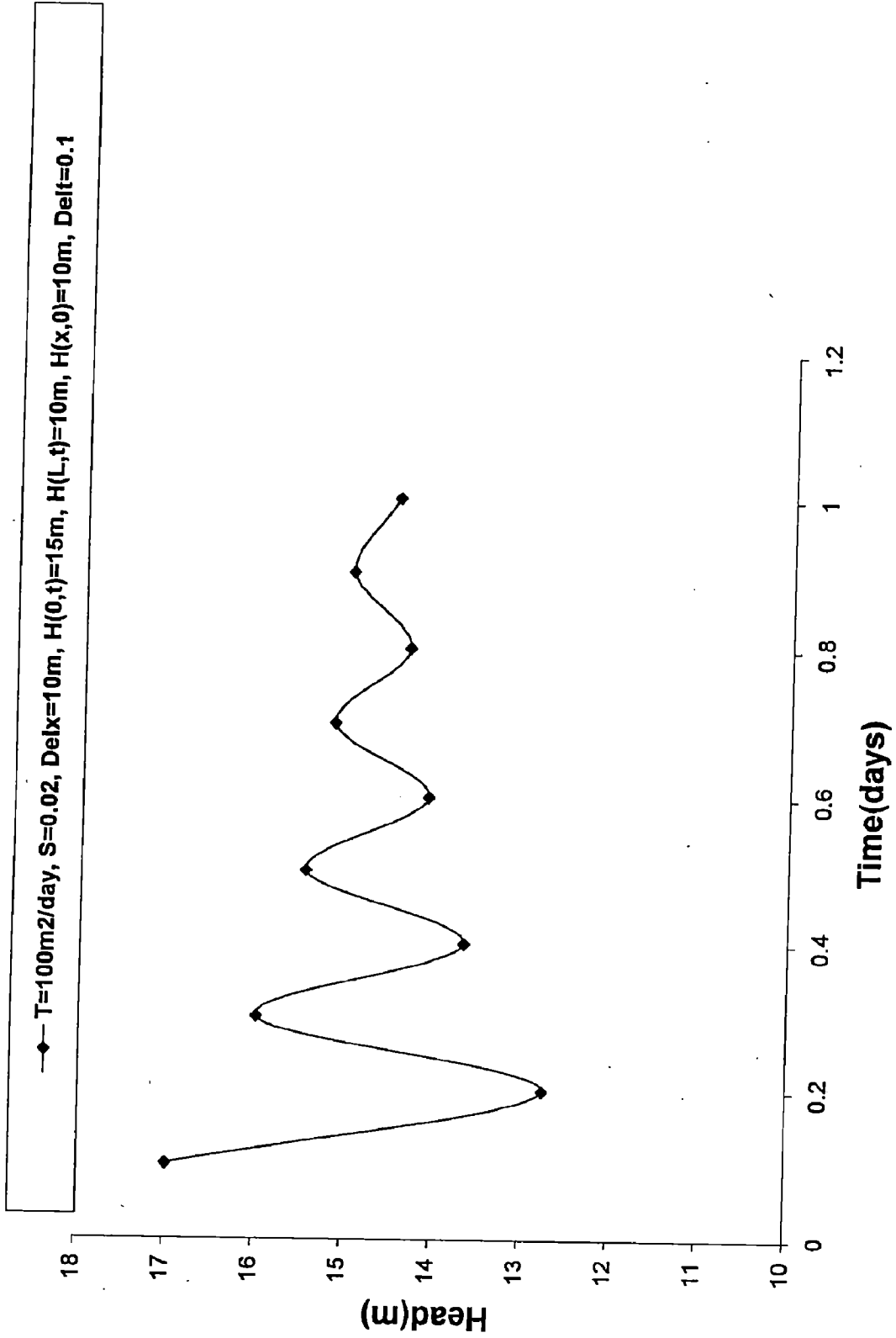


Fig.5.1: Head vs. Time curve($x=0\text{m}$, $t=0.1\text{day}$), by Crank Nicholson Scheme

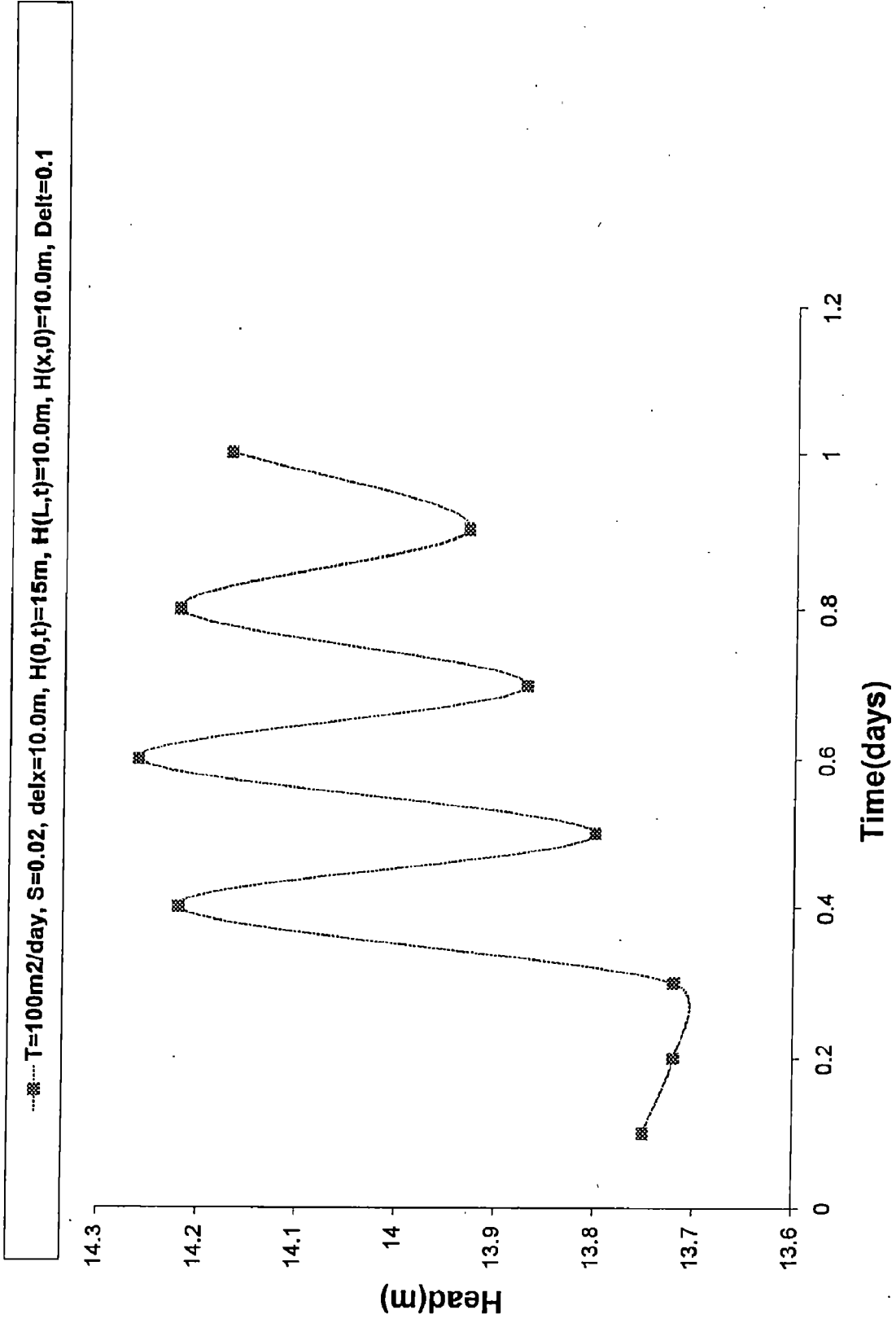


Fig.5.2 : Head vs. Time curve ($x=10.0\text{m}$, $t=0.1\text{day}$), by Crank Nicholson scheme

—◆— $T=100\text{m}^2/\text{day}$, $S=0.02$, $\text{Delx}=10.0\text{m}$, $H(0,t)=15.0\text{m}$, $H(L,t)=10.0\text{m}$, $H(x,0)=10.0\text{m}$, $H(L,t)=10.0\text{m}$, $\text{Delt}=0.1$

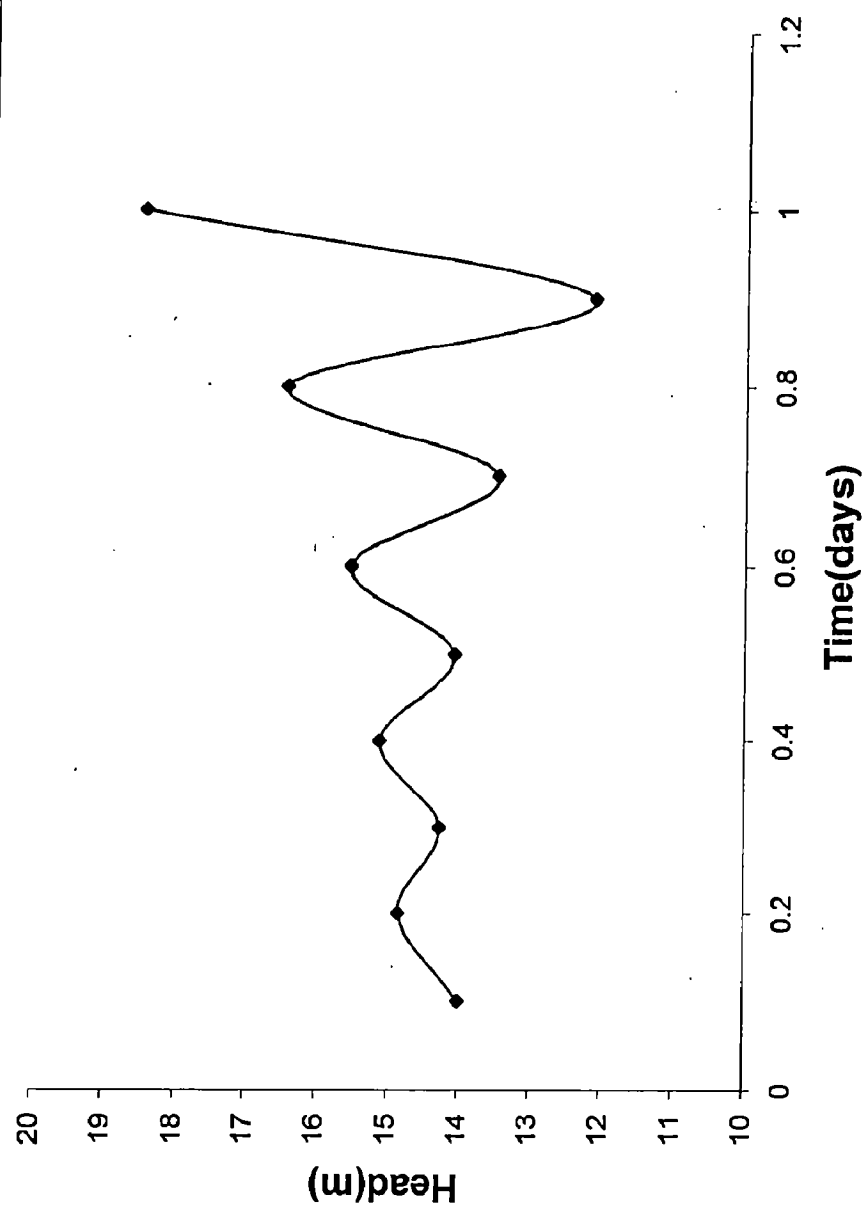


Fig. 5.3 : Head vs. Time curve ($x=0\text{m}$, $t=0.1$ day), by Improved Finite Difference Scheme.

$T=100\text{m}^2/\text{day}$, $S=0.02$, $\text{Delx}=10.0\text{m}$, $H(0,t)=15.0\text{m}$, $H(L,t)=10.0\text{m}$, $H(x,0)=10.0\text{m}$, $\text{Delt}=0.1$

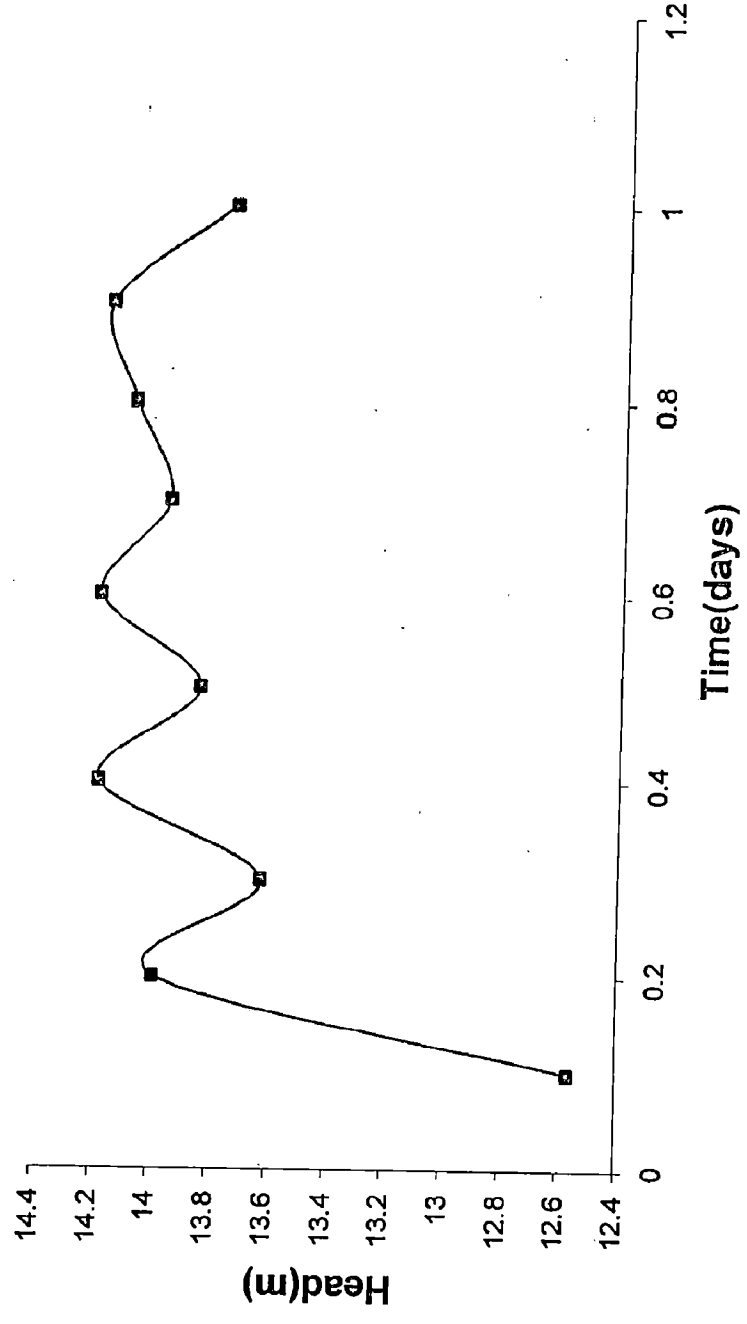


Fig. 5.4 : Head vs. Time curve ($x=10\text{m}$, $t=0.1$ day), by Improved Finite Difference Scheme.

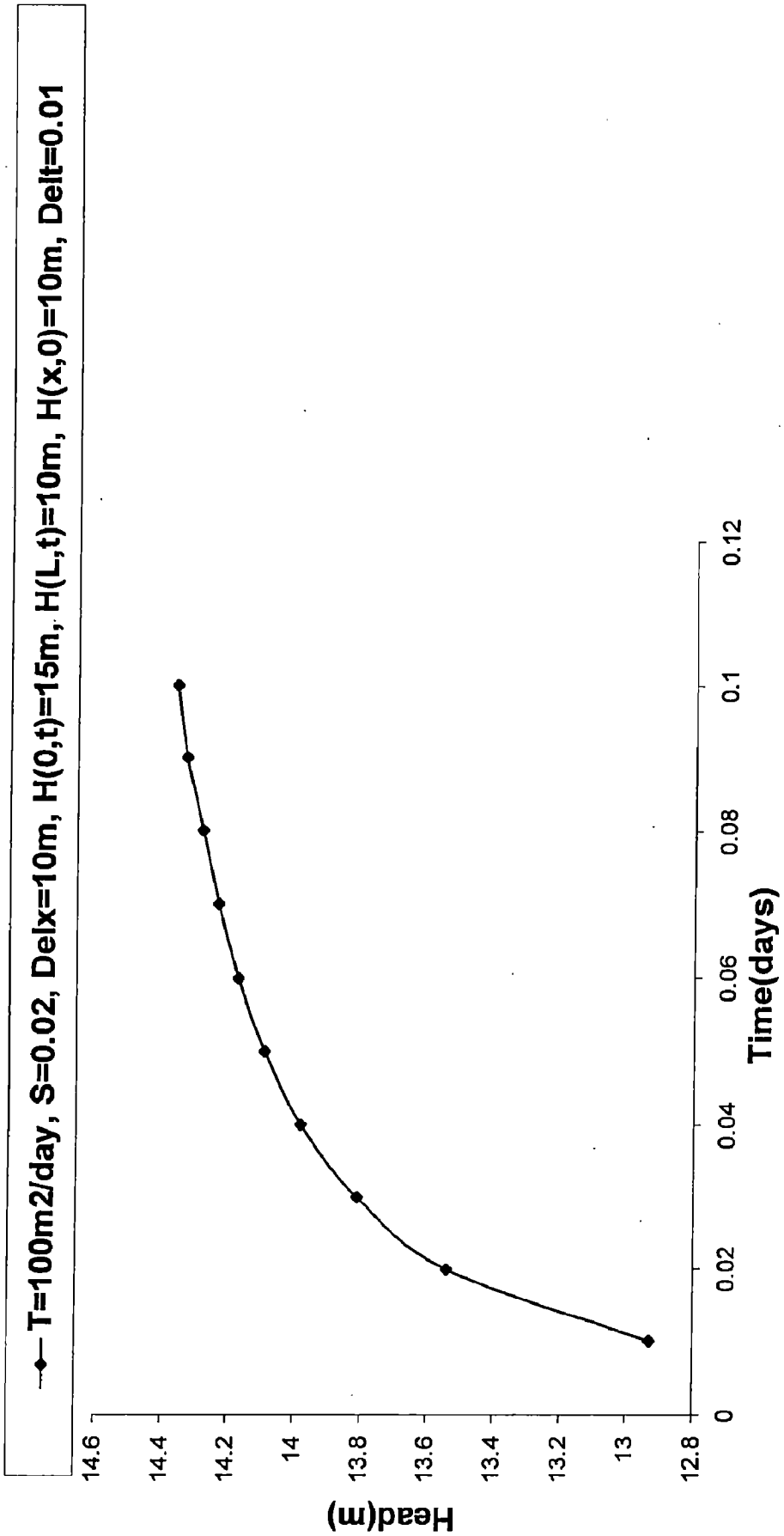


Fig. 5.5 : Head vs. Time curve ($x=0\text{m}$, $t=0.01$ day), by Crank Nicholson Scheme.

-■- $T=100\text{m}^2/\text{day}$, $S=0.02$, $\Delta x=10\text{m}$, $H(0,t)=15\text{m}$, $H(L,t)=10\text{m}$,
 $H(x,0)=10\text{m}$, $\Delta t=0.01$

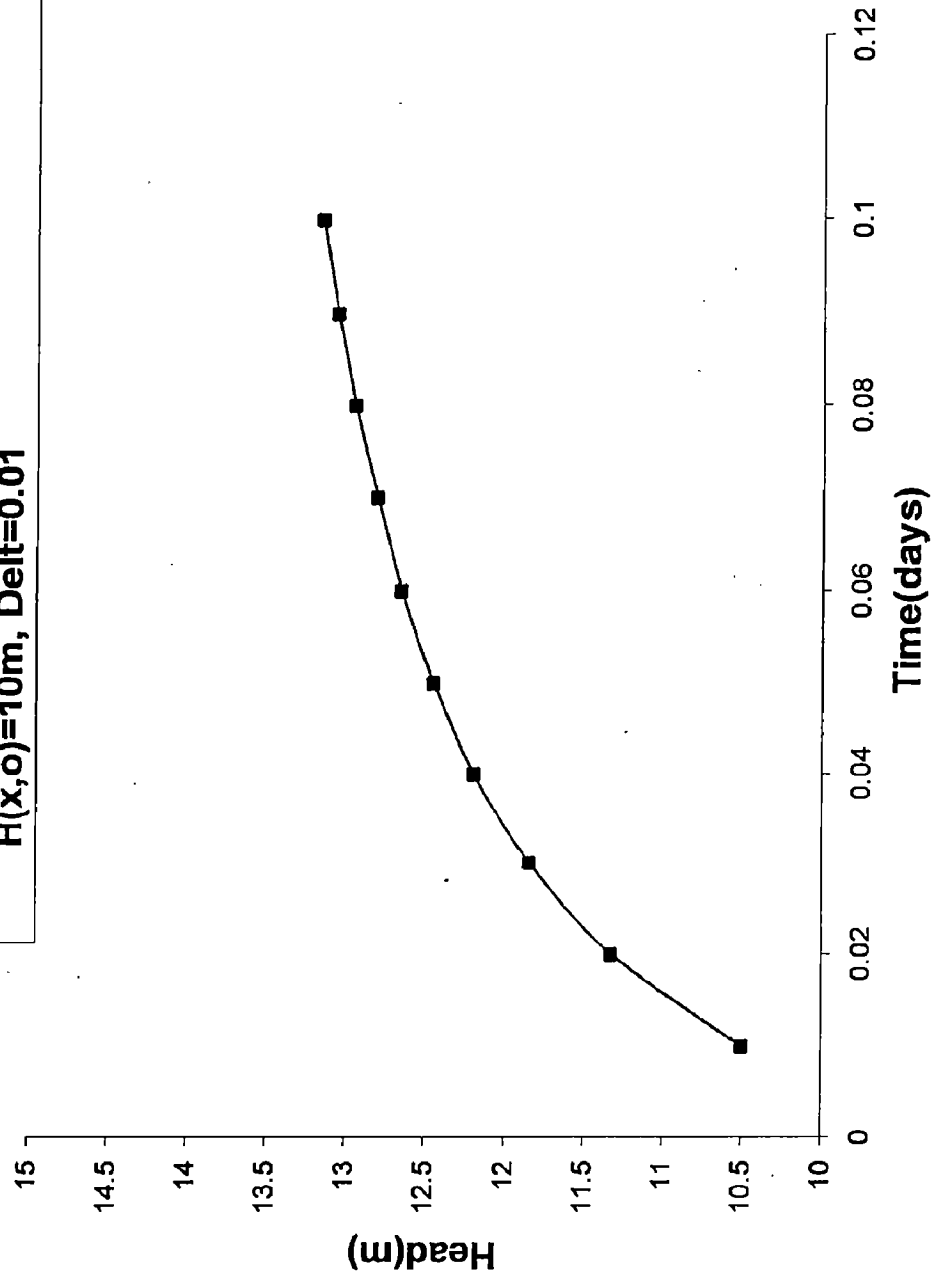


Fig. 5.6 : Head vs. Time curve ($x=10\text{m}$, $t=0.01$ day), by Crank Nicholson Scheme.

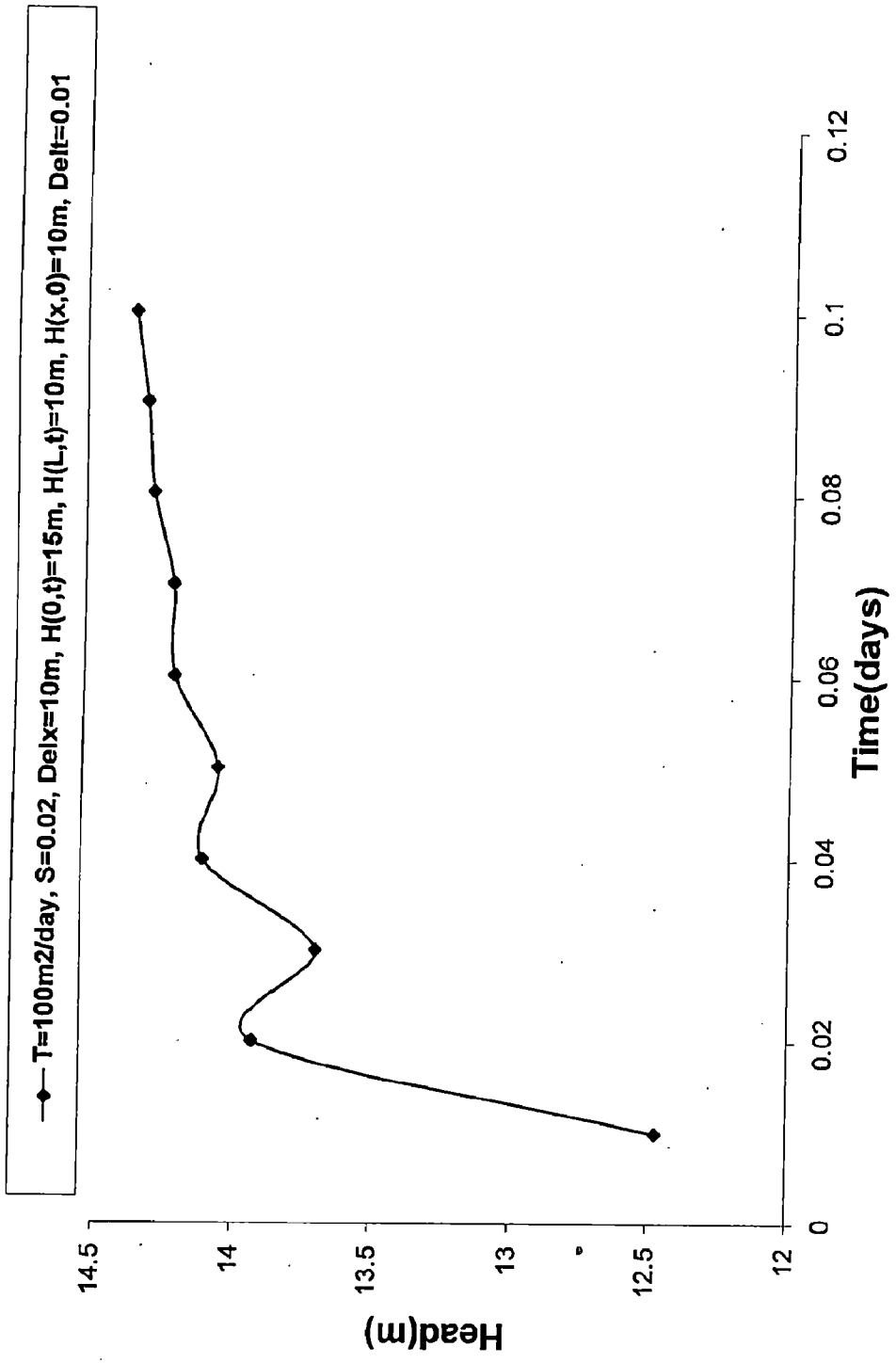


Fig. 5.7 : Head vs. Time curve ($x=0\text{m}$, $t=0.01$ day), by Improved Finite Difference Scheme.

—■— $T=100\text{m}^2/\text{day}$, $S=0.02$, $\text{Delx}=10\text{m}$, $H(0,t)=15\text{m}$, $H(L,t)=10\text{m}$, $H(x,0)=10\text{m}$, $\text{Delt}=0.01$

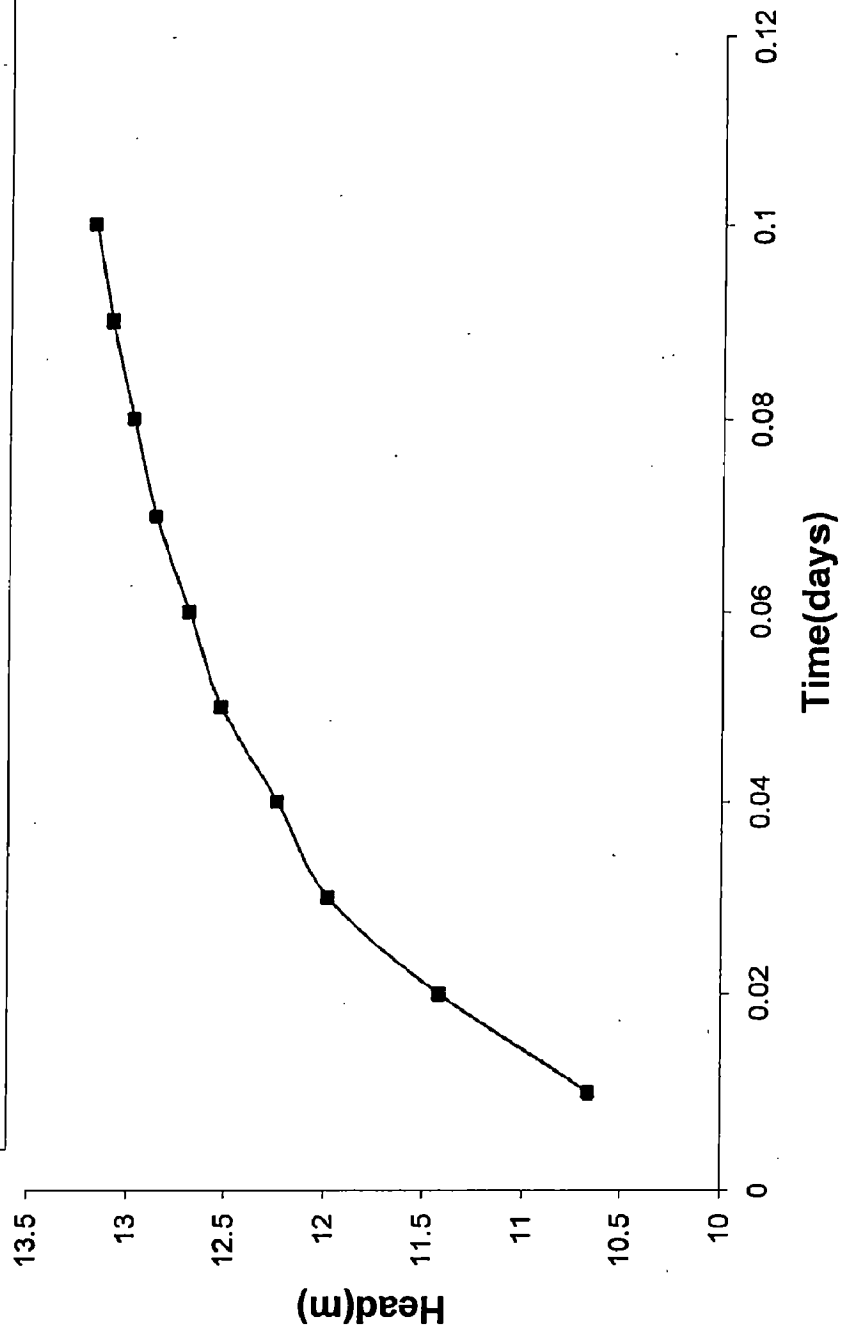


Fig. 5.8 : Head vs. Time curve ($x=10\text{m}$, $t=0.01$ day), by Improved Finite Difference Scheme.

CHAPTER -6

CONCLUSION

Following conclusions are made:

- In existing finite difference method, the spatial variation of flow is assumed non-linear which follows a second-degree equation.
- For small time step, the existing finite difference scheme and the improved finite difference scheme performs equally and the result tallies with analytical solution.
- All numerical methods exhibit oscillations in computed head. The oscillation is prominent for course time step at grid adjacent to the boundary.
- Oscillation is caused when the actual boundary inflow is not accounted truly.
- For non-homogeneous case, the improved finite difference scheme which takes care of variation of head with time and space will be more efficient.

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APPENDICES

APPENDIX- 1

Let us consider that the spatial variation of head in the vicinity of x_0 follows an equation of the form $h = a_1 + b_1(x-x_0) + c_1(x-x_0)^2$

$$h = h(x) + \left[\frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} - \frac{\Delta x_1}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} \right] (x - x_0)$$

$$+ \frac{1}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} (x - x_0)^2$$

$$\Delta x_1 = \frac{\Delta x(j) + \Delta x(j+1)}{2}; \Delta x_2 = \frac{\Delta x(j-1) + \Delta x(j)}{2}$$

The gradient at any point within $(x_0 - \Delta x_2) \leq x \leq (x_0 + \Delta x_1)$

$$\frac{\partial h}{\partial x} = b_1 + 2c_1(x - x_0)$$

Substituting the value of b_1 and c_1

$$\frac{\partial h}{\partial x} = \left[\frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} - \frac{\Delta x_1}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} \right]$$

$$+ \frac{2}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} (x - x_0)$$

$$\frac{\partial h}{\partial x \text{ at } x_0 - \Delta x_2 / 2} = \left[\frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} - \frac{\Delta x_1}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} \right]$$

$$+ \frac{2}{\Delta x_1 + \Delta x_2} \left\{ \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} + \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_2} \right\} \left(x_0 - \frac{\Delta x_2}{2} - x_0 \right)$$

$$= \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} - \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1 + \Delta x_2} - \frac{\Delta x_1}{\Delta x_2 (\Delta x_1 + \Delta x_2)} \{ h(x_0 - \Delta x_2) - h(x_0) \}$$

$$- \frac{\Delta x_2}{\Delta x_1 + \Delta x_2} \frac{h(x_0 + \Delta x_1) - h(x_0)}{\Delta x_1} - \frac{h(x_0 - \Delta x_2) - h(x_0)}{\Delta x_1 + \Delta x_2}$$

$$= h(x_0 + \Delta x_1) \left\{ \frac{1}{\Delta x_1} - \frac{1}{\Delta x_1 + \Delta x_2} - \frac{\Delta x_2}{\Delta x_1 (\Delta x_1 + \Delta x_2)} \right\}$$

$$+ h(x_0) \left\{ -\frac{1}{\Delta x_1} + \frac{1}{\Delta x_1 + \Delta x_2} + \frac{\Delta x_1}{\Delta x_2 (\Delta x_1 + \Delta x_2)} + \frac{\Delta x_2}{\Delta x_1 (\Delta x_1 + \Delta x_2)} + \frac{1}{\Delta x_1 + \Delta x_2} \right\} - \frac{h(x_0 - \Delta x_2)}{\Delta x_1 + \Delta x_2}$$

$$- \frac{\Delta x_1 h(x_0 - \Delta x_2)}{\Delta x_2 (\Delta x_1 + \Delta x_2)}$$

$$= \frac{h(x_0) - h(x_0 - \Delta x_2)}{\Delta x_2}$$

$$= \frac{h(j) - h(j-1)}{\frac{\Delta x(j-1) + \Delta x(j)}{2}}$$

In finite difference the gradient between two consecutive grid points is also given by the above equation.

APPENDIX - 2
COMPUTER PROGRAMME

APPENDIX - 2A

```

C     THIS PROGRAMME COMPUTES HEAD BY THE NEW FINITE DIFFERENCE METHOD
C     THE GRID SIZES ARE EQUAL, THE AQUIFER IS NON HOMOGENEOUS
      DIMENSION DELX(25), T(25), S(25), TRISE(25,100)
      DIMENSION SRIVR(0:100), H(25,0:100), SRIVL(0:100), RISE(25,100)
      DIMENSION FC1(25), FC2(25), FC4(25), FC22(25),
1         FC44(25), FC6(25,100), HSOL(25),
2         A(25,25), RIGHT(25), DKER(100), SIGMA(0:100)
C     DIMENSION AA(25,25), AAAA(25,25)

      OPEN(1, FILE='SREST.DAT', STATUS='OLD')
      OPEN(2, FILE='SREST.OUT', STATUS='UNKNOWN')

C
      READ(1, *) JMAX, DELTAX
      READ(1, *) TRANS, STORC
      READ(1, *) DELT, NTIME
      READ(1, *) BHL, BHR, HI
      WRITE(2, *) 'TRANS=', TRANS
      WRITE(2, *) 'STORC=', STORC
      WRITE(2, 60)
60     FORMAT(2X, 'JMAX', 5X, 'DELTAX')
      WRITE(2, 51) JMAX, DELTAX
51     FORMAT(2X, I2, 4X, F8.2)

      DO J=1, JMAX
      DELX(J)      =DELTAX
      END DO
      WRITE(2, 70)
70     FORMAT(2X, 'NTIME', 2X, 'DELT')
      WRITE(2, 51) NTIME, DELT

C
      WRITE(2, 61)
61     FORMAT(5X, 'BHL', 5X, 'BHR', 5X, 'HI')
      WRITE(2, 52) BHL, BHR, HI
52     FORMAT(3F10.2)

      DO J=1, JMAX
      H(J,0)=HI
      END DO
      SRIVR(0)=BHR
C     SRIVL(0)=BHL
      SRIVL(0)=HI
      SIGMA(0)=HI
      WRITE(2, *) 'THE RESULTS ARE FOR A RAMP INPUT'
      DO K=1, NTIME
      AK=K
      SRIVR(K)=BHR
      SRIVL(K)=HI+(BHL-HI)*DELT*AK
      SIGMA(K)=SRIVL(K)
      END DO

C
C     TRANSMISSIVITY VALUES ARE BEING READ
C
C     READ(1, *) (T(J), J=1, JMAX)
C     WRITE(2, 54) (T(J), J=1, JMAX)
C54    FORMAT(6F8.2)

```



```

C
DO J=1, JMAX
T(J)=TRANS
END DO

C
C
C STORAGE COEFFICIENT VALUES ARE BEING READ
C
C
C READ(1, *) (S(J), J=1, JMAX)
C WRITE(2, 54) (S(J), J=1, JMAX)
C
DO J=1, JMAX
S(J)=STORC
END DO

C
M=JMAX
DO I=1, M
DO J=1, M
A(I, J)=0.
END DO
END DO
K=1
C
W2=0.5
C
W3=0.5
W2=0.
W3=1.
WRITE(2, *) 'FIRST TIME STEP'
WRITE(2, *) 'W2=', W2
WRITE(2, *) 'W3=', W3
J=1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
FC22(J)=W3*(-18.*T(J)-6.*HMT2)
FC2(J)=W3*(100.*T(J)+140.*HMT2)
FC1(J)=-120*S(J)*DELX(J)**2/DELT+W3*(-450.*T(J)-150.*HMT2)
DO J=2, JMAX-2
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC22(J)=W3*(HMT4-HMT2)
FC2(J)=W3*(-3.*HMT4+27.*HMT2)
FC1(J)=-24.*S(J)*DELX(J)**2/DELT+W3*(-21.*HMT4-27.*HMT2)
FC4(J)=W3*(23.*HMT4+HMT2)
END DO

J=JMAX-1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC2(J)=W3*(HMT4+23.*HMT2)
FC1(J)=-24.*S(J)*DELX(J)**2/DELT+W3*(-27.*HMT4-21.*HMT2)
FC4(J)=W3*(27.*HMT4-3.*HMT2)
FC44(J)=W3*(-HMT4+HMT2)

J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC1(J)=-120.*S(J)*DELX(J)**2/DELT+W3*(-150.*HMT4-450.*T(J))
FC4(J)=W3*(140.*HMT4+100.*T(j))
FC44(J)=W3*(-6.*HMT4-18.*T(j))

I=1
A(I, I)=FC1(I)
A(I, I+1)=FC2(I)
A(I, I+2)=FC22(I)

```

```

DO I=2, JMAX-2
A(I, I-1)=FC4(I)
A(I, I)=FC1(I)
A(I, I+1)=FC2(I)
A(I, I+2)=FC22(I)
END DO

I=JMAX-1

A(I, I+1)=FC2(I)
A(I, I)=FC1(I)
A(I, I-1)=FC4(I)
A(I, I-2)=FC44(I)

I=JMAX
A(I, I)=FC1(I)
A(I, I-1)=FC4(I)
A(I, I-2)=FC44(I)

C WRITE(2, *) 'ELEMENT OF THE MATRIX'
C DO I=1, M
C WRITE(2, 197) (A(I, J), J=1, M)
C END DO

C STORING OF THE MATRIX ELEMENT
C DO I=1, M
C DO J=1, M
C AA(I, J)=A(I, J)
C END DO
C END DO
C DO I=1, M
C WRITE(2, 197) ( A(I, J), J=1, M)
C END DO
197 FORMAT(7E10.4)
C
C CALL MATIN (A, M)
C WRITE(2, *) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1, M
C WRITE(2, 197) (A(I, J), J=1, M)
C END DO

C WRITE(2, *) 'CHECKING THE MATRIX INVERSION'
C KK=0
C DO I=1, M
C SUM=0
C KK=KK+1
C DO J=1, M
C SUM=SUM+AA(I, J)*A(J, I)
C END DO
C AAAA(I, KK)=SUM
C END DO
C DO I=1, M
C WRITE(2, 197) (AAAA(I, J), J=1, M)
C END DO
C SOLUTION FOR THE FIRST TIME STEP
C FC6(J, 1) AT INTERIOR NODES
K=1
J=1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
FC6(J, K)=(120.*S(J)*DELX(J)**2/DELTA)*H(J, K-1)-w2*T(J)*
1(18.*h(j+2, k-1)-100.*h(j+1, k-1)+450.*h(j, k-1)-368.*srivl(k-1))+

```

```

2 w2*HMT2*(-6.*h(j+2,k-1)+140.*h(j+1,k-1)-150.*h(j,k-1)+
3 16.*srivl(k-1))+
4 w3*(368.*T(j)*srivl(k)+16.*HMT2*srivl(k))

DO J=2,JMAX-2
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC6(J,K)=(24*S(J)*DELX(J)**2/DELTA)*H(J,K-1)
1 -w2*HMT4*(-h(j+2,k-1)+3.*h(j+1,k-1)+21.*h(j,k-1)-23.*h(j-1,k-1))
2 +w2*HMT2*(-h(j+2,k-1)+27.*h(j+1,k-1)-27.*h(j,k-1)+h(j-1,k-1))
END DO

J=JMAX-1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC6(J,K)=(24.*S(J)*DELX(J)**2/DELTA)*H(J,K-1)
1 -w2*HMT4*(h(j-2,k-1)-27.*h(j-1,k-1)+27.*h(j,k-1)-h(j+1,k-1))
2 +w2*HMT2*(h(j-2,k-1)-3.*h(j-1,k-1)-21.*h(j,k-1)+23.*h(j+1,k-1))

J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC6(J,K)=(120.*S(J)*DELX(J)**2/DELTA)*H(J,K-1)
1 -w2*HMT4*(-16.*srivr(k-1)+150.*h(j,k-1)-140.*h(j-1,k-1)
2 +6.*h(j-2,k-1))+w2*T(j)*
3 (368.*srivr(k-1)-450.*h(j,k-1)+100.*h(j-1,k-1)-18.*h(j-2,k-1))
4 +w3*(16.*HMT4*srivr(k)+368.*T(j)*srivr(k))

C
INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
RIGHT(INDEX)=-FC6(J,K)
END DO

C WRITE(2,*)'K=',K
C WRITE(2,*)'RIGHTHAND COLUMN MATRIX'
C WRITE(2,197)(RIGHT(J),J=1,JMAX)

DO I=1,M
HSOL(I)=0.
DO J=1,M
HSOL(I)=HSOL(I)+A(I,J)*RIGHT(J)
END DO
END DO

C
INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
H(J,K)=HSOL(INDEX)
END DO

C SOLUTION FOR K=2

M=JMAX

DO I=1,M
DO J=1,M
A(I,J)=0.

```

END DO
END DO

K=2

W1=-1./12.
W2=2./3.
W3=5./12.

J=1

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
FC22(J)=W3*(-18.*T(J)-6.*HMT2)
FC2(J)=W3*(100.*T(J)+140.*HMT2)
FC1(J)=-120*S(J)*DELX(J)**2/DELTA+W3*(-450.*T(J)-150.*HMT2)

DO J=2, JMAX-2

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC22(J)=W3*(HMT4-HMT2)
FC2(J)=W3*(-3.*HMT4+27.*HMT2)
FC1(J)=-24.*S(J)*DELX(J)**2/DELTA+W3*(-21.*HMT4-27.*HMT2)
FC4(J)=W3*(23.*HMT4+HMT2)

END DO

J=JMAX-1

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC2(J)=W3*(HMT4+23.*HMT2)
FC1(J)=-24.*S(J)*DELX(J)**2/DELTA+W3*(-27.*HMT4-21.*HMT2)
FC4(J)=W3*(27.*HMT4-3.*HMT2)
FC44(J)=W3*(-HMT4+HMT2)

J=JMAX

HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
FC1(J)=-120.*S(J)*DELX(J)**2/DELTA+W3*(-150.*HMT4-450.*T(J))
FC4(J)=W3*(140.*HMT4+100.*T(J))
FC44(J)=W3*(-6.*HMT4-18.*T(J))

I=1

A(I, I)=FC1(I)
A(I, I+1)=FC2(I)
A(I, I+2)=FC22(I)

DO I=2, JMAX-2

A(I, I-1)=FC4(I)
A(I, I)=FC1(I)
A(I, I+1)=FC2(I)
A(I, I+2)=FC22(I)
END DO

I=JMAX-1

A(I, I+1)=FC2(I)
A(I, I)=FC1(I)
A(I, I-1)=FC4(I)
A(I, I-2)=FC44(I)

I=JMAX

A(I, I)=FC1(I)
A(I, I-1)=FC4(I)
A(I, I-2)=FC44(I)

```

C WRITE(2,*) 'ELEMENT OF THE MATRIX FOR K=2'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO
C STORING OF THE MATRIX ELEMENT
C DO I=1,M
C DO J=1,M
C AA(I,J)=A(I,J)
C END DO
C END DO
C CALL MATRIX INVERSE
C WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C DO I=1,M
C WRITE(2,197) ( A(I,J),J=1,M)
C END DO

CALL MATIN (A,M)

C WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO

C WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
C KK=0
C DO I=1,M
C SUM=0
C KK=KK+1
C DO J=1,M
C SUM=SUM+AA(I,J)*A(J,I)
C END DO
C AAAA(I, KK)=SUM
C END DO

C DO I=1,M
C WRITE(2,197) (AAAA(I,J),J=1,M)
C END DO

C SOLUTION FOR THE 2ND TIME STEP ONWARD

1000 CONTINUE
J=1
FC6(J,K)=(120.*S(J)*DELX(J)**2/DELT)*H(J,K-1)-w1*T(J)*
1(18.*h(j+2,k-2)-100.*h(j+1,k-2)+450.*h(j,k-2)-368.*srivl(k-2))+
2w1*HMT2*(-6.*h(j+2,k-2)+140.*h(j+1,k-2)-150.*h(j,k-2)+
316.*srivl(k-2))-w2*T(J)*
4(18.*h(j+2,k-1)-100.*h(j+1,k-1)+450.*h(j,k-1)-368.*srivl(k-1))+
6w2*HMT2*(-6.*h(j+2,k-1)+140.*h(j+1,k-1)-150.*h(j,k-1)
7+16.*srivl(k-1))+ W3*(368.*T(J)*srivl(k)+16.*HMT2*srivl(k))

DO J=2,JMAX-2

FC6(J,K)=(24*S(J)*DELX(J)**2/DELT)*H(J,K-1)
1-w1*HMT4*(-h(j+2,k-2)+3.*h(j+1,k-2)+21.*h(j,k-2)-23.*h(j-1,k-2))
2-w2*HMT4*(-h(j+2,k-1)+3.*h(j+1,k-1)+21.*h(j,k-1)-23.*h(j-1,k-1))
3+w1*HMT2*(-h(j+2,k-2)+27.*h(j+1,k-2)-27.*h(j,k-2)+h(j-1,k-2))
4+w2*HMT2*(-h(j+2,k-1)+27.*h(j+1,k-1)-27.*h(j,k-1)+h(j-1,k-1))

END DO

```

```

      J=JMAX-1
      FC6(J,K)=(24*S(J)*DELX(J)**2/DELT)*H(J,K-1)
      1-w1*HMT4*(h(j-2,k-2)-27.*h(j-1,k-2)+27.*h(j,k-2)-h(j+1,k-2))
      2-w2*HMT4*(h(j-2,k-1)-27.*h(j-1,k-1)+27.*h(j,k-1)-h(j+1,k-1))
      3+w1*HMT2*(h(j-2,k-2)-3.*h(j-1,k-2)-21.*h(j,k-2)+23.*h(j+1,k-2))
      4+w2*HMT2*(h(j-2,k-1)-3.*h(j-1,k-1)-21.*h(j,k-1)+23.*h(j+1,k-1))
      J=JMAX
      FC6(J,K)=(120.*S(J)*DELX(J)**2/DELT)*H(J,K-1)-w1*HMT4*
      1(-16.*srivr(k-2)+150.*h(j,k-2)-140.*h(j-1,k-2)+6.*h(j-2,k-2))
      3+w1*T(j)*(368.*srivr(k-2)-450.*h(j,k-2)+100.*h(j-1,k-2)
      4-18.*h(j-2,k-2))-w2*HMT4*
      5(-16.*srivr(k-1)+150.*h(j,k-1)-140.*h(j-1,k-1)+6.*h(j-2,k-1))
      6+w2*T(j)*(368.*srivr(k-1)-450.*h(j,k-1)+100.*h(j-1,k-1)-
      718.*h(j-2,k-1))+w3*(16.*HMT4*srivr(k)+368.*T(j)*srivr(k))
      INDEX=0
      DO J=1,JMAX
      INDEX=INDEX+1
      RIGHT(INDEX)=-FC6(J,K)
      END DO
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'RIGHTHAND COLUMN MATRIX'
C     WRITE(2,*)(RIGHT(J),J=1,JMAX)
      DO I=1,M
      HSOL(I)=0.
      DO J=1,M
      HSOL(I)=HSOL(I)+A(I,J)*RIGHT(J)
      END DO
      END DO
C
      INDEX=0
      DO J=1,JMAX
      INDEX=INDEX+1
      H(J,K)=HSOL(INDEX)
      END DO

      K=K+1
      IF(K.LE.NTIME)GO TO 1000
C     WRITE(2,*)'COMPUTATION OVER'
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'HEAD VALUES ARE WRITTEN HERE'

      DO K=1,NTIME
C     WRITE(2,*)'TIME STEP=',K
      WRITE(2,222)(H(J,K),J=1,JMAX)
      END DO
222  FORMAT(10F8.3)

      DO K=1,NTIME
      DO J=1,JMAX
      RISE(J,K)=H(J,K)-HI
      END DO
      END DO
      WRITE(2,*)'RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY'

      DO K=1,NTIME
      WRITE(2,333)(RISE(J,K),J=1,JMAX)
      END DO
C     WRITE(2,*)'PIEZOMETRIC RISE OBTAINED ANALYTICALLY'

```

```

DISTX=DELX(1)/2.
T=TRANS*DELT
PHI=STORC
DO J=1,NTIME
CALL DISCK(DISTX,T,PHI,J,RES)
DKER(J)=RES
END DO

```

```

DO N=1,NTIME
SUM=0.
DO NGAMA=1,N
SUM=SUM+(SIGMA(NGAMA)-SIGMA(NGAMA-1))*DKER(N-NGAMA+1)
END DO
TRISE(1,N)=SUM
END DO

```

333 format(10f7.4)

```

DISTX=DELX(1)+DELX(2)/2.
DO J=1,NTIME
CALL DISCK(DISTX,T,PHI,J,RES)
DKER(J)=RES
END DO

```

```

DO N=1,NTIME
SUM=0.
DO NGAMA=1,N
SUM=SUM+(SIGMA(NGAMA)-SIGMA(NGAMA-1))*DKER(N-NGAMA+1)
END DO
TRISE(2,N)=SUM
END DO

```

```

write(2,333)(trise(1,k),k=1,ntime)
WRITE(2,*)'RISE AT SECOND NODE'
write(2,333)(trise(2,k),k=1,ntime)
STOP
END

```

```

SUBROUTINE MATIN (AAA,MMM)
DIMENSION AAA(25,25),B(25),C(25)
NN=MMM-1
AAA(1,1)=1./AAA(1,1)
DO 8 M=1,NN
K=M+1
DO 3 I=1,M
B(I)=0.0
DO 3 J=1,M
3 B(I)=B(I)+AAA(I,J)*AAA(J,K)
D=0.0
DO 4 I=1,M
4 D=D+AAA(K,I)*B(I)
D=-D+AAA(K,K)
AAA(K,K)=1./D
DO 5 I=1,M
5 AAA(I,K)=-B(I)*AAA(K,K)
DO 6 J=1,M
C(J)=0.0
DO 6 I=1,M
6 C(J)=C(J)+AAA(K,I)*AAA(I,J)

```

```

DO 7 J=1,M
7 AAA(K,J)=-C(J)*AAA(K,K)
DO 8 I=1,M
DO 8 J=1,M
8 AAA(I,J)=AAA(I,J)-B(I)*AAA(K,J)
RETURN
END

SUBROUTINE ERF(X,ERFX)
XINDEX=X
X1=X
IF(X)4,5,5
4 X1=-X
5 CONTINUE
IF(X1-15.)1,2,2
1 CONTINUE
T=1.0/(1.0+0.3275911*X1)
ERFX=1.0-(0.25482959*T-0.28449673*T**2+1.42141374*T**3-1.
1 45315202*T**4+1.06140542*T**5)*EXP(-X1**2)
GO TO3
2 ERFX=1.
3 CONTINUE
IF(XINDEX)6,7,7
6 ERFX=-ERFX
7 CONTINUE
C WRITE(2,52)X,ERFX
C52 FORMAT(2F10.5)
RETURN
END

SUBROUTINE DISCK(DISTX,T,PHI,J,RES)
BETA=T/PHI
PAI=3.14159265
C1=2.*SQRT(BETA)
AJ=J
IF (J.EQ.1)GO TO 100
X=DISTX/( C1*SQRT(AJ-1.) )
TERM5=EXP(-X*X)
CALL ERF(X,ERFX)
TERM1=ERFX
X=DISTX/( C1*SQRT(AJ) )
TERM6=EXP(-X*X)
CALL ERF(X,ERFX)
TERM2=ERFX
TERM3=DISTX*SQRT( (AJ-1.) / (BETA*PAI) )
TERM4=DISTX*SQRT( (AJ) / (BETA*PAI) )
RES=1.+( (AJ-1.)+DISTX**2/(2.*BETA) )*TERM1
1 -( AJ+DISTX**2/(2.*BETA) )*TERM2+TERM3*TERM5-TERM4*TERM6
IF(RES.LT.0.0)RES=0.0
IF(abs(RES).LT.0.00001)RES=0.0
GO TO 200
100 X=DISTX/C1
E=EXP(-X*X)
CALL ERF(X,ERFX)
RES=1.-ERFX+DISTX**2/(2.*BETA)*(1.-ERFX)-DISTX/SQRT(BETA*PAI)*E
IF(RES.LT.0.0)RES=0.0
200 CONTINUE
RETURN
END

```


APPENDIX - 2B

```
C THIS PROGRAMME COMPUTES HEADS BY THE IMPROVED FINITE DIFFERENCE
C METHOD AT VARIOUS NODES

C THE GRIDS ARE UNEQUAL, THE AQUIFER IS NON-HOMOGENEOUS

DIMENSION DELX(25),DELXD(25),T(25),S(25),TRISE(25,100)

DIMENSION SRIVR(0:100),H(25,0:100),SRIVL(0:100),RISE(25,100)

DIMENSION FC1(25),FC2(25),FC4(25),FC22(25),
1 FC44(25),FC6(25,100),HSOL(25),
2 A(25,25),RIGHT(25)
DIMENSION AA(25,25),AAAA(25,25)

OPEN(1,FILE='SREST1.DAT',STATUS='OLD')
OPEN(2,FILE='SREST1.OUT',STATUS='UNKNOWN')

READ(1,*)JMAX,DELTAX
c READ(1,*)TRANS,STORC
READ(1,*)DELT,NTIME
READ(1,*)BOUNHL,BOUNHR,HEADI

C
C TRANSMISSIVITY VALUES ARE BEING READ
C
READ(1,*) (T(J),J=1,JMAX)
WRITE(2,54) (T(J),J=1,JMAX)
54 FORMAT(6F8.2)

c DO J=1,JMAX
c T(J)=TRANS
c END DO

C
C STORAGE COEFFICIENT VALUES ARE BEING READ
C
READ(1,*) (S(J),J=1,JMAX)
WRITE(2,54) (S(J),J=1,JMAX)

C
c DO J=1,JMAX
c S(J)=STORC
c END DO

C
C GRID SIZES ARE BEING READ
C
READ(1,*) (DELX(J),J=1,JMAX)
WRITE(2,54) (DELX(J),J=1,JMAX)

C
c DO J=1,JMAX
c DELX(J) =DELTAX
c END DO
C WRITE(2,60)
60 FORMAT(2X,'JMAX',5X,'DELTAX')
C WRITE(2,51)JMAX,DELTAX
51 FORMAT(2X,I2,4X,F8.2)
```

```

WRITE(2,70)
70  FORMAT(2X,'NTIME',6X,'DELT')
    WRITE(2,51)NTIME,DELT

WRITE(2,61)
61  FORMAT(5X,'BOUNHL',5X,'BOUNHR',5X,'HEADI')
    WRITE(2,52)BOUNHL,BOUNHR,HEADI
52  FORMAT(3F10.2)

DO J=1,JMAX
H(J,0)=HEADI
END DO

SRIVR(0)=BOUNHR
C  SRIVL(0)=BOUNHL
    SRIVL(0)=HEADI

DO K=1,NTIME
SRIVR(K)=BOUNHR
SRIVL(K)=BOUNHL
END DO

C
M=JMAX
DO I=1,M
DO J=1,M
A(I,J)=0.
END DO
END DO

K=1

W2=0.5
W3=0.5

J=1

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))

DELXD(J+1)=(DELX(J)+DELX(J+1))/2.
DELXD(J+2)=(DELX(J+1)+DELX(J+2))/2.

D11=DELXD(J+1)**2
D12=DELXD(J+1)**3
D21=(DELXD(J+1)+DELXD(J+2))**2
D22=(DELXD(J+1)+DELXD(J+2))**3

DETERM1=D11*D22-D12*D21

D11=DELXD(J+1)
D12=DELXD(J+1)**3
D21=DELXD(J+1)+DELXD(J+2)
D22=(DELXD(J+1)+DELXD(J+2))**3

DETERM2=D11*D22-D12*D21

D11=DELXD(J+1)
D12=DELXD(J+1)**2
D21=DELXD(J+1)+DELXD(J+2)
D22=(DELXD(J+1)+DELXD(J+2))**2

```

DETERM3=D11*D22-D12*D21

DETER=(-DELX(J)/2.)*DETERM1-(DELX(J)**2/4.)*DETERM2+
1 (-DELX(J)**3/8.)*DETERM3

D11=DELXD(J+1)**2
D12=(DELXD(J+1)+DELXD(J+2))**2
D21=DELXD(J+1)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D41=(D11*D22-D12*D21)/DETER

D11=DELX(J)**2/4.
D12=(DELXD(J+1)+DELXD(J+2))**2
D21=-DELX(J)**3/8.
D22=(DELXD(J+1)+DELXD(J+2))**3

D42=(D11*D22-D12*D21)/DETER

D11=DELX(J)**2/4.
D12=DELXD(J+1)**2
D21=-DELX(J)**3/8.
D22=DELXD(J+1)**3

D43=(D11*D22-D12*D21)/DETER

D11=DELXD(J+1)
D12=DELXD(J+1)+DELXD(J+2)
D21=DELXD(J+1)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D44=(D11*D22-D12*D21)/DETER

D11=-DELX(J)/2.
D12=DELXD(J+1)+DELXD(J+2)
D21=-DELX(J)**3/8.
D22=(DELXD(J+1)+DELXD(J+2))**3

D45=(D11*D22-D12*D21)/DETER

D11=-DELX(J)/2.
D12=DELXD(J+1)
D21=-DELX(J)**3/8.
D22=DELXD(J+1)**3

D46=(D11*D22-D12*D21)/DETER

D11=DELXD(J+1)
D12=DELXD(J+1)+DELXD(J+2)
D21=DELXD(J+1)**2
D22=(DELXD(J+1)+DELXD(J+2))**2

D47=(D11*D22-D12*D21)/DETER

D11=-DELX(J)/2.
D12=DELXD(J+1)+DELXD(J+2)
D21=DELX(J)**2/4.
D22=(DELXD(J+1)+DELXD(J+2))**2

D48=(D11*D22-D12*D21)/DETER

```

D11=-DELX(J)/2.
D12=DELXD(J+1)
D21=DELX(J)**2/4.
D22=DELXD(J+1)**2

D49=(D11*D22-D12*D21)/DETER

FC22(J)=W3*(-T(J)*(D43+D46*DELX(J)+D49*.75*DELX(J)**2)+
1HMT2*(D43-D46*DELX(J)+D49*.75*DELX(J)**2))

FC2(J)=W3*(-T(J)*(-D42-D45*DELX(J)-D48*.75*DELX(J)**2)+HMT2*
1(-D42+D45*DELX(J)-D48*.75*DELX(J)**2))

FC1(J)=W3*(-T(J)*(-D41+D42-D43-(D44-D45+D46)*DELX(J)+
1(-D47+D48-D49)*.75*DELX(J)**2)+HMT2*(-D41+D42-D43+
2(D44-D45+D46)*DELX(J)+(-D47+D48-D49)*.75*DELX(J)**2))-
3S(J)*DELX(J)/DELT
DO J=2,JMAX-2
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

DELXD(J)=(DELX(J-1)+DELX(J))/2.
DELXD(J+1)=(DELX(J)+DELX(J+1))/2.
DELXD(J+2)=(DELX(J+1)+DELX(J+2))/2.

D11=DELXD(J+1)**2
D12=DELXD(J+1)**3
D21=(DELXD(J+1)+DELXD(J+2))**2
D22=(DELXD(J+1)+DELXD(J+2))**3
DETERM1=D11*D22-D12*D21

D11=DELXD(J+1)
D12=DELXD(J+1)**3
D21=DELXD(J+1)+DELXD(J+2)
D22=(DELXD(J+1)+DELXD(J+2))**3
DETERM2=D11*D22-D12*D21

D11=DELXD(J+1)
D12=DELXD(J+1)**2
D21=DELXD(J+1)+DELXD(J+2)
D22=(DELXD(J+1)+DELXD(J+2))**2
DETERM3=D11*D22-D12*D21

DETER=-DELXD(J)*DETERM1-DELXD(J)**2*DETERM2-DELXD(J)**3*DETERM3

D11=DELXD(J+1)**2
D12=(DELXD(J+1)+DELXD(J+2))**2
D21=DELXD(J+1)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D1=(D11*D22-D12*D21)/DETER

D11=DELXD(J)**2
D12=(DELXD(J+1)+DELXD(J+2))**2
D21=-DELXD(J)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D2=(D11*D22-D12*D21)/DETER

D11=DELXD(J)**2

```

D12=DELXD(J+1)**2
D21=-DELXD(J)**3
D22=DELXD(J+1)**3

D3=(D11*D22-D12*D21)/DETER

D11=DELXD(J+1)
D12=DELXD(J+1)+DELXD(J+2)
D21=DELXD(J+1)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D4=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELXD(J+1)+DELXD(J+2)
D21=-DELXD(J)**3
D22=(DELXD(J+1)+DELXD(J+2))**3

D5=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELXD(J+1)
D21=-DELXD(J)**3
D22=DELXD(J+1)**3

D6=(D11*D22-D12*D21)/DETER

D11=DELXD(J+1)
D12=DELXD(J+1)+DELXD(J+2)
D21=DELXD(J+1)**2
D22=(DELXD(J+1)+DELXD(J+2))**2

D7=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELXD(J+1)+DELXD(J+2)
D21=DELXD(J)**2
D22=(DELXD(J+1)+DELXD(J+2))**2

D8=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELXD(J+1)
D21=DELXD(J)**2
D22=DELXD(J+1)**2

D9=(D11*D22-D12*D21)/DETER

FC22(J)=W3*(-HMT4*(D3+D6*DELX(J)+D9*.75*DELX(J)**2)+
1HMT2*(D3-D6*DELX(J)+D9*.75*DELX(J)**2))

FC2(J)=W3*(-HMT4*(-D2-D5*DELX(J)-D8*.75*DELX(J)**2)+
1HMT2*(-D2+D5*DELX(J)-D8*.75*DELX(J)**2))

FC1(J)=W3*(-HMT4*(-D1+D2-D3-(D4-D5+D6)*DELX(J)+
1(-D7+D8-D9)*.75*DELX(J)**2)+
2HMT2*(-D1+D2-D3+(D4-D5+D6)*DELX(J)+
3(-D7+D8-D9)*.75*DELX(J)**2))-S(J)*DELX(J)/DELT

FC4(J)=W3*(-HMT4*(D1+D4*DELX(J)+D7*.75*DELX(J)**2)+

```
1HMT2*(D1-D4*DELX(J)+D7*.75*DELX(j)**2))
END DO
```

```
J=JMAX-1
```

```
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
```

```
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
```

```
DELXD(J-1)=(DELX(J-2)+DELX(J-1))/2.
```

```
DELXD(J)=(DELX(J-1)+DELX(J))/2.
```

```
DELXD(J+1)=(DELX(J)+DELX(J+1))/2.
```

```
D11=DELXD(J)**2
```

```
D12=-DELXD(J)**3
```

```
D21=DELXD(J+1)**2
```

```
D22=DELXD(J+1)**3
```

```
DETERM1=D11*D22-D12*D21
```

```
D11=-DELXD(J)
```

```
D12=-DELXD(J)**3
```

```
D21=DELXD(J+1)
```

```
D22=DELXD(J+1)**3
```

```
DETERM2=D11*D22-D12*D21
```

```
D11=-DELXD(J)
```

```
D12=DELXD(J)**2
```

```
D21=DELXD(J+1)
```

```
D22=DELXD(J+1)**2
```

```
DETERM3=D11*D22-D12*D21
```

```
DETER=- (DELXD(J)+DELXD(J-1))*DETERM1-(DELXD(J)+DELXD(J-1))**2  
1*DETERM2-(DELXD(J)+DELXD(J-1))**3*DETERM3
```

```
D11=DELXD(J)**2
```

```
D12=DELXD(J+1)**2
```

```
D21=-DELXD(J)**3
```

```
D22=DELXD(J+1)**3
```

```
D31=(D11*D22-D12*D21)/DETER
```

```
D11=(DELXD(J)+DELXD(J-1))**2
```

```
D12=DELXD(J+1)**2
```

```
D21=- (DELXD(J)+DELXD(J-1))**3
```

```
D22=DELXD(J+1)**3
```

```
D32=(D11*D22-D12*D21)/DETER
```

```
D11=(DELXD(J)+DELXD(J-1))**2
```

```
D12=DELXD(J)**2
```

```
D21=- (DELXD(J)+DELXD(J-1))**3
```

```
D22=-DELXD(J)**3
```

```
D33=(D11*D22-D12*D21)/DETER
```

```
D11=-DELXD(J)
```

```
D12=DELXD(J+1)
```

```
D21=-DELXD(J)**3
```

```
D22=DELXD(J+1)**3
```

```
D34=(D11*D22-D12*D21)/DETER
```

```

D11=-(DELXD(J)+DELXD(J-1))
D12=DELXD(J+1)
D21=-(DELXD(J)+DELXD(J-1))**3
D22=DELXD(J+1)**3

D35=(D11*D22-D12*D21)/DETER

D11=-(DELXD(J)+DELXD(J-1))
D12=-DELXD(J)
D21=-(DELXD(J)+DELXD(J-1))**3
D22=-DELXD(J)**3

D36=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELXD(J+1)
D21=DELXD(J)**2
D22=DELXD(J+1)**2

D37=(D11*D22-D12*D21)/DETER

D11=-(DELXD(J)+DELXD(J-1))
D12=DELXD(J+1)
D21=(DELXD(J)+DELXD(J-1))**2
D22=DELXD(J+1)**2

D38=(D11*D22-D12*D21)/DETER

D11=-(DELXD(J)+DELXD(J-1))
D12=-DELXD(J)
D21=(DELXD(J)+DELXD(J-1))**2
D22=DELXD(J)**2

D39=(D11*D22-D12*D21)/DETER

FC2(J)=W3*(-HMT4*(D33+D36*DELX(J)+D39*.75*DELX(J)**2)+
1HMT2*(D33-D36*DELX(J)+D39*.75*DELX(J)**2))

FC1(J)=W3*(-HMT4*(-D31+D32-D33-(D34-D35+D36)*DELX(J)+
1(-D37+D38-D39)*.75*DELX(J)**2)+HMT2*(-D31+D32-D33+
2(D34-D35+D36)*DELX(J)+(-D37+D38-D39)*.75*DELX(J)**2))-
3S(J)*DELX(J)/DELT

FC4(J)=W3*(-HMT4*(-D32-D35*DELX(J)-D38*.75*DELX(J)**2)+
1HMT2*(-D32+D35*DELX(J)-D38*.75*DELX(J)**2))

FC44(J)=W3*(-HMT4*(D31+D34*DELX(J)+D37*.75*DELX(J)**2)+
1HMT2*(D31-D34*DELX(J)+D37*.75*DELX(J)**2))
J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
DELXD(J-1)=(DELX(J-2)+DELX(J-1))/2.
DELXD(J)=(DELX(J-1)+DELX(J))/2.

D11=DELXD(J)**2
D12=-DELXD(J)**3
D21=DELX(J)**2/4.
D22=DELX(J)**3/8.

```

DETERM1=D11*D22-D12*D21

D11=-DELXD(J)
D12=-DELXD(J)**3
D21=DELX(J)/2.
D22=DELX(J)**3/8.

DETERM2=D11*D22-D12*D21

D11=-DELXD(J)
D12=DELXD(J)**2
D21=DELX(J)/2.
D22=DELX(J)**2/4.

DETERM3=D11*D22-D12*D21

DETER=- (DELXD(J)+DELXD(J-1)) *DETERM1- (DELXD(J)+DELXD(J-1)) **2*
1DETERM2- (DELXD(J)+DELXD(J-1)) **3*DETERM3

D11=DELXD(J)**2
D12=DELX(J)**2/4.
D12=-DELXD(J)**3
D21=DELX(J)**3/8.

D51=(D11*D22-D12*D21)/DETER

D11=(DELXD(J)+DELXD(J-1))**2
D12=DELX(J)**2/4.
D21=- (DELXD(J)+DELXD(J-1))**3
D22=DELX(J)**3/8.

D52=(D11*D22-D12*D21)/DETER

D11=(DELXD(J)+DELXD(J-1))**2
D12=DELXD(J)**2
D21=- (DELXD(J)+DELXD(J-1))**3
D22=-DELXD(J)**3

D53=(D11*D22-D12*D21)/DETER

D11=-DELXD(J)
D12=DELX(J)/2.
D21=-DELXD(J)**3
D22=DELX(J)**3/8.

D54=(D11*D22-D12*D21)/DETER

D11=- (DELXD(J)+DELXD(J-1))
D12=DELX(J)/2.
D21=- (DELXD(J)+DELXD(J-1))**3
D22=DELX(J)**3/8.

D55=(D11*D22-D12*D21)/DETER

D11=- (DELXD(J)+DELXD(J-1))
D12=-DELXD(J)
D21=- (DELXD(J)+DELXD(J-1))**3
D22=-DELXD(J)**3

D56=(D11*D22-D12*D21)/DETER


```

D11=-DELXD(J)
D12=DELX(J)/2.
D21=DELXD(J)**2
D22=DELX(J)**2/4.

D57=(D11*D22-D12*D21)/DETER

D11=-(DELXD(J)+DELXD(J-1))
D12=DELX(J)/2.
D21=(DELXD(J)+DELXD(J-1))**2
D22=DELX(J)**2/4.

D58=(D11*D22-D12*D21)/DETER

D11=-(DELXD(J)+DELXD(J-1))
D12=-DELXD(J)
D21=(DELXD(J)+DELXD(J-1))**2
D22=DELXD(J)**2

D59=(D11*D22-D12*D21)/DETER

FC1(J)=W3*(-HMT4*(-D51+D52-D53-(D54-D55+D56)*DELX(J)+
1(-D57+D58-D59)*.75*DELX(J)**2)+T(J)*(-D51+D52-D53+
2(D54-D55+D56)*DELX(J)+(-D57+D58-D59)*.75*DELX(J)**2))-
3S(J)*DELX(J)/DELT

FC4(J)=W3*(-HMT4*(-D52-D55*DELX(J)-D58*.75*DELX(J)**2)+
1T(J)*(-D52+D55*DELX(J)-D58*.75*DELX(J)**2))

FC44(J)=W3*(-HMT4*(D51+D54*DELX(J)+D57*.75*DELX(J)**2)+
1T(J)*(D51-D54*DELX(J)+D57*.75*DELX(J)**2))
I=1
A(I,I)=FC1(I)
A(I,I+1)=FC2(I)
A(I,I+2)=FC22(I)

DO I=2,JMAX-2
A(I,I-1)=FC4(I)
A(I,I)=FC1(I)
A(I,I+1)=FC2(I)
A(I,I+2)=FC22(I)
END DO
I=JMAX-1
A(I,I+1)=FC2(I)
A(I,I)=FC1(I)
A(I,I-1)=FC4(I)
A(I,I-2)=FC44(I)
I=JMAX
A(I,I)=FC1(I)
A(I,I-1)=FC4(I)
A(I,I-2)=FC44(I)
C WRITE(2,*)'ELEMENT OF THE MATRIX FOR K=1'
DO I=1,M
C WRITE(2,197)(A(I,J),J=1,M)
END DO

C STORING OF THE MATRIX ELEMENT
DO I=1,M
DO J=1,M
AA(I,J)=A(I,J)
END DO

```

```

END DO

C   CALL MATRIX INVERSE
C   WRITE(2,*)'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C   DO I=1,M
C   WRITE(2,197) ( A(I,J),J=1,M)
C   END DO
197  FORMAT(7E10.4)
C
C
C   CALL MATIN (A,M)
C
C
C   WRITE(2,*)'MATRIX ELEMENT AFTER INVERSION'
C   DO I=1,M
C   WRITE(2,197) (A(I,J),J=1,M)
C   END DO

C   WRITE(2,*)'CHECKING THE MATRIX INVERSION'
C   KK=0
C   DO I=1,M
C   SUM=0
C   KK=KK+1
C   DO J=1,M
C   SUM=SUM+AA(I,J)*A(J,I)
C   END DO
C   AAAA(I, KK)=SUM
C   END DO

C   DO I=1,M
C   WRITE(2,197) (AAAA(I,J),J=1,M)
C   END DO

C   SOLUTION FOR THE FIRST TIME STEP

C   FC6(J,1)  AT  INTERIOR NODES

C   K=1
C   J=1
C   HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))

C   FC6(J,K)=W2*(-T(J)*(D43+D46*DELX(J)+D49*.75*DELX(J)**2)
1  +HMT2*(D43-D46*DELX(J)+D49*.75*DELX(J)**2))*H(J+2,K-1)+
2  W2*(-T(J)*(-D42-D45*DELX(J)-D48*.75*DELX(J)**2)+HMT2*
3  (-D42+D45*DELX(J)-D48*.75*DELX(J)**2))*H(J+1,K-1)+
4  W2*(-T(J)*(-D41+D42-D43-(D44-D45+D46)*DELX(J)+
5  (-D47+D48-D49)*.75*DELX(J)**2)+HMT2*(-D41+D42-D43+
6  (D44-D45+D46)*DELX(J)+(-D47+D48-D49)*.75*DELX(J)**2))*H(J,k-1)+
7  W2*(-T(J)*(D41+D44*DELX(J)+D47*.75*DELX(J)**2)+HMT2*(D41-D44*
8  DELX(J)+D47*.75*DELX(J)**2))*SRIVL(K-1)+
9  S(J)*DELX(J)/DELT*H(J,K-1)
C   FC6(J,K)=FC6(J,K)+ W3*(-T(J)*(D41+D44*DELX(J)
1  +D47*.75*DELX(J)**2)+HMT2*
2  (D41-D44*DELX(J)+D47*.75*DELX(J)**2))*SRIVL(K)

C   DO J=2,JMAX-2
C   HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))

```

```

HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

A1=W2*(-HMT4*(D3+D6*DELX(J)+D9*.75*DELX(J)**2)+
1   HMT2*(D3-D6*DELX(J)+D9*.75*DELX(J)**2))*H(J+2,K-1)+
2   W2*(-HMT4*(-D2-D5*DELX(J)-D8*.75*DELX(J)**2)+
3   HMT2*(-D2+D5*DELX(J)-D8*.75*DELX(J)**2))*H(J+1,K-1)+
4   W2*(-HMT4*(-D1+D2-D3-(D4-D5+D6)*DELX(J)+
5   (-D7+D8-D9)*.75*DELX(J)**2)+
6   HMT2*(-D1+D2-D3+(D4-D5+D6)*DELX(J)+
7   (-D7+D8-D9)*.75*DELX(J)**2))*H(J,K-1)+
8   W2*(-HMT4*(D1+D4*DELX(J)+D7*.75*DELX(J)**2)+
9   HMT2*(D1-D4*DELX(J)+D7*.75*DELX(j)**2))*H(J-1,K-1)
FC6(J,K)=A1+S(J)*DELX(J)/DELT*H(J,K-1)
END DO

J=JMAX-1

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC6(J,k)=W2*(-HMT4*(D33+D36*DELX(J)+D39*.75*DELX(J)**2)+
1   HMT2*(D33-D36*DELX(J)+D39*.75*DELX(J)**2))*H(J+1,K-1)+
2   W2*(-HMT4*(-D31+D32-D33-(D34-D35+D36)*DELX(J)+
3   (-D37+D38-D39)*.75*DELX(J)**2)+HMT2*(-D31+D32-D33+
4   (D34-D35+D36)*DELX(J)+(-D37+D38-D39)*.75*DELX(J)**2))*H(J,K-1)+
5   W2*(-HMT4*(-D32-D35*DELX(J)-D38*.75*DELX(J)**2)+
6   HMT2*(-D32+D35*DELX(J)-D38*.75*DELX(J)**2))*H(J-1,K-1)+
7   W2*(-HMT4*(D31+D34*DELX(J)+D37*.75*DELX(J)**2)+
8   HMT2*(D31-D34*DELX(J)+D37*.75*DELX(J)**2))*H(J-2,K-1)+
9   S(J)*DELX(J)/DELT*H(J,K-1)

J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

A2=W2*(-HMT4*(-D51+D52-D53-(D54-D55+D56)*DELX(J)+
1   (-D57+D58-D59)*.75*DELX(J)**2)+T(J)*(-D51+D52-D53+
2   (D54-D55+D56)*DELX(J)+(-D57+D58-D59)*.75*DELX(J)**2))*H(J,K-1)+
3   W2*(-HMT4*(-D52-D55*DELX(J)-D58*.75*DELX(J)**2)+
4   T(J)*(-D52+D55*DELX(J)-D58*.75*DELX(J)**2))*H(J-1,K-1)+
5   W2*(-HMT4*(D51+D54*DELX(J)+D57*.75*DELX(J)**2)+
6   T(J)*(D51-D54*DELX(J)+D57*.75*DELX(J)**2))*H(J-2,K-1)+
7   W2*(-HMT4*(D53+D56*DELX(J)+D59*.75*DELX(J)**2)+
8   T(J)*(D53-D56*DELX(J)+D59*.75*DELX(J)**2))*SRIVR(K-1)+
9   S(J)*DELX(J)/DELT*H(J,K-1)

FC6(J,K)=A2+W3*(-HMT4*(D53+D56*DELX(J)+
1   D59*.75*DELX(J)**2)+T(J)*(D53-D56*DELX(J)+D59*.75*DELX(J)**2))*
2   SRIVR(K)

```

C

```

INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
RIGHT(INDEX)=-FC6(J,K)
END DO

```

C

```
WRITE(2,*)'K=',K
```

C

```
WRITE(2,*)'RIGHTHAND COLUMN MATRIX'
```

C

```
WRITE(2,197)(RIGHT(J),J=1,JMAX)
```

```

DO I=1,M
HSOL(I)=0.
DO J=1,M
HSOL(I)=HSOL(I)+A(I,J)*RIGHT(J)
END DO
END DO

```

C

```

INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
H(J,K)=HSOL(INDEX)
END DO

```

C

```

SOLUTION FOR K=2
M=JMAX

```

```

DO I=1,M
DO J=1,M
A(I,J)=0.
END DO
END DO
K=2
W1=-1./12.
W2=2./3.
W3=5./12.

```

```

J=1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))

```

```

FC22(J)=W3*(-T(J)*(D43+D46*DELX(J)+D49*.75*DELX(J)**2)+
1HMT2*(D43-D46*DELX(J)+D49*.75*DELX(J)**2))

```

```

FC2(J)=W3*(-T(J)*(-D42-D45*DELX(J)-D48*.75*DELX(J)**2)+HMT2*
1(-D42+D45*DELX(J)-D48*.75*DELX(J)**2))

```

```

FC1(J)=W3*(-T(J)*(-D41+D42-D43-(D44-D45+D46)*DELX(J)+
1(-D47+D48-D49)*.75*DELX(J)**2)+HMT2*(-D41+D42-D43+
2(D44-D45+D46)*DELX(J)+(-D47+D48-D49)*.75*DELX(J)**2))-
3S(J)*DELX(J)/DELT

```

```

DO J=2,JMAX-2

```

```

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

```

```

FC22(J)=W3*(-HMT4*(D3+D6*DELX(J)+D9*.75*DELX(J)**2)+
1HMT2*(D3-D6*DELX(J)+D9*.75*DELX(J)**2))

```

```

FC2(J)=W3*(-HMT4*(-D2-D5*DELX(J)-D8*.75*DELX(J)**2)+
1HMT2*(-D2+D5*DELX(J)-D8*.75*DELX(J)**2))

```

```

FC1(J)=W3*(-HMT4*(-D1+D2-D3-(D4-D5+D6)*DELX(J)+
1(-D7+D8-D9)*.75*DELX(J)**2)+
2HMT2*(-D1+D2-D3+(D4-D5+D6)*DELX(J)+
3(-D7+D8-D9)*.75*DELX(J)**2))-S(J)*DELX(J)/DELT

```

```

FC4(J)=W3*(-HMT4*(D1+D4*DELX(J)+D7*.75*DELX(J)**2)+
1HMT2*(D1-D4*DELX(J)+D7*.75*DELX(j)**2))

```

END DO

J=JMAX-1

HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC2(J)=W3*(-HMT4*(D33+D36*DELX(J)+D39*.75*DELX(J)**2)+
1 HMT2*(D33-D36*DELX(J)+D39*.75*DELX(J)**2))

FC1(J)=W3*(-HMT4*(-D31+D32-D33-(D34-D35+D36)*DELX(J)+
1 (-D37+D38-D39)*.75*DELX(J)**2)+HMT2*(-D31+D32-D33+
2 (D34-D35+D36)*DELX(J)+(-D37+D38-D39)*.75*DELX(J)**2))-
3 S(J)*DELX(J)/DELT

FC4(J)=W3*(-HMT4*(-D32-D35*DELX(J)-D38*.75*DELX(J)**2)+
1 HMT2*(-D32+D35*DELX(J)-D38*.75*DELX(J)**2))

FC44(J)=W3*(-HMT4*(D31+D34*DELX(J)+D37*.75*DELX(J)**2)+
1 HMT2*(D31-D34*DELX(J)+D37*.75*DELX(J)**2))

J=JMAX

HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

FC1(J)=W3*(-HMT4*(-D51+D52-D53-(D54-D55+D56)*DELX(J)+
1 (-D57+D58-D59)*.75*DELX(J)**2)+T(J)*(-D51+D52-D53+
2 (D54-D55+D56)*DELX(J)+(-D57+D58-D59)*.75*DELX(J)**2))-
3 S(J)*DELX(J)/DELT

FC4(J)=w3*(-HMT4*(-D52-D55*DELX(J)-D58*.75*DELX(J)**2)+
1 T(J)*(-D52+D55*DELX(J)-D58*.75*DELX(J)**2))

FC44(J)=w3*(-HMT4*(D51+D54*DELX(J)+D57*.75*DELX(J)**2)+
1 T(J)*(D51-D54*DELX(J)+D57*.75*DELX(J)**2))

I=1

A(I,I)=FC1(I)

A(I,I+1)=FC2(I)

A(I,I+2)=FC22(I)

DO I=2, JMAX-2

A(I,I-1)=FC4(I)

A(I,I)=FC1(I)

A(I,I+1)=FC2(I)

A(I,I+2)=FC22(I)

END DO

I=JMAX-1

A(I,I+1)=FC2(I)

A(I,I)=FC1(I)

A(I,I-1)=FC4(I)

A(I,I-2)=FC44(I)

I=JMAX

A(I,I)=FC1(I)

A(I,I-1)=FC4(I)

A(I,I-2)=FC44(I)

C WRITE(2,*) 'ELEMENT OF THE MATRIX FOR K=2'

```

DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
END DO

C STORING OF THE MATRIX ELEMENT
DO I=1,M
DO J=1,M
AA(I,J)=A(I,J)
END DO
END DO

C CALL MATRIX INVERSE
C WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C DO I=1,M
C WRITE(2,197) ( A(I,J),J=1,M)
C END DO

CALL MATIN (A,M)

C WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO
C WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
KK=0
DO I=1,M
SUM=0
KK=KK+1
DO J=1,M
SUM=SUM+AA(I,J)*A(J,I)
END DO
AAAA(I, KK)=SUM
END DO
DO I=1,M
C WRITE(2,197) (AAAA(I,J),J=1,M)
END DO

C SOLUTION FOR THE 2ND TIME STEP ONWARD
1000 CONTINUE
J=1
A1=W1*(-T(J)*(D43+D46*DELX(J)+D49*.75*DELX(J)**2)+
1 HMT2*(D43-D46*DELX(J)+D49*.75*DELX(J)**2))*H(J+2,K-2)+
2 W1*(-T(J)*(-D42-D45*DELX(J)-D48*.75*DELX(J)**2)+HMT2*
3 (-D42+D45*DELX(J)-D48*.75*DELX(J)**2))*H(J+1,K-2)+
4 W1*(-T(J)*(-D41+D42-D43-(D44-D45+D46)*DELX(J)+
5 (-D47+D48-D49)*.75*DELX(J)**2)+HMT2*(-D41+D42-D43+
6 (D44-D45+D46)*DELX(J)+(-D47+D48-D49)*.75*DELX(J)**2))*H(J,k-2)+
7 W1*(-T(J)*(D41+D44*DELX(J)+D47*.75*DELX(J)**2)+HMT2*(D41-D44*
8 DELX(J)+D47*.75*DELX(J)**2))*SRIVL(K-2)
A2=S(J)*DELX(J)/DELT*H(J,K-1)
A3= W3*(-T(J)*(D41+D44*DELX(J)+D47*.75*DELX(J)**2)+HMT2*
1 (D41-D44*DELX(J)+D47*.75*DELX(J)**2))*SRIVL(K)
A4=W2*(-T(J)*(D43+D46*DELX(J)+D49*.75*DELX(J)**2)+
1 HMT2*(D43-D46*DELX(J)+D49*.75*DELX(J)**2))*H(J+2,K-1)+
2 W2*(-T(J)*(-D42-D45*DELX(J)-D48*.75*DELX(J)**2)+HMT2*
3 (-D42+D45*DELX(J)-D48*.75*DELX(J)**2))*H(J+1,K-1)+
4 W2*(-T(J)*(-D41+D42-D43-(D44-D45+D46)*DELX(J)+
5 (-D47+D48-D49)*.75*DELX(J)**2)+HMT2*(-D41+D42-D43+
6 (D44-D45+D46)*DELX(J)+(-D47+D48-D49)*.75*DELX(J)**2))*H(J,k-1)+
7 W2*(-T(J)*(D41+D44*DELX(J)+D47*.75*DELX(J)**2)+HMT2*(D41-D44*
8 DELX(J)+D47*.75*DELX(J)**2))*SRIVL(K-1)

```

```

FC6(J,K)=A1+A2+A3+A4
DO J=2,JMAX-2
A1=W1*(-HMT4*(D3+D6*DELX(J)+D9*.75*DELX(J)**2)+
1 HMT2*(D3-D6*DELX(J)+D9*.75*DELX(J)**2))*H(J+2,K-2)+
2 W1*(-HMT4*(-D2-D5*DELX(J)-D8*.75*DELX(J)**2)+
3 HMT2*(-D2+D5*DELX(J)-D8*.75*DELX(J)**2))*H(J+1,K-2)+
4 W1*(-HMT4*(-D1+D2-D3-(D4-D5+D6)*DELX(J)+
5 (-D7+D8-D9)*.75*DELX(J)**2)+
6 HMT2*(-D1+D2-D3+(D4-D5+D6)*DELX(J)+
7 (-D7+D8-D9)*.75*DELX(J)**2))*H(J,K-2)+
8 W1*(-HMT4*(D1+D4*DELX(J)+D7*.75*DELX(J)**2)+
9 HMT2*(D1-D4*DELX(J)+D7*.75*DELX(j)**2))*H(J-1,K-2)

A2= S(J)*DELX(J)/DELT*H(J,K-1)

A3=W2*(-HMT4*(D3+D6*DELX(J)+D9*.75*DELX(J)**2)+
1 HMT2*(D3-D6*DELX(J)+D9*.75*DELX(J)**2))*H(J+2,K-1)+
2 W2*(-HMT4*(-D2-D5*DELX(J)-D8*.75*DELX(J)**2)+
3 HMT2*(-D2+D5*DELX(J)-D8*.75*DELX(J)**2))*H(J+1,K-1)+
4 W2*(-HMT4*(-D1+D2-D3-(D4-D5+D6)*DELX(J)+
5 (-D7+D8-D9)*.75*DELX(J)**2)+
6 HMT2*(-D1+D2-D3+(D4-D5+D6)*DELX(J)+
7 (-D7+D8-D9)*.75*DELX(J)**2))*H(J,K-1)+
8 W2*(-HMT4*(D1+D4*DELX(J)+D7*.75*DELX(J)**2)+
9 HMT2*(D1-D4*DELX(J)+D7*.75*DELX(j)**2))*H(J-1,K-1)
FC6(J,K)=A1+A2+A3
END DO
J=JMAX-1
FC6(J,k)=W1*(-HMT4*(D33+D36*DELX(J)+D39*.75*DELX(J)**2)+
1 HMT2*(D33-D36*DELX(J)+D39*.75*DELX(J)**2))*H(J+1,K-2)+
2 W1*(-HMT4*(-D31+D32-D33-(D34-D35+D36)*DELX(J)+
3 (-D37+D38-D39)*.75*DELX(J)**2)+HMT2*(-D31+D32-D33+
4 (D34-D35+D36)*DELX(J)+(-D37+D38-D39)*.75*DELX(J)**2))*H(J,K-2)+
5 W1*(-HMT4*(-D32-D35*DELX(J)-D38*.75*DELX(J)**2)+
6 HMT2*(-D32+D35*DELX(J)-D38*.75*DELX(J)**2))*H(J-1,K-2)+
7 W1*(-HMT4*(D31+D34*DELX(J)+D37*.75*DELX(J)**2)+
8 HMT2*(D31-D34*DELX(J)+D37*.75*DELX(J)**2))*H(J-2,K-2)+
9 S(J)*DELX(J)/DELT*H(J,K-1)
FC6(J,k)=FC6(J,K)+W2*(-HMT4*(D33+D36*DELX(J)+D39*.75*DELX(J)**2)
1 +HMT2*(D33-D36*DELX(J)+D39*.75*DELX(J)**2))*H(J+1,K-1)+
2 W2*(-HMT4*(-D31+D32-D33-(D34-D35+D36)*DELX(J)+
3 (-D37+D38-D39)*.75*DELX(J)**2)+HMT2*(-D31+D32-D33+
4 (D34-D35+D36)*DELX(J)+(-D37+D38-D39)*.75*DELX(J)**2))*H(J,K-1)+
5 W2*(-HMT4*(-D32-D35*DELX(J)-D38*.75*DELX(J)**2)+
6 HMT2*(-D32+D35*DELX(J)-D38*.75*DELX(J)**2))*H(J-1,K-1)+
7 W2*(-HMT4*(D31+D34*DELX(J)+D37*.75*DELX(J)**2)+
8 HMT2*(D31-D34*DELX(J)+D37*.75*DELX(J)**2))*H(J-2,K-1)

J=JMAX

A1=W1*(-HMT4*(-D51+D52-D53-(D54-D55+D56)*DELX(J)+
1 (-D57+D58-D59)*.75*DELX(J)**2)+T(J)*(-D51+D52-D53+
2 (D54-D55+D56)*DELX(J)+(-D57+D58-D59)*.75*DELX(J)**2))*H(J,K-2)+
3 w1*(-HMT4*(-D52-D55*DELX(J)-D58*.75*DELX(J)**2)+
4 T(J)*(-D52+D55*DELX(J)-D58*.75*DELX(J)**2))*H(J-1,K-2)+
5 w1*(-HMT4*(D51+D54*DELX(J)+D57*.75*DELX(J)**2)+
6 T(J)*(D51-D54*DELX(J)+D57*.75*DELX(J)**2))*H(J-2,K-2)+
7 W1*(-HMT4*(D53+D56*DELX(J)+D59*.75*DELX(J)**2)+
8 T(J)*(D53-D56*DELX(J)+D59*.75*DELX(J)**2))*SRIVR(K-2)
A2= S(J)*DELX(J)/DELT*H(J,K-1)

```

```

      A3= W3*(-HMT4*(D53+D56*DELX(J)+
1  D59*.75*DELX(J)**2)+T(J)*(D53-D56*DELX(J)+D59*.75*DELX(J)**2))*
2  SRIVR(K)
      A4=W2*(-HMT4*(-D51+D52-D53-(D54-D55+D56)*DELX(J)+
1  (-D57+D58-D59)*.75*DELX(J)**2)+T(J)*(-D51+D52-D53+
2  (D54-D55+D56)*DELX(J)+(-D57+D58-D59)*.75*DELX(J)**2))*H(J,K-1)+
3  w2*(-HMT4*(-D52-D55*DELX(J)-D58*.75*DELX(J)**2)+
4  T(J)*(-D52+D55*DELX(J)-D58*.75*DELX(J)**2))*H(J-1,K-1)+
5  w2*(-HMT4*(D51+D54*DELX(J)+D57*.75*DELX(J)**2)+
6  T(J)*(D51-D54*DELX(J)+D57*.75*DELX(J)**2))*H(J-2,K-1)+
7  W2*(-HMT4*(D53+D56*DELX(J)+D59*.75*DELX(J)**2)+
8  T(J)*(D53-D56*DELX(J)+D59*.75*DELX(J)**2))*SRIVR(K-1)
      FC6(J,K)=A1+A2+A3+A4
      INDEX=0
      DO J=1,JMAX
      INDEX=INDEX+1
      RIGHT(INDEX)=-FC6(J,K)
      END DO
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'RIGHTHAND COLUMN MATRIX'
C     WRITE(2,*)(RIGHT(J),J=1,JMAX)
      DO I=1,M
      HSOL(I)=0.
      DO J=1,M
      HSOL(I)=HSOL(I)+A(I,J)*RIGHT(J)
      END DO
      END DO
C
      INDEX=0
      DO J=1,JMAX
      INDEX=INDEX+1
      H(J,K)=HSOL(INDEX)
      END DO
      K=K+1
      IF(K.LE.NTIME)GO TO 1000
C     WRITE(2,*)'COMPUTATION OVER'
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'K=',K
C     WRITE(2,*)'HEAD VALUES ARE WRITTEN HERE'
      DO K=1,NTIME
      WRITE(2,*)'TIME STEP=',K
      WRITE(2,222)(H(J,K),J=1,JMAX)
      END DO
222  FORMAT(10F8.3)
      DO K=1,NTIME
      DO J=1,JMAX
      RISE(J,K)=H(J,K)-HEAD1
      END DO
      END DO
      WRITE(2,*)'RISE IN PIEZOMETRIC SURFACE'
      DO K=1,NTIME
      WRITE(2,333)(RISE(J,K),J=1,JMAX)
      END DO
333  format(10f8.4)
      x1=DELX(1)/2.
      beta=t(1)/s(1)
C     WRITE(2,*)'RISE AT FIRST NODE'
      DO N=1,NTIME
      AN=N
      x=x1/((4.*beta*AN*DELT)**0.5)
      call erf(x,erfx)

```



```

trise(1,n)=(BOUNHL-HEAD1)*(1.-erfx)
END DO
x1=DELX(1)+DELX(2)/2.
beta=t(1)/s(1)
DO N=1,NTIME
AN=N
x=x1/((4.*beta*AN*DELT)**0.5)
call erf(x,erfx)
trise(2,n)=(BOUNHL-HEAD1)*(1.-erfx)
END DO
C write(2,333)(trise(1,k),k=1,ntime)
C WRITE(2,*)'RISE AT SECOND NODE'
C write(2,333)(trise(2,k),k=1,ntime)
STOP
END

SUBROUTINE MATIN (AAA,MMM)
DIMENSION AAA(25,25),B(25),C(25)
NN=MMM-1
AAA(1,1)=1./AAA(1,1)
DO 8 M=1,NN
K=M+1
DO 3 I=1,M
B(I)=0.0
DO 3 J=1,M
3 B(I)=B(I)+AAA(I,J)*AAA(J,K)
D=0.0
DO 4 I=1,M
4 D=D+AAA(K,I)*B(I)
D=-D+AAA(K,K)
AAA(K,K)=1./D
DO 5 I=1,M
5 AAA(I,K)=-B(I)*AAA(K,K)
DO 6 J=1,M
C(J)=0.0
DO 6 I=1,M
6 C(J)=C(J)+AAA(K,I)*AAA(I,J)
DO 7 J=1,M
7 AAA(K,J)=-C(J)*AAA(K,K)
DO 8 I=1,M
DO 8 J=1,M
8 AAA(I,J)=AAA(I,J)-B(I)*AAA(K,J)
RETURN
END
SUBROUTINE ERF(X,ERFX)
XINDEX=X
X1=X
IF(X)4,5,5
4 X1=-X
5 CONTINUE
IF(X1-15.)1,2,2
1 CONTINUE
T=1.0/(1.0+0.3275911*X1)
ERFX=1.0-(0.25482959*T-0.28449673*T**2+1.42141374*T**3-1.
1 45315202*T**4+1.06140542*T**5)*EXP(-X1**2)
GO TO3
2 ERFX=1.
3 CONTINUE
IF(XINDEX)6,7,7
6 ERFX=-ERFX

```

```
7 CONTINUE
C WRITE(2,52)X,ERFX
C52 FORMAT(2F10.5)
RETURN
END
```

APPENDIX - 2C

\$DebuG

C IN THIS PROGRAMME THE HEADS AT VARIOUS NODES HAVE BEEN FOUND
C USING ANALYTICAL SOLUTION

```
DIMENSION DIST(10),HEAD(10,10),RISE(10,10)
OPEN(1, FILE= 'SREST3.DAT', STATUS= 'OLD')
OPEN(2, FILE= 'SREST3.OUT', STATUS='UNKNOWN')
READ(1,*)DELX,TRANS,PHI,HEADI,SIGMA0,NTIME,DISTI
```

```
PAI=3.14159265
BETA=TRANS/PHI
```

```
WRITE(2,20)
20 FORMAT(5X,'TRANSMISSIVITY',8X,'STORATIVITY',9X,
1 'HYDRAULIC DIFFUSIVITY')
WRITE(2,21)TRANS,PHI,BETA
21 FORMAT(2X,F10.2,12X,F10.4,13X,F10.1)
WRITE(2,22)
22 FORMAT(2X,'INITIAL HEAD',5X,'SIGMA0')
WRITE(2,23)HEADI,SIGMA0
23 FORMAT(2F12.2)
WRITE(2,24)
24 FORMAT(2X,'TIME ',4X,'DISTI',8X,'DELX')
WRITE(2,25)NTIME,DISTI,DELX
25 FORMAT(I5,2F12.2)
```

```
TIME=NTIME
DIST(1)=DISTI+0.5*DELX
DIST(2)=DISTI+1.5*DELX
DIST(3)=DISTI+2.5*DELX
DIST(4)=DISTI+3.5*DELX
```

```
DO I=1,4
X=SQRT(DIST(I)**2/(4.*BETA*TIME))
CALL ERF(X,ERFX)
RISE(I,NTIME)=SIGMA0*(1.-ERFX)
HEAD(I,NTIME)=HEADI+RISE(I,NTIME)
END DO
```

```
WRITE(2,26)
26 FORMAT(2X,'HEAD AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:')
WRITE(2,*)(HEAD(I,NTIME),I=1,4)
WRITE(2,27)
27 FORMAT(2X,'RISE AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:')
WRITE(2,*)(RISE(I,NTIME),I=1,4)
```

C POLYNOMIAL EXPRESSION : $H = A + B \cdot X + C \cdot X^2 + D \cdot X^3$
C A, B, C, D ARE OBTAINED

```
N=NTIME
I=2
A=HEAD(I,N)
B=(-HEAD(I+2,N)+6.*HEAD(I+1,N)-3.*HEAD(I,N)-2.*HEAD(I-1,N))
1 / (6.*DELX)
C=(HEAD(I+1,N)-2.*HEAD(I,N)+HEAD(I-1,N))/(2.*DELX**2)
D=(HEAD(I+2,N)-3.*HEAD(I+1,N)+3.*HEAD(I,N)-HEAD(I-1,N))
1 / (6.*DELX**3)
WRITE(2,32)
32 FORMAT(8X,'A',16X,'B',16X,'C',16X,'D')
WRITE(2,33)A,B,C,D
33 FORMAT(F14.5,3E17.4)
```

```

WRITE (2,28)

HEADL=A-B*DELX/2.+C*(DELX/2.)**2-D*(DELX/2)**3

X1=DISTI+DELX
X=SQRT(X1**2/(4.*BETA*TIME))
CALL ERF(X,ERFX)
RISEL=SIGMA0*(1.-ERFX)
HEADLC=RISEL+HEADI
WRITE (2,29)X1,HEADLC,HEADL

HEADR=A+B*DELX/2.+C*(DELX/2.)**2+D*(DELX/2)**3
X1=DISTI+2.*DELX
X=SQRT(X1**2/(4.*BETA*TIME))
CALL ERF(X,ERFX)
RISER=SIGMA0*(1.-ERFX)
HEADRC=RISER+HEADI
WRITE (2,28)
28  FORMAT(2X,'DISTANCE FROM STREAM',4X,'ANALYTICAL HEAD'
1     ,4X,'COMPUTED HEAD')
WRITE (2,29)X1,HEADRC,HEADR
29  FORMAT(2XF10.2,11X,F10.4,10X,F10.4)

C  COMPUTATION OF DIFFERENTIAL

CENTDL=(HEAD(2,NTIME)-HEAD(1,NTIME))/DELX
CENTDR=(HEAD(3,NTIME)-HEAD(2,NTIME))/DELX
DIFFL=B+2.*C*(-DELX/2.)+3.*D*(DELX/2.)**2.
DIFFLC=-SIGMA0*2/SQRT(PI)*EXP(-(DELX+DISTI)**2/(4.*BETA*TIME))*
1  1./SQRT(4.*BETA*TIME)
DIFFR=B+2.*C*(DELX/2.)+3.*D*(DELX/2.)**2.
DIFFRC=-SIGMA0*2/SQRT(PI)*EXP(-(DISTI+2.*DELX)**2
1  /(4.*BETA*TIME))/SQRT(4.*BETA*TIME)
WRITE (2,30)
30  FORMAT(2X,'COMPUTED DIFFERENTIAL',2X,'ANALYTICAL DIFFERENTIAL',
1  2X,'CENTRAL DIFFERENTIAL')
WRITE (2,31)DIFFL,DIFFLC,CENTDL
WRITE (2,30)
WRITE (2,31)DIFFR,DIFFRC,CENTDR
31  FORMAT(3E20.4)

WRITE(2,*)'CHECKING THE END DERIVATION'

DIST(1)=0.5*DELX
DIST(2)=1.5*DELX
DIST(3)=2.5*DELX

DO I=1,3
X=SQRT(DIST(I)**2/(4.*BETA*TIME))
CALL ERF(X,ERFX)
RISE(I,NTIME)=SIGMA0*(1.-ERFX)
HEAD(I,NTIME)=HEADI+RISE(I,NTIME)
END DO
WRITE(2,126)
126  FORMAT(2X,'HEAD AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:')
WRITE(2,*) (HEAD(I,NTIME),I=1,3)
WRITE(2,127)
127  FORMAT(2X,'RISE AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:')

```

```

WRITE(2, *) (RISE(I, NTIME), I=1, 3)
N=NTIME
I=1
A=HEAD(I, N)
B=(-3.*HEAD(I+2, N)+20.*HEAD(I+1, N)+15.*HEAD(I, N)-32.*
1 (SIGMA0+HEADI)) / (30.*DELX)
C=(-HEAD(I+2, N)+10.*HEAD(I+1, N)-25.*HEAD(I, N)+16.*(SIGMA0+HEADI)
1 ) / (10.*DELX**2)
D=(6.*HEAD(I+2, N)-20.*HEAD(I+1, N)+30.*HEAD(I, N)-16.*
1 (SIGMA0+HEADI)) / (30.*DELX**3)

WRITE(2, 32)
WRITE(2, 33) A, B, C, D
X=DELX/2.
HEADR1=A+B*X+C*X**2+D*X**3
X1=DELX
X=SQRT(X1**2/(4.*BETA*TIME))
CALL ERF(X, ERFX)
RISER1=SIGMA0*(1.-ERFX)
HEADRC1=RISER1+HEADI
WRITE(2, 29) X1, HEADRC1, HEADR1

X=1.5*DELX
HEADR2=A+B*X+C*X**2+D*X**3
X1=2.0*DELX
X=SQRT(X1**2/(4.*BETA*TIME))
CALL ERF(X, ERFX)
RISER2=SIGMA0*(1.-ERFX)
HEADRC2=RISER2+HEADI
WRITE(2, 28)
WRITE(2, 29) X1, HEADRC2, HEADR2

STOP
END

SUBROUTINE ERF(X, ERFX)
XINDEX=X
X1=X
IF(X) 4, 5, 5
4 X1=-X
5 CONTINUE
IF(X1-15.) 1, 2, 2
1 CONTINUE
T=1.0/(1.0+0.3275911*X1)
ERFX=1.0-(0.25482959*T-0.28449673*T**2+1.42141374*T**3-1.
1 45315202*T**4+1.06140542*T**5)*EXP(-X1**2)
GO TO3
2 ERFX=1.
3 CONTINUE
IF(XINDEX) 6, 7, 7
6 ERFX=-ERFX
7 CONTINUE
C WRITE(2, 52) X, ERFX
C52 FORMAT(2F10.5)
RETURN
END

```

APPENDIX - 2D

```
$Debug
C   FLOW FROM THE RIVER IS COMPUTED NUMERICALLY STARTING FROM THE 1ST
C   TIME STEP
C   IN THIS PROGRAMME THE HEADS AT VARIOUS NODES HAVE BEEN FOUND
C   DIRECTLY USING MATRIX INVERSION METHOD. THIS IS A PROGRAMME
C   IN WHICH HEAD IS OBTAINED USING CRANK NICHOLSON IMPLICIT
C   SCHEME
C   IN THIS THE RESULT HAS BEEN OBTAINED FOR RAMP AND STEP INPUT

      DIMENSION DELX(25),T(25),S(25)

      DIMENSION SRIVR(0:100),H(25,0:100),SRIVL(0:100)

      DIMENSION FC1(25),FC2(25),FC4(25),
1         FC6(25,100),HSOL(25),
2         A(25,25),RIGHT(25)
C   DIMENSION AA(25,25),AAAA(25,25), RISE(25,100)

      OPEN(1, FILE= 'SREST4.DAT', STATUS= 'OLD')
      OPEN(2, FILE= 'SREST4.OUT', STATUS='UNKNOWN')
      READ(1,*) TRANS, PHI, DELXJ, JMAX, HEADL, HEADR, HEADI
      READ(1,*) DELT, NTIME
      READ(1,*) W11, W22, W33
      READ(1,*) W111, W222, W333
      WRITE(2,*) 'THE RESULTS ARE FOR A STEP INPUT'
      WRITE(2,*) 'THE INFLOW AT X=0 IS OBTAINED NUMERICALLY'
      WRITE(2,41)
41  FORMAT(7X, 'DELT')
      WRITE(2,42) DELT
42  FORMAT(F10.3)

      WRITE(2,40)
40  FORMAT(2X, 'TRANSMISSIVITY', 3X, 'STORATIVITY', 5X, 'DELXJ', 4X,
1     'INITIALHEAD', 3X, 'HEADL ', 6X, 'HEADR')
      WRITE(2,44) TRANS, PHI, DELXJ, HEADI, HEADL, HEADR
44  FORMAT(2X, F8.1, 2X, F12.3, 2X, 2F13.1, 2X, 2F10.2)

C   READ(1,*) (DELX(J), J=1, JMAX)
C   WRITE(2,40)
C40  FORMAT(4X, 'J', 8X, 'DELX(J)')
C   DO J=1, JMAX
C   WRITE(2,51) J, DELX(J)
C   END DO
C51  FORMAT(I5, 5X, F8.2)
C
      DO J=1, JMAX
      DELX(J)=DELXJ
      END DO

      DO J=1, JMAX
      H(J,0)=HEADI
      END DO

      SRIVR(0)=HEADR
      SRIVL(0)=HEADL

C   SRIVL(0)=HEADI
C   IF SRIVL(0)=HEADI, IT CORRESPONDS TO RAMP INPUT
C   IF SRIVL(0)=HEADL, IT CORRESPONDS TO STEP INPUT
```

```

C
DO K=1,NTIME
C RIVER STAGE FOR RAMP INPUT
C AK=K
C SRIVL(K)=(HEADL-HEADI)*AK*DELT+HEADI
C SRIVL(K)=HEADL
C SRIVR(K)=HEADR
C END DO
C WRITE(2,*)'BOUNDARY CONDITION AT X=0; SRIVL(K)'
C WRITE(2,55)(SRIVL(K),K=1,NTIME)
55 FORMAT(5F10.2)
C
C
C TRANSMISSIVITY VALUES ARE BEING READ
C
C WRITE(2,*)'TRANSMISSIVITY VALUES'
C READ(1,*) (T(J),J=1,JMAX)
C WRITE(2,54)(T(J),J=1,JMAX)
C54 FORMAT(6F10.2)
C DO J=1,JMAX
C T(J)=TRANS
C END DO
C
C STORAGE COEFFICIENT VALUES ARE BEING READ
C
C RTRIVL=2.*T(1)/DELX(1)
C RTRIVR=2.*T(JMAX)/DELX(JMAX)
C RTRIVR=0.
C RTRIVL=0.
C WRITE(2,*)'STORATIVITY VALUES'
C READ(1,*) (S(J),J=1,JMAX)
C WRITE(2,54)(S(J),J=1,JMAX)
C DO J=1,JMAX
C S(J)=PHI
C END DO
C
C COEFFICIENTS OF HEADS AT INTERIOR NODES
C IN FINITE DIFFERENCE EQUATION
C
C K=1
C W1=W11
C W2=W22+W11
C W3=W33
C WRITE(2,*)'W2=',W2
C WRITE(2,*)'W3=',W3
C J=1
C HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
C TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
C TERM4=RTRIVL/DELX(J)*W3
C FC2(J)=HMT2*TERML2*W3
C FC4(J)=0.
C
C FLOW FROM RIVER HAS BEEN CONSIDERED NUMWRICALLY
C
C FC1(J)=-S(J)/DELT-(FC2(J)+TERM4)
C
C DO J=2,JMAX-1
C
C HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
C HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))

```

```

TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))

FC2(J)=HMT2*TERML2*W3
FC4(J)=HMT4*TERML4*W3

FC1(J)=-S(J)/DELT-(FC2(J)+FC4(J))
END DO

J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))

TERM2=RTRIVR/DELX(J)*W3
FC2(J)=0.
FC4(J)=HMT4*TERML4*W3
FC1(J)=-S(J)/DELT-(TERM2+FC4(J))
C
C GENERATION OF MATRIX COEFFICIENTS
M=JMAX
DO I=1,M
DO J=1,M
A(I,J)=0.
END DO
END DO
C
C ELEMENT OF THE SPARCE BANDED MATRIX
C
DO I=1,M
INDEX=0

DO J1=1,JMAX
INDEX=INDEX+1
IF(I.EQ.INDEX) GO TO 1
GO TO 6
1 CONTINUE
A(I,INDEX)=FC1(J1)
IF(J1.EQ.JMAX) GO TO 2
A(I,INDEX+1)=FC2(J1)
2 CONTINUE
IF(J1.EQ.1) GO TO 3
A(I,INDEX-1)=FC4(J1)
3 CONTINUE
6 CONTINUE
END DO
END DO

C WRITE(2,*)'ELEMENT OF THE MATRIX'
C DO I=1,M
C WRITE(2,197)(A(I,J),J=1,M)
C END DO

C STORING OF THE MATRIX ELEMENT
C
C DO I=1,M
C DO J=1,M
C AA(I,J)=A(I,J)
C END DO
C END DO
C
C
C

```



```

C      CALL MATRIX INVERSE
C
C      WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C      DO I=1,M
C      WRITE(2,197) ( A(I,J),J=1,M)
C      END DO

197   FORMAT(10F7.3)
C
C
C      CALL MATIN (A,M)

C      WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C      DO I=1,M
C      WRITE(2,197) (A(I,J),J=1,M)
C      END DO

C      WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
C      KK=0
C      DO I=1,M
C      SUM=0
C      KK=KK+1
C      DO J=1,M
C      SUM=SUM+AA(I,J)*A(J,I)
C      END DO
C      AAAA(I, KK)=SUM
C      END DO
C      DO I=1,M
C      WRITE(2,197) (AAAA(I,J),J=1,M)
C      END DO
C
C      SOLUTION FOR THE FIRST TIME STEP
C
C
C      FC6(1,K) FOR  NODES NEAR LEFT BOUNDARY
C
C      J=1

C      FLOW FROM STREAM HAS BEEN CONSIDERED NUMERICALLY

      FC6(J,K)=S(J)/DELT*H(J,K-1)
1     +W3*RTRIVL/DELX(J)*SRIVL(K)
2     +W2*RTRIVL/DELX(J)*(SRIVL(K-1)-H(J,K-1))
3     +W2/W3*FC2(J)*(H(J+1,K-1)-H(J,K-1))

C
C
C      FC6(J,K)  AT  INTERIOR NODES
C
      DO J=2,JMAX-1
      FC6(J,K)=S(J)/DELT*H(J,K-1)
1     +W2/W3*FC2(J)*(H(J+1,K-1)-H(J,K-1))
2     +W2/W3*FC4(J)*(H(J-1,K-1)-H(J,K-1))

      END DO

C
C      FC6(JMAX,K) FOR  NODES NEAR RIGHT BOUNDARY

```

C

J=JMAX

```
FC6(J,K)=S(J)/DELT*H(J,K-1)
1 +W3*RTRIVR/DELX(J)*SRIVR(K)
2 +W2*RTRIVR/DELX(J)*(SRIVR(K-1)-H(J,K-1))
3 +W2/W3*FC4(J)*(H(J-1,K-1)-H(J,K-1))
```

C

```
INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
RIGHT(INDEX)=-FC6(J,K)
END DO
```

C

```
WRITE(2,*)'TIME STEP K=',K
```

C

```
WRITE(2,*)'RIGHTHAND COLUMN MATRIX'
```

C

```
WRITE(2,*)(RIGHT(J),J=1,JMAX)
```

```
DO I=1,M
```

```
HSOL(I)=0.
```

```
DO J=1,M
```

```
HSOL(I)=HSOL(I)+A(I,J)*RIGHT(J)
```

```
END DO
```

```
END DO
```

C

```
INDEX=0
DO J=1,JMAX
INDEX=INDEX+1
H(J,K)=HSOL(INDEX)
END DO
```

C

```
SOLUTION FOR FIRST TIME IS OVER
```

```
W1=W111
```

```
W2=W222
```

```
W3=W333
```

```
WRITE(2,*)'W1=',W1
```

```
WRITE(2,*)'W2=',W2
```

```
WRITE(2,*)'W3=',W3
```

```
J=1
```

```
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
```

```
TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
```

```
FC2(J)=HMT2*TERML2*W3
```

```
TERM4=RTRIVL/DELX(J)*W3
```

```
FC4(J)=0.
```

```
FC1(J)=-S(J)/DELT-(FC2(J)+TERM4)
```

```
DO J=2,JMAX-1
```

```
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
```

```
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
```

```
TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
```

```
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))
```

```
FC2(J)=HMT2*TERML2*W3
```

```
FC4(J)=HMT4*TERML4*W3
```

```
FC1(J)=-S(J)/DELT-(FC2(J)+FC4(J))
```

```
END DO
```

```
J=JMAX
```

```
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
```

```
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))
```

```
TERM2=RTRIVR/DELX(J)*W3
```

```
FC2(J)=0.
```

```
FC4(J)=HMT4*TERML4*W3
```

```
FC1(J)=-S(J)/DELT-(FC4(J)+TERM2)
```

C

C

```
GENERATION OF MATRIX COEFFICIENTS
```

```

M=JMAX
DO I=1,M
DO J=1,M
A(I,J)=0.
END DO
END DO

C
C ELEMENT OF THE SPARCE BANDED MATRIX
C
DO I=1,M
INDEX=0
DO J1=1,JMAX
INDEX=INDEX+1
IF(I.EQ.INDEX) GO TO 199
GO TO 699
199 CONTINUE
A(I,INDEX)=FC1(J1)
IF(J1.EQ.JMAX) GO TO 299
A(I,INDEX+1)=FC2(J1)
299 CONTINUE
IF(J1.EQ.1) GO TO 399
A(I,INDEX-1)=FC4(J1)
399 CONTINUE
699 CONTINUE
END DO
END DO

C WRITE(2,*) 'ELEMENT OF THE MATRIX'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO
C
C STORING OF THE MATRIX ELEMENT
C
C DO I=1,M
C DO J=1,M
C AA(I,J)=A(I,J)
C END DO
C END DO
C
C CALL MATRIX INVERSE
C
C WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C DO I=1,M
C WRITE(2,197) ( A(I,J),J=1,M)
C END DO
C
C CALL MATIN (A,M)
C WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO
C
C WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
C KK=0
C DO I=1,M
C SUM=0
C KK=KK+1
C DO J=1,M
C SUM=SUM+AA(I,J)*A(J,I)
C END DO

```

```

C      AAAAA(I, KK)=SUM
C      END DO
C      DO I=1, M
C      WRITE(2, 197) (AAAA(I, J), J=1, M)
C      END DO
C
C      K=2
1000  CONTINUE
C      SOLUTION FOR THE 2ND TIME STEP ONWARD
C
C      FC6(1, K) FOR  NODES NEAR LEFT BOUNDARY
C
C      J=1
C      FC6(J, K)=S(J)/DELT*H(J, K-1)
1      +W3*RTRIVL/DELX(J)*SRIVL(K)
2      +W2*RTRIVL/DELX(J)*(SRIVL(K-1)-H(J, K-1))
3      +(W2/W3)*FC2(J)*(H(J+1, K-1)-H(J, K-1))
4      +W1*RTRIVL/DELX(J)*(SRIVL(K-2)-H(J, K-2))
5      +(W1/W3)*FC2(J)*(H(J+1, K-2)-H(J, K-2))
C
C
C      FC6(J, K)  AT  INTERIOR NODES
C
C      DO J=2, JMAX-1
C      FC6(J, K)=S(J)*H(J, K-1)/DELT
1      +W2/W3*FC2(J)*(H(J+1, K-1)-H(J, K-1))
2      +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
3      +W1/W3*FC2(J)*(H(J+1, K-2)-H(J, K-2))
4      +W1/W3*FC4(J)*(H(J-1, K-2)-H(J, K-2))
C      END DO
C
C      FC6(JMAX, K) FOR  NODES NEAR RIGHT BOUNDARY
C
C      J=JMAX
C
C      FC6(J, K)=S(J)/DELT*H(J, K-1)
1      +W3*RTRIVR/DELX(J)*SRIVR(K)
2      +W2*RTRIVR/DELX(J)*(SRIVR(K-1)-H(J, K-1))
3      +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
4      +W1*RTRIVR/DELX(J)*(SRIVR(K-2)-H(J, K-2))
5      +W1/W3*FC4(J)*(H(J-1, K-2)-H(J, K-2))
C
C      INDEX=0
C      DO J=1, JMAX
C      INDEX=INDEX+1
C      RIGHT(INDEX)=-FC6(J, K)
C      END DO
C
C      WRITE(2, *) 'TIME STEP K=', K
C      WRITE(2, *) 'RIGHTHAND COLUMN MATRIX'
C      WRITE(2, *) (RIGHT(J), J=1, JMAX)
C
C      DO I=1, M
C      HSOL(I)=0.
C      DO J=1, M
C      HSOL(I)=HSOL(I)+A(I, J)*RIGHT(J)

```

```

END DO
END DO

C
INDEX=0
DO J=1, JMAX
INDEX=INDEX+1
H(J, K)=HSOL(INDEX)
END DO
K=K+1
IF(K.LE.NTIME) GO TO 1000
WRITE(2, *) 'HEAD (metre) AT DIFFERENT TIMES AND NODES '
DO K=1, NTIME
C
WRITE(2, *) 'K=', K
WRITE(2, 222) (H(J, K), J=1, JMAX)
222
FORMAT(8F8.2)
END DO
STOP
END

SUBROUTINE MATIN (AAA, MMM)
DIMENSION AAA(25, 25), B(25), C(25)
NN=MMM-1
AAA(1, 1)=1./AAA(1, 1)
DO 8 M=1, NN
K=M+1
DO 3 I=1, M
B(I)=0.0
DO 3 J=1, M
3
B(I)=B(I)+AAA(I, J)*AAA(J, K)
D=0.0
DO 4 I=1, M
4
D=D+AAA(K, I)*B(I)
D=-D+AAA(K, K)
AAA(K, K)=1./D
DO 5 I=1, M
5
AAA(I, K)=-B(I)*AAA(K, K)
DO 6 J=1, M
C(J)=0.0
DO 6 I=1, M
6
C(J)=C(J)+AAA(K, I)*AAA(I, J)
DO 7 J=1, M
7
AAA(K, J)=-C(J)*AAA(K, K)
DO 8 I=1, M
DO 8 J=1, M
8
AAA(I, J)=AAA(I, J)-B(I)*AAA(K, J)
RETURN
END

SUBROUTINE ERF(X, ERFX)
XINDEX=X
X1=X
IF(X) 4, 5, 5
4
X1=-X
5
CONTINUE
IF(X1-15.) 1, 2, 2
1
CONTINUE
T=1.0/(1.0+0.3275911*X1)
ERFX=1.0-(0.25482959*T-0.28449673*T**2+1.42141374*T**3-1.
1 45315202*T**4+1.06140542*T**5)*EXP(-X1**2)
GO TO 3
2
ERFX=1.

```

```
3      CONTINUE
      IF (XINDEX) 6,7,7
6      ERFX=-ERFX
7      CONTINUE
C      WRITE (2,52) X,ERFX
C52    FORMAT (2F10.5)
      RETURN
      END
```

APPENDIX - 2E

```

$Debug
C   FLOW FROM RIVER HAS BEEN CONSIDERED ANALYTICALLY FOR THE 1ST
C   TIME STEP
C   IN THIS PROGRAMME THE HEADS AT VARIOUS NODES HAVE BEEN FOUND
C   DIRECTLY USING MATRIX INVERSION METHOD. THIS IS A PROGRAMME
C   IN WHICH HEAD IS OBTAINED USING CRANK NICHOLSON IMPLICIT
C   SCHEME
C   IN THIS THE RESULT HAS BEEN OBTAINED FOR RAMP AND STEP INPUT
DIMENSION DELX(25),T(25),S(25)
DIMENSION SRIVR(0:100),H(25,0:100),SRIVL(0:100)

DIMENSION FC1(25),FC2(25),FC4(25),
1         FC6(25,100),HSOL(25),
2         A(25,25),RIGHT(25)
C   DIMENSION AA(25,25),AAAA(25,25),RISE(25,100)

OPEN(1, FILE= 'SREST5.DAT', STATUS= 'OLD')
OPEN(2, FILE= 'SREST5.OUT', STATUS='UNKNOWN')
READ(1, *) TRANS, PHI, DELXJ, JMAX, HEADL, HEADR, HEADI
READ(1, *) DELT, NTIME
READ(1, *) W11, W22, W33
READ(1, *) W111, W222, W333
WRITE(2, 41)
41  FORMAT(7X, 'DELT')
WRITE(2, 42) DELT
42  FORMAT(F10.3)

WRITE(2, 40)
40  FORMAT(2X, 'TRANSMISSIVITY', 3X, 'STORATIVITY', 5X, 'DELXJ', 4X,
1     'INITIALHEAD', 3X, 'HEADL ', 6X, 'HEADR')
WRITE(2, 44) TRANS, PHI, DELXJ, HEADI, HEADL, HEADR
44  FORMAT(2X, F8.1, 2X, F12.3, 2X, 2F13.1, 2X, 2F10.2)

C   READ(1, *) (DELX(J), J=1, JMAX)
C   WRITE(2, 40)
C40  FORMAT(4X, 'J', 8X, 'DELX(J)')
C   DO J=1, JMAX
C   WRITE(2, 51) J, DELX(J)
C   END DO
C51  FORMAT(I5, 5X, F8.2)
C
DO J=1, JMAX
DELX(J)=DELXJ
END DO

DO J=1, JMAX
H(J, 0)=HEADI
END DO

SRIVR(0)=HEADR
SRIVL(0)=HEADL
C   SRIVL(0)=HEADI
C   IF SRIVL(0)=HEADI, IT CORRESPONDS TO RAMP INPUT
C   IF SRIVL(0)=HEADL, IT CORRESPONDS TO STEP INPUT
C
DO K=1, NTIME
C
C   AK=K
C   SRIVL(K)=(HEADL-HEADI)*AK*DELT+HEADI
C   SRIVL(K)=HEADL

```

```

SRIVR(K)=HEADR
END DO

WRITE(2,*) 'SRIVL(K) '
WRITE(2,55) (SRIVL(K),K=1,NTIME)
55  FORMAT(5F10.2)
C
C
C   TRANSMISSIVITY VALUES ARE BEING READ
C
C   WRITE(2,*) 'TRANSMISSIVITY VALUES '
C   READ(1,*) (T(J),J=1,JMAX)
C   WRITE(2,54) (T(J),J=1,JMAX)
C54  FORMAT(6F10.2)
      DO J=1,JMAX
      T(J)=TRANS
      END DO

C
C   STORAGE COEFFICIENT VALUES ARE BEING READ
C
C   RTRIVL=2.*T(1)/DELX(1)
      RTRIVR=2.*T(JMAX)/DELX(JMAX)

C
C   RTRIVR=0.
C   RTRIVL=0.
C   WRITE(2,*) 'STORATIVITY VALUES '
C   READ(1,*) (S(J),J=1,JMAX)
C   WRITE(2,54) (S(J),J=1,JMAX)
      DO J=1,JMAX
      S(J)=PHI
      END DO

C
C   COEFFICIENTS OF HEADS AT INTERIOR NODES
C   IN FINITE DIFFERENCE EQUATION
C
      K=1
      W1=W11
      W2=W22+W11
      W3=W33
      WRITE(2,*) 'W3=',W3
      WRITE(2,*) 'W2=',W2
      J=1
      HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
      TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
      FC2(J)=HMT2*TERML2*W3
      FC4(J)=0.
      FC1(J)=-S(J)/DELT-FC2(J)
      DO J=2,JMAX-1
      HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
      HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
      TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
      TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))
      FC2(J)=HMT2*TERML2*W3
      FC4(J)=HMT4*TERML4*W3
      FC1(J)=-S(J)/DELT-(FC2(J)+FC4(J))
      END DO
      J=JMAX
      HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
      TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))

```



```

TERM2=RTRIVR/DELX(J)*W3
FC2(J)=0.
FC4(J)=HMT4*TERML4*W3
FC1(J)=-S(J)/DELT-(TERM2+FC4(J))
C
C GENERATION OF MATRIX COEFFICIENTS
M=JMAX
DO I=1,M
DO J=1,M
A(I,J)=0.
END DO
END DO

C
C ELEMENT OF THE SPARCE BANDED MATRIX
C
DO I=1,M
INDEX=0
DO J1=1,JMAX
INDEX=INDEX+1
IF(I.EQ.INDEX) GO TO 1
GO TO 6
1 CONTINUE
A(I,INDEX)=FC1(J1)
IF(J1.EQ.JMAX) GO TO 2
A(I,INDEX+1)=FC2(J1)
2 CONTINUE
IF(J1.EQ.1) GO TO 3
A(I,INDEX-1)=FC4(J1)
3 CONTINUE
6 CONTINUE
END DO
END DO

C WRITE(2,*) 'ELEMENT OF THE MATRIX'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO
C STORING OF THE MATRIX ELEMENT
C
C DO I=1,M
C DO J=1,M
C AA(I,J)=A(I,J)
C END DO
C END DO
C
C
C CALL MATRIX INVERSE
C
C WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C DO I=1,M
C WRITE(2,197) ( A(I,J),J=1,M)
C END DO
197 FORMAT(10F7.3)
C
C
C CALL MATIN (A,M)
C WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1,M
C WRITE(2,197) (A(I,J),J=1,M)
C END DO

```

```

C      WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
C      KK=0
C      DO I=1,M
C      SUM=0
C      KK=KK+1
C      DO J=1,M
C      SUM=SUM+AA(I,J)*A(J,I)
C      END DO
C      AAAA(I, KK)=SUM
C      END DO
C      DO I=1,M
C      WRITE(2,197) (AAAA(I, J), J=1, M)
C      END DO
C
C      SOLUTION FOR THE FIRST TIME STEP
C
C
C      FC6(1,K) FOR  NODES NEAR LEFT BOUNDARY
C
C      PAI=3.14159265
C      J=1
C      FLOW FROM STREAM HAS BEEN CONSIDERED ANALYTICALLY
C      RISE=HEADL-HEADI
C      FC6(J, K)=S(J)/DELT*H(J, K-1)+2.*SQRT(T(1)*S(1)/PAI)*RISE/
1      (SQRT(DELT)*DELX(1))+W2/W3*FC2(J)*(H(J+1, K-1)-H(J, K-1))
C
C
C      FC6(J, K) AT  INTERIOR NODES
C
C      DO J=2, JMAX-1
C      FC6(J, K)=S(J)/DELT*H(J, K-1)
1      +W2/W3*FC2(J)*(H(J+1, K-1)-H(J, K-1))
2      +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
C
C      END DO
C
C      FC6(JMAX, K) FOR  NODES NEAR RIGHT BOUNDARY
C
C      J=JMAX
C      FC6(J, K)=S(J)/DELT*H(J, K-1)
1      +W3*RTRIVR/DELX(J)*SRIVR(K)
2      +W2*RTRIVR/DELX(J)*(SRIVR(K-1)-H(J, K-1))
3      +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
C
C      INDEX=0
C      DO J=1, JMAX
C      INDEX=INDEX+1
C      RIGHT(INDEX)=-FC6(J, K)
C      END DO
C      WRITE(2,*) 'TIME STEP K=', K
C      WRITE(2,*) 'RIGHTHAND COLUMN MATRIX'
C      WRITE(2,*) (RIGHT(J), J=1, JMAX)
C      DO I=1, M
C      HSOL(I)=0.
C      DO J=1, M
C      HSOL(I)=HSOL(I)+A(I, J)*RIGHT(J)
C      END DO

```

```

END DO
C
INDEX=0
DO J=1, JMAX
INDEX=INDEX+1
H(J, K)=HSOL(INDEX)
END DO
C
SOLUTION FOR FIRST TIME IS OVER
W1=W111
W2=W222
W3=W333
WRITE(2, *) 'W1=', W1
WRITE(2, *) 'W2=', W2
WRITE(2, *) 'W3=', W3
J=1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
FC2(J)=HMT2*TERML2*W3
TERM4=RTRIVL/DELX(J)*W3
FC4(J)=0.
FC1(J)=-S(J)/DELT-(FC2(J)+TERM4)
DO J=2, JMAX-1
HMT2=(DELX(J)+DELX(J+1))/(DELX(J)/T(J)+DELX(J+1)/T(J+1))
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
TERML2=2./((DELX(J)+DELX(J+1))*DELX(J))
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))
FC2(J)=HMT2*TERML2*W3
FC4(J)=HMT4*TERML4*W3
FC1(J)=-S(J)/DELT-(FC2(J)+FC4(J))
END DO
J=JMAX
HMT4=(DELX(J)+DELX(J-1))/(DELX(J)/T(J)+DELX(J-1)/T(J-1))
TERML4=2./((DELX(J)+DELX(J-1))*DELX(J))
TERM2=RTRIVR/DELX(J)*W3
FC2(J)=0.
FC4(J)=HMT4*TERML4*W3
FC1(J)=-S(J)/DELT-(FC4(J)+TERM2)
C
C
GENERATION OF MATRIX COEFFICIENTS
M=JMAX
DO I=1, M
DO J=1, M
A(I, J)=0.
END DO
END DO
C
C
ELEMENT OF THE SPARCE BANDED MATRIX
C
DO I=1, M
INDEX=0

DO J1=1, JMAX
INDEX=INDEX+1
IF(I.EQ.INDEX) GO TO 199
GO TO 699
199 CONTINUE
A(I, INDEX)=FC1(J1)
IF(J1.EQ.JMAX) GO TO 299
A(I, INDEX+1)=FC2(J1)
299 CONTINUE
IF(J1.EQ.1) GO TO 399

```

```

A(I, INDEX-1)=FC4(J1)
399 CONTINUE
699 CONTINUE
END DO
END DO
C WRITE(2,*) 'ELEMENT OF THE MATRIX'
C DO I=1,M
C WRITE(2,197) (A(I,J), J=1,M)
C END DO
C
C STORING OF THE MATRIX ELEMENT
C
C DO I=1,M
C DO J=1,M
C AA(I,J)=A(I,J)
C END DO
C END DO
C
C CALL MATRIX INVERSE
C
C WRITE(2,*) 'WRITING THE MATRIX ELEMENT BEFORE INVERSION'
C DO I=1,M
C WRITE(2,197) ( A(I,J), J=1,M)
C END DO
C
C CALL MATIN (A,M)
C
C WRITE(2,*) 'MATRIX ELEMENT AFTER INVERSION'
C DO I=1,M
C WRITE(2,197) (A(I,J), J=1,M)
C END DO
C WRITE(2,*) 'CHECKING THE MATRIX INVERSION'
C KK=0
C DO I=1,M
C SUM=0
C KK=KK+1
C DO J=1,M
C SUM=SUM+AA(I,J)*A(J,I)
C END DO
C AAAA(I, KK)=SUM
C END DO
C DO I=1,M
C WRITE(2,197) (AAAA(I,J), J=1,M)
C END DO
C
C K=2
1000 CONTINUE
C SOLUTION FOR THE 2ND TIME STEP ONWARD
C FC6(1,K) FOR NODES NEAR LEFT BOUNDARY
C
C J=1
FC6(J,K)=S(J)/DELT*H(J,K-1)
1 +W3*RTRIVL/DELX(J)*SRIVL(K)
2 +W2*RTRIVL/DELX(J)*(SRIVL(K-1)-H(J,K-1))
3 +(W2/W3)*FC2(J)*(H(J+1,K-1)-H(J,K-1))
4 +W1*RTRIVL/DELX(J)*(SRIVL(K-2)-H(J,K-2))
5 +(W1/W3)*FC2(J)*(H(J+1,K-2)-H(J,K-2))
C
C
C FC6(J,K) AT INTERIOR NODES

```

```

C
DO J=2, JMAX-1
FC6(J, K)=S(J)*H(J, K-1)/DELT
1 +W2/W3*FC2(J)*(H(J+1, K-1)-H(J, K-1))
2 +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
3 +W1/W3*FC2(J)*(H(J+1, K-2)-H(J, K-2))
4 +W1/W3*FC4(J)*(H(J-1, K-2)-H(J, K-2))
END DO

C
C FC6(JMAX, K) FOR NODES NEAR RIGHT BOUNDARY
C
J=JMAX
FC6(J, K)=S(J)/DELT*H(J, K-1)
1 +W3*RTRIVR/DELX(J)*SRIVR(K)
2 +W2*RTRIVR/DELX(J)*(SRIVR(K-1)-H(J, K-1))
3 +W2/W3*FC4(J)*(H(J-1, K-1)-H(J, K-1))
4 +W1*RTRIVR/DELX(J)*(SRIVR(K-2)-H(J, K-2))
5 +W1/W3*FC4(J)*(H(J-1, K-2)-H(J, K-2))

C
INDEX=0
DO J=1, JMAX
INDEX=INDEX+1
RIGHT(INDEX)=-FC6(J, K)
END DO

C
WRITE(2, *) 'TIME STEP K=', K
C
WRITE(2, *) 'RIGHTHAND COLUMN MATRIX'
C
WRITE(2, *) (RIGHT(J), J=1, JMAX)
DO I=1, M
HSOL(I)=0.
DO J=1, M
HSOL(I)=HSOL(I)+A(I, J)*RIGHT(J)
END DO
END DO

C
INDEX=0
DO J=1, JMAX
INDEX=INDEX+1
H(J, K)=HSOL(INDEX)
END DO
K=K+1 IF(K.LE.NTIME) GO TO 1000

WRITE(2, *) 'HEAD (metre) AT DIFFERENT TIMES AND NODES '
DO K=1, NTIME
C
WRITE(2, *) 'K=', K
WRITE(2, 222) (H(J, K), J=1, JMAX)
222 FORMAT(8F8.2)
END DO
STOP
END
SUBROUTINE MATIN (AAA, MMM)
DIMENSION AAA(25, 25), B(25), C(25)
NN=MMM-1
AAA(1, 1)=1./AAA(1, 1)
DO 8 M=1, NN
K=M+1
DO 3 I=1, M
B(I)=0.0
DO 3 J=1, M
3 B(I)=B(I)+AAA(I, J)*AAA(J, K)
D=0.0

```

```

DO 4 I=1,M
4 D=D+AAA(K,I)*B(I)
D=-D+AAA(K,K)
AAA(K,K)=1./D
DO 5 I=1,M
5 AAA(I,K)=-B(I)*AAA(K,K)
DO 6 J=1,M
C(J)=0.0
DO 6 I=1,M
6 C(J)=C(J)+AAA(K,I)*AAA(I,J)
DO 7 J=1,M
7 AAA(K,J)=-C(J)*AAA(K,K)
DO 8 I=1,M
DO 8 J=1,M
8 AAA(I,J)=AAA(I,J)-B(I)*AAA(K,J)
RETURN
END

```

```

SUBROUTINE ERF(X,ERFX)
XINDEX=X
X1=X
IF(X)4,5,5
4 X1=-X
5 CONTINUE
IF(X1-15.)1,2,2
1 CONTINUE
T=1.0/(1.0+0.3275911*X1)
ERFX=1.0-(0.25482959*T-0.28449673*T**2+1.42141374*T**3-1.
1 45315202*T**4+1.06140542*T**5)*EXP(-X1**2)
GO TO3
2 ERFX=1.
3 CONTINUE
IF(XINDEX)6,7,7
6 ERFX=-ERFX
7 CONTINUE
C WRITE(2,52)X,ERFX
C52 FORMAT(2F10.5)
RETURN
END

```

APPENDIX - 3 DATA INPUT

APPENDIX - 3A

8	10.	
100.	0.02	
.1	10	
15.	10.	10.

APPENDIX - 3B

8	10.						
0.01	10						
15.	10.	10.					
100.	50.	50.	50.	50.	50.	50.	100.
0.02	0.01	0.01	0.01	0.01	0.01	0.01	0.02
10.	20.	20.	20.	20.	20.	20.	10.

APPENDIX - 3C

10.	300.	.02	10.	5.	1	0.
50.	10.	0.001	50.	5.0	1	0.

APPENDIX - 3D

100.	0.02	10.	8	15.	10.	10.
.05	10					
0.	0.	1.				
0.	0.	1.				

APPENDIX - 3E

100.	0.02	10.	8	15.	10.	10.
.05	10					
0.	0.	1.				
0.	0.	1.				

APPENDIX - 4 OUTPUT DATA

OUTPUT DATA OF PROGRAMME-2A (CASE 1)

TRANS= 100.000000

STORC= 2.000000E-02

JMAX DELTAX

8 10.00

NTIME DELT

10 .10

BHL BHR HI

15.00 10.00 10.00

THE RESULTS ARE FOR A STEP INPUT

FIRST TIME STEP

W2= 0.000000E+00

W3= 1.000000

13.999	12.562	11.637	11.039	10.649	10.388	10.206	10.064
14.849	13.987	12.988	12.114	11.423	10.897	10.491	10.156
14.269	13.623	13.123	12.553	11.942	11.344	10.783	10.257
15.106	14.185	13.274	12.571	11.979	11.417	10.855	10.286
14.066	13.841	13.466	12.835	12.145	11.488	10.875	10.289
15.528	14.189	13.259	12.681	12.145	11.562	10.944	10.316
13.474	13.955	13.636	12.886	12.155	11.510	10.904	10.302
16.438	14.080	13.144	12.731	12.223	11.599	10.950	10.314
12.124	14.164	13.811	12.853	12.111	11.516	10.930	10.315
18.462	13.750	12.952	12.813	12.292	11.599	10.926	10.302

RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY

3.9993	2.5618	1.6366	1.0388	.6487	.3884	.2057	.0642
4.8494	3.9865	2.9877	2.1137	1.4233	.8972	.4909	.1558
4.2692	3.6233	3.1229	2.5532	1.9423	1.3436	.7828	.2567
5.1060	4.1850	3.2737	2.5707	1.9787	1.4174	.8549	.2858
4.0661	3.8415	3.4657	2.8349	2.1450	1.4882	.8749	.2887
5.5283	4.1886	3.2593	2.6806	2.1447	1.5618	.9443	.3156
3.4741	3.9546	3.6359	2.8860	2.1546	1.5096	.9036	.3016
6.4382	4.0804	3.1438	2.7309	2.2227	1.5994	.9499	.3141
2.1241	4.1642	3.8107	2.8532	2.1106	1.5158	.9304	.3146
8.4623	3.7497	2.9519	2.8132	2.2924	1.5995	.9262	.3023

OUTPUT DATA OF PROGRAMME-2A (CASE2)

TRANS= 100.000000
 STORC= 2.000000E-02
 JMAX DELTAX
 8 10.00
 NTIME DELT
 10 .10
 BHL BHR HI
 15.00 10.00 10.00

THE RESULTS ARE FOR A RAMP INPUT

FIRST TIME STEP

W2= 0.000000E+00

W3= 1.000000

10.400	10.256	10.164	10.104	10.065	10.039	10.021	10.006
10.839	10.578	10.390	10.257	10.165	10.101	10.054	10.017
11.294	10.954	10.689	10.485	10.329	10.209	10.116	10.037
11.761	11.343	11.007	10.739	10.522	10.345	10.196	10.063
12.221	11.744	11.343	11.008	10.727	10.490	10.282	10.092
12.699	12.145	11.679	11.283	10.941	10.642	10.373	10.122
13.151	12.552	12.023	11.561	11.156	10.795	10.465	10.153
13.643	12.954	12.363	11.842	11.374	10.950	10.558	10.184
14.076	13.366	12.710	12.121	11.591	11.106	10.651	10.215
14.598	13.762	13.048	12.404	11.811	11.262	10.744	10.246

RISE IN PIEZOMETRIC SURFACE COMPUTED NUMERICALLY

.3999	.2562	.1637	.1039	.0649	.0388	.0206	.0064
.8391	.5781	.3897	.2574	.1655	.1012	.0543	.0171
1.2937	.9541	.6891	.4846	.3286	.2094	.1157	.0369
1.7614	1.3434	1.0074	.7385	.5221	.3451	.1960	.0635
2.2207	1.7438	1.3429	1.0076	.7273	.4897	.2820	.0921
2.6989	2.1452	1.6791	1.2828	.9411	.6416	.3726	.1221
3.1511	2.5519	2.0232	1.5609	1.1559	.7950	.4649	.1529
3.6434	2.9541	2.3626	1.8415	1.3745	.9503	.5575	.1837
4.0764	3.3655	2.7096	2.1209	1.5913	1.1060	.6514	.2151
4.5984	3.7624	3.0485	2.4039	1.8112	1.2618	.7443	.2460
.3858	.8337	1.2937	1.7599	2.2302	2.7033	3.1785	3.6555
4.1339	4.6134						

RISE AT SECOND NODE

.2200	.5673	.9488	1.3485	1.7599	2.1797	2.6058	3.0370	3.4724	3.9112
-------	-------	-------	--------	--------	--------	--------	--------	--------	--------

OUTPUT DATA OF PROGRAMME-2B

100.00	50.00	50.00	50.00	50.00	50.00		
50.00	100.00						
.02	.01	.01	.01	.01	.01		
.01	.02						
10.00	20.00	20.00	20.00	20.00	20.00		
20.00	10.00						
NTIME	DELT						
10	.01						
BOUNHL	BOUNHR	HEADI					
15.00	10.00	10.00					
TIME STEP=	1						
11.805	10.185	10.010	10.001	10.000	10.000	10.000	10.000
TIME STEP=	2						
14.161	10.531	10.050	10.004	10.000	10.000	10.000	10.000
TIME STEP=	3						
13.942	10.969	10.129	10.013	10.001	10.000	10.000	10.000
TIME STEP=	4						
14.229	11.273	10.239	10.032	10.004	10.000	10.000	10.000
TIME STEP=	5						
14.254	11.546	10.359	10.061	10.008	10.001	10.000	10.000
TIME STEP=	6						
14.328	11.767	10.484	10.099	10.016	10.002	10.000	10.000
TIME STEP=	7						
14.369	11.956	10.609	10.145	10.027	10.004	10.000	10.000
TIME STEP=	8						
14.408	12.118	10.730	10.195	10.042	10.008	10.001	10.000
TIME STEP=	9						
14.440	12.258	10.847	10.250	10.060	10.012	10.002	10.000
TIME STEP=	10						
14.468	12.380	10.958	10.308	10.081	10.018	10.003	10.000
RISE IN PIEZOMETRIC SURFACE							
1.8053	.1854	.0103	.0006	.0000	.0000	.0000	.0000
4.1610	.5305	.0495	.0037	.0003	.0000	.0000	.0000
3.9422	.9688	.1287	.0132	.0011	.0001	.0000	.0000
4.2287	1.2731	.2389	.0323	.0035	.0003	.0000	.0000
4.2543	1.5458	.3589	.0615	.0083	.0009	.0000	.0000
4.3283	1.7670	.4843	.0994	.0162	.0022	.0001	.0000
4.3685	1.9563	.6089	.1446	.0274	.0043	.0004	.0000
4.4084	2.1177	.7304	.1954	.0422	.0075	.0008	.0001
4.4402	2.2576	.8470	.2504	.0602	.0120	.0016	.0002
4.4682	2.3799	.9580	.3083	.0815	.0180	.0028	.0003

OUTPUT DATA OF PROGRAMME-2C (CASE1)

TRANSMISSIVITY	STORATIVITY	HYDRAULIC DIFFUSIVITY	
□ 300.00	.0200	15000.0	
□ INITIAL HEAD	SIGMA0		
10.00	5.00		
TIME	DISTI	DELX	
1	.00	10.00	
HEAD AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
14.884850	14.654940	14.426170	14.199300
RISE AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
4.884851	4.654937	4.426169	4.199300
A	B	C	D
14.65494	-.2295E-01	.5732E-05	.1254E-06
DISTANCE FROM STREAM		ANALYTICAL HEAD	COMPUTED HEAD
10.00		14.7698	14.7698
20.00		14.5404	14.5404
COMPUTED DIFFERENTIAL	ANALYTICAL DIFFERENTIAL	CENTRAL DIFFERENTIAL	
-.2299E-01	-.2299E-01	-.2299E-01	
COMPUTED DIFFERENTIAL	ANALYTICAL DIFFERENTIAL	CENTRAL DIFFERENTIAL	
-.2288E-01	-.2288E-01	-.2288E-01	
CHECKING THE END DERIVATION			
HEAD AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
14.884850	14.654940	14.426170	
RISE AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
4.884851	4.654937	4.426169	
A	B	C	D
14.88485	-.2302E-01	.1936E-05	.1265E-06
DISTANCE FROM STREAM		ANALYTICAL HEAD	COMPUTED HEAD
10.00		14.7698	14.7698
20.00		14.5404	14.5404

OUTPUT DATA OF PROGRAMME-2C (CASE-2)

TRANSMISSIVITY	STORATIVITY	HYDRAULIC DIFFUSIVITY	
10.00	.0010	10000.0	
INITIAL HEAD	SIGMA0		
50.00	5.00		
TIME	DISTI	DELX	
1	.00	50.00	
HEAD AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
54.298420	52.979420	51.883800	51.079620
RISE AT 4 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
4.298419	2.979415	1.883795	1.079625
A	B	C	D
52.97942	-.2437E-01	.4468E-04	.9075E-07
DISTANCE FROM STREAM		ANALYTICAL HEAD	COMPUTED HEAD
50.00		53.6184	53.6152
DISTANCE FROM STREAM		ANALYTICAL HEAD	COMPUTED HEAD
100.00		52.3975	52.3994
COMPUTED DIFFERENTIAL	ANALYTICAL DIFFERENTIAL	CENTRAL DIFFERENTIAL	
-.2644E-01	-.2650E-01	-.2638E-01	
COMPUTED DIFFERENTIAL	ANALYTICAL DIFFERENTIAL	CENTRAL DIFFERENTIAL	
-.2197E-01	-.2197E-01	-.2191E-01	
CHECKING THE END DERIVATION			
HEAD AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
54.298420	52.979420	51.883800	
RISE AT 3 CONSECUTIVE NODES COMPUTED ANALYTICALLY:			
4.298419	2.979415	1.883795	
A	B	C	D
54.29842	-.2772E-01	.1799E-04	.1779E-06
50.00		53.6184	53.6193

DISTANCE FROM STREAM
100.00

ANALYTICAL HEAD
52.3975

COMPUTED HEAD
52.3953

OUTPUT DATA OF PROGRAMME-2D

THE RESULTS ARE FOR A STEP INPUT

THE INFLOW AT X=0 IS OBTAINED NUMERICALLY

DELT

.050

TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR
100.0	.020	10.0	10.0	15.00	10.00

BOUNDARY CONDITION AT X=0; SRIVL(K)

15.00	15.00	15.00	15.00	15.00	
15.00	15.00	15.00	15.00	15.00	

W2= 0.000000E+00

W3= 1.000000

W1= 0.000000E+00

W2= 0.000000E+00

W3= 1.000000

HEAD (metre) AT DIFFERENT TIMES AND NODES

13.49	11.87	11.00	10.54	10.29	10.15	10.07	10.02
14.18	12.80	11.80	11.12	10.68	10.39	10.20	10.06
14.39	13.27	12.33	11.59	11.05	10.65	10.35	10.11
14.50	13.53	12.66	11.93	11.34	10.87	10.48	10.16
14.56	13.69	12.89	12.18	11.57	11.05	10.60	10.19
14.59	13.80	13.05	12.36	11.74	11.18	10.69	10.22
14.62	13.87	13.16	12.48	11.86	11.29	10.75	10.25
14.64	13.93	13.23	12.57	11.95	11.36	10.80	10.27
14.65	13.96	13.29	12.64	12.02	11.42	10.84	10.28
14.66	13.99	13.33	12.69	12.06	11.46	10.87	10.29

OUTPUT DATA OF PROGRAMME-2E

DELT

.050							
TRANSMISSIVITY	STORATIVITY	DELXJ	INITIALHEAD	HEADL	HEADR		
100.0	.020	10.0	10.0	15.00	10.00		
SRIVL(K)							
15.00	15.00	15.00	15.00	15.00			
15.00	15.00	15.00	15.00	15.00			
W3=	1.000000						
W2=	0.000000E+00						
W1=	0.000000E+00						
W2=	0.000000E+00						
W3=	1.000000						

HEAD (metre) AT DIFFERENT TIMES AND NODES

14.13	12.22	11.19	10.64	10.34	10.18	10.08	10.02
14.30	12.98	11.95	11.23	10.75	10.44	10.22	10.07
14.43	13.35	12.42	11.68	11.11	10.69	10.38	10.12
14.51	13.58	12.73	12.00	11.40	10.91	10.51	10.16
14.57	13.72	12.93	12.23	11.61	11.08	10.62	10.20
14.60	13.82	13.07	12.39	11.77	11.21	10.70	10.23
14.63	13.89	13.18	12.51	11.88	11.31	10.77	10.25
14.64	13.94	13.25	12.59	11.97	11.38	10.81	10.27
14.66	13.97	13.30	12.65	12.03	11.43	10.85	10.28
14.66	14.00	13.34	12.70	12.07	11.46	10.87	10.29